

From Foundation Models to Multi-Modal Models in Medical Imaging (FMLLM)



Ismail Ben Ayed



Tanveer Syeda-Mahmood



Yunsoo Kim



Julio Silva-Rodríguez

Outline (Morning session)

- **M1. Introduction to Foundation Models -- 8 to 9:30 AM (Tanveer)**

- Evolution of Machine learning models
- Definition of Foundation models
- What makes a model foundational?
- Foundational models in medical imaging
- Self-supervised learning, contrastive learning, masked auto-encoders
- LLMs- transformers

- **M2. Vision-Language Models (VLMs) – 9:30 to 10:00 AM (Ismail)**

- Contrastive Language-Image Pre-training (CLIP)
- Zero-shot and few-shot inference
- Vision-language models for medical imaging (e.g., embedding domain knowledge)

- **Coffee break: 10 to 10:30 AM**

Outline (Morning session)

- **M3. Fine-tuning large Vision-Language Models - 10:30 to 11:10 AM (Ismail)**
 - Prompt learning
 - Adapters
 - Linear-probing baselines
 - Parameter-efficient fine-tuning (e.g., low-rank approximation)
 - Transduction helps VLMs.
- **M4. Foundational models for segmentation -- 11:10 to 11:50 AM (Julio)**
 - Types of foundation models: a data perspective.
 - Learning/usages-based classification.
 - Zero-shot/adaptation-oriented volumetric foundation models.
- **M5. Techniques for Improving LLM performance --11:50-12:10 PM (Tanveer)**
 - Instruction tuning
 - Retrieval-augmented generation
 - Fact-checking
- **M6. Deployment considerations of generative AI -- 12:-10 PM -12:30 PM (Tanveer)**
 - Datasets for training foundational models
 - Evaluation of foundational models

Part 4

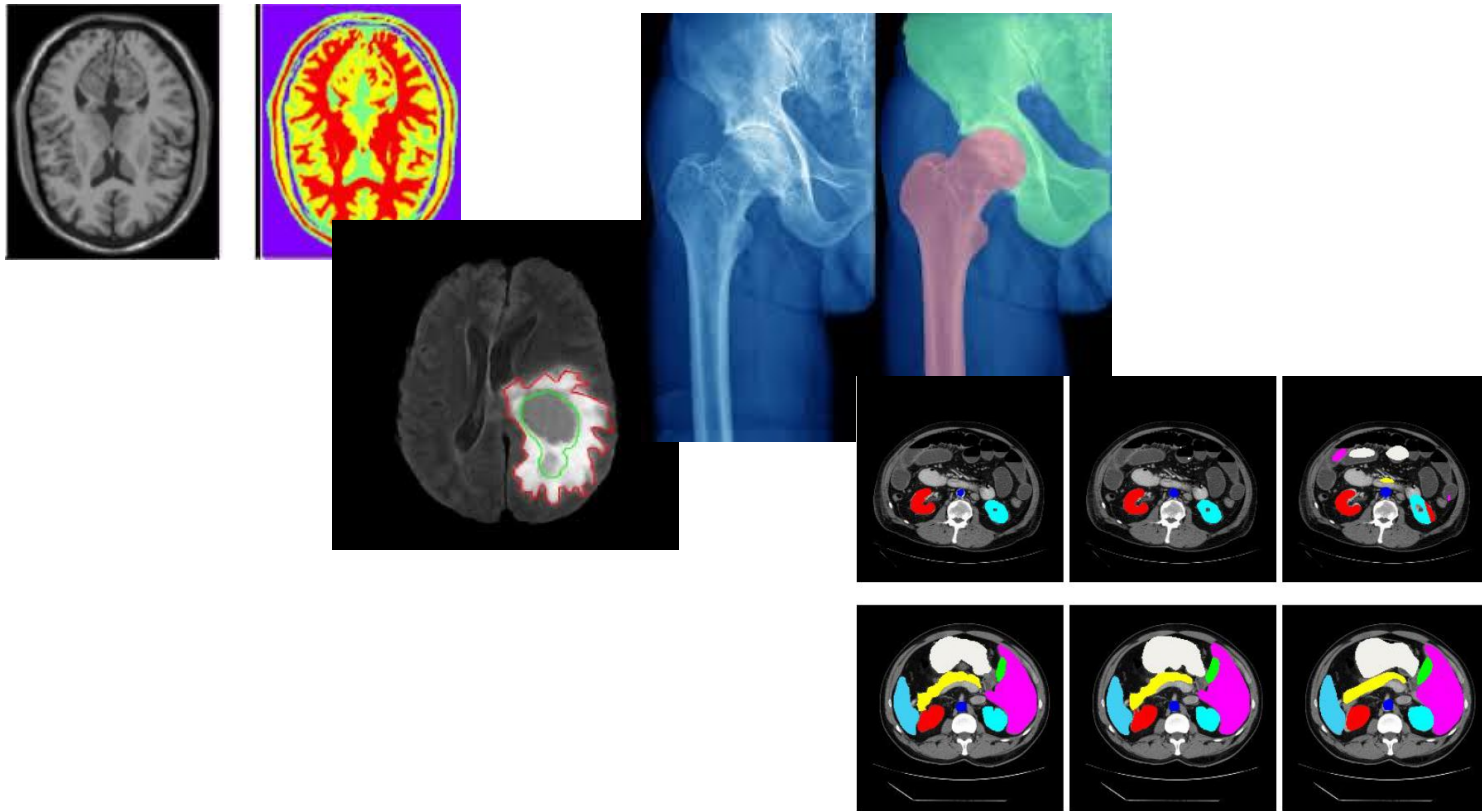
Foundational models for segmentation

Outline

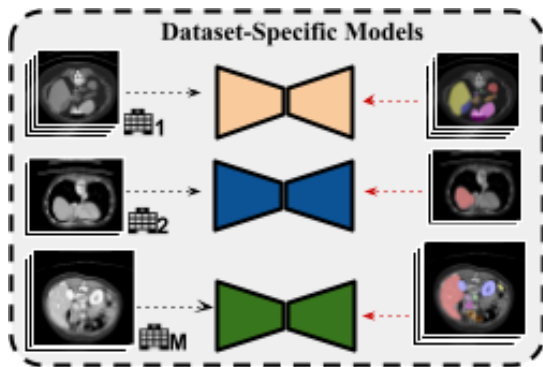
M4. Foundational models for segmentation

- Types of foundation models: a data perspective.
- Learning/usages-based classification.
- Zero-shot/adaptation-oriented volumetric foundation models.

Foundation models for medical image segmentation

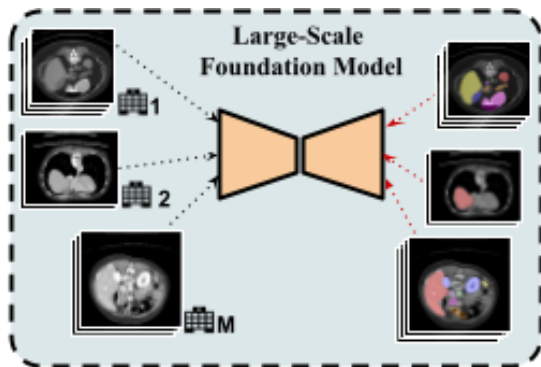


Foundation models for medical image segmentation



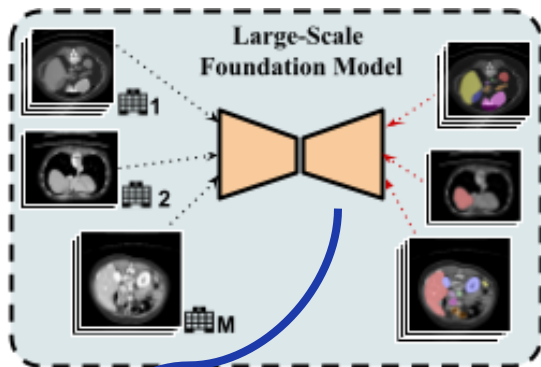
Foundation models for medical image segmentation

Trained with many
data / tasks / domains

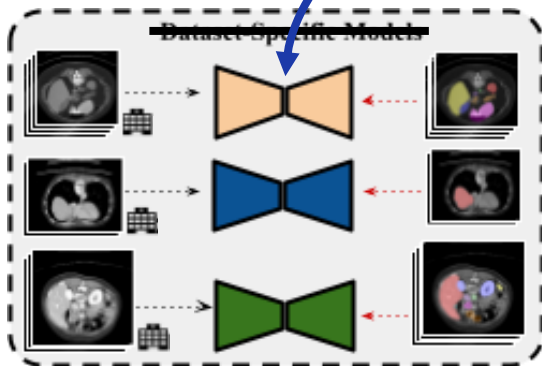


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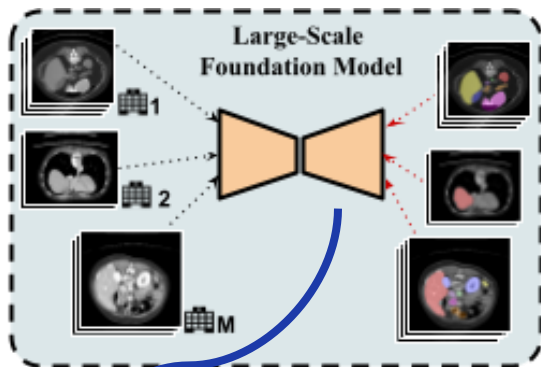
Transfer to new
domains/tasks



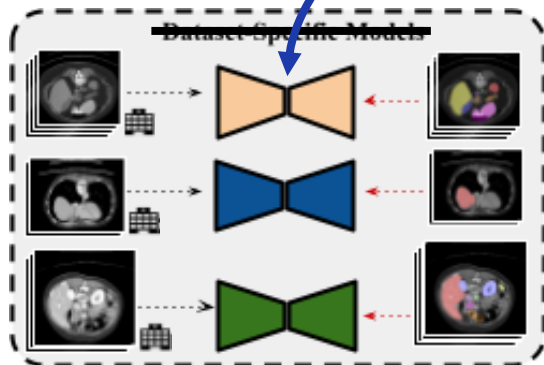
+ Some target
domain feedback
(ideally small)

Foundation models for medical image segmentation

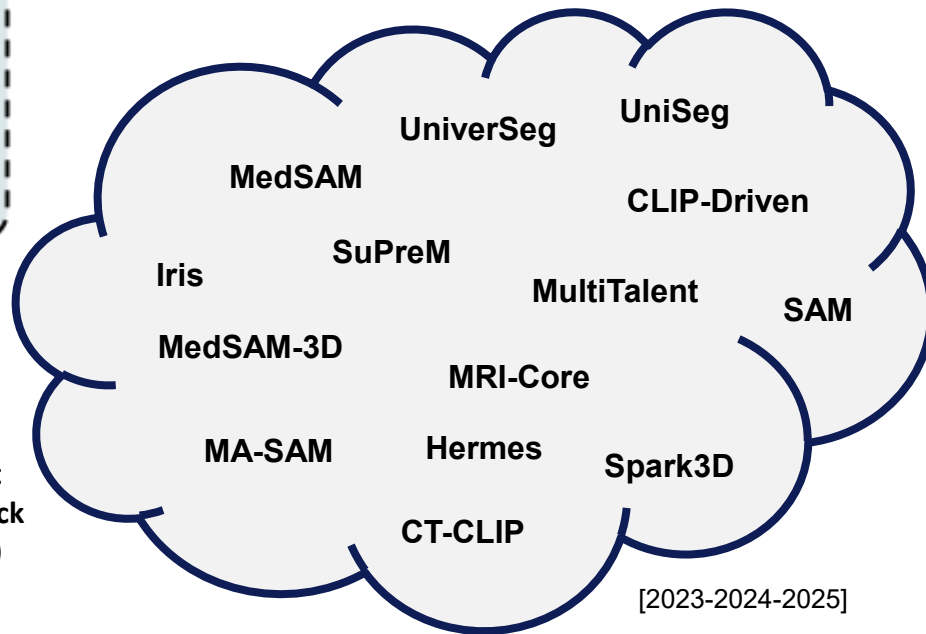
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Transfer to new
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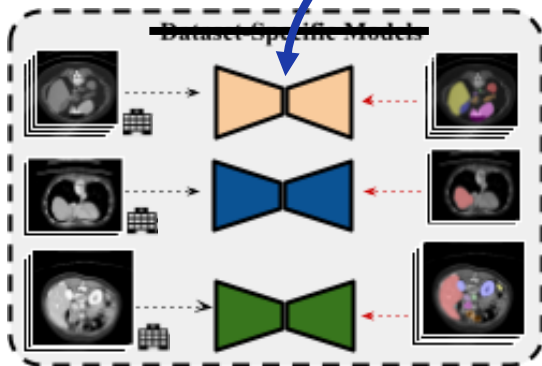
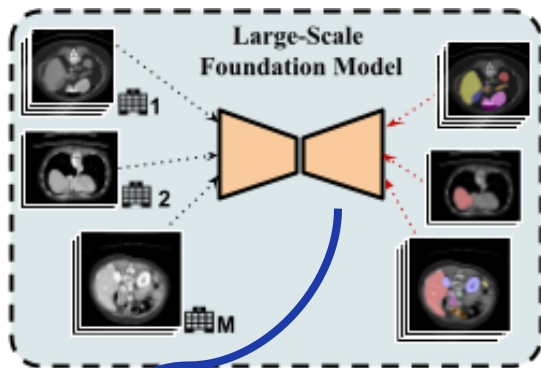
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[2023-2024-2025]

Foundation models for medical image segmentation

Trained with many
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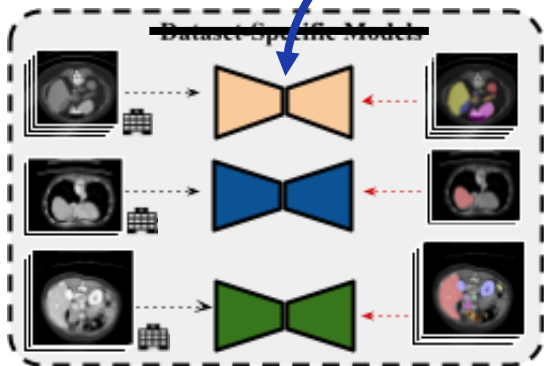
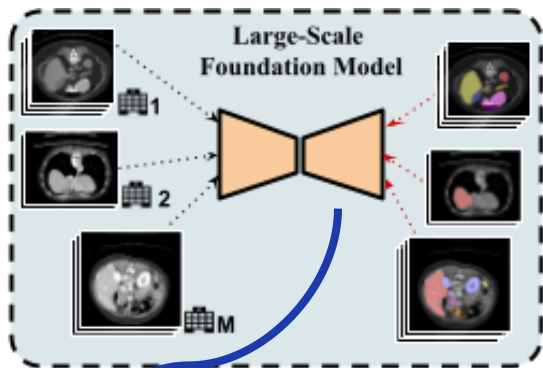
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Organizing the mess!

1. Types of foundation models: a data perspective.
 - A. Generalist vs. Specialized
 - B. 2D vs. 3D
 - C. Multimodal vs. Unimodal
2. Learning/Usage Objectives
 - A. Zero-shot / Transfer Learning
 - B. In-Context Learning
 - C. Interactive Models ("SAM")
3. Zero-shot / Adaptation-oriented (3D data)
 - A. How to pre-train?
 - B. How useful are foundation models? Limitations on the adaptation stage
 - C. Few-shot Parameter-Efficient Fine-tuning

Foundation models for medical image segmentation

Trained with many
data / tasks / domains



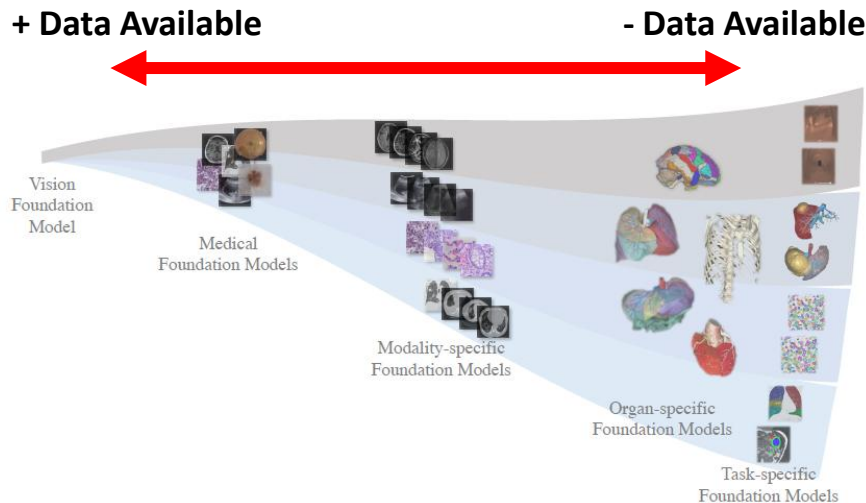
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Types of foundation models: a data perspective.

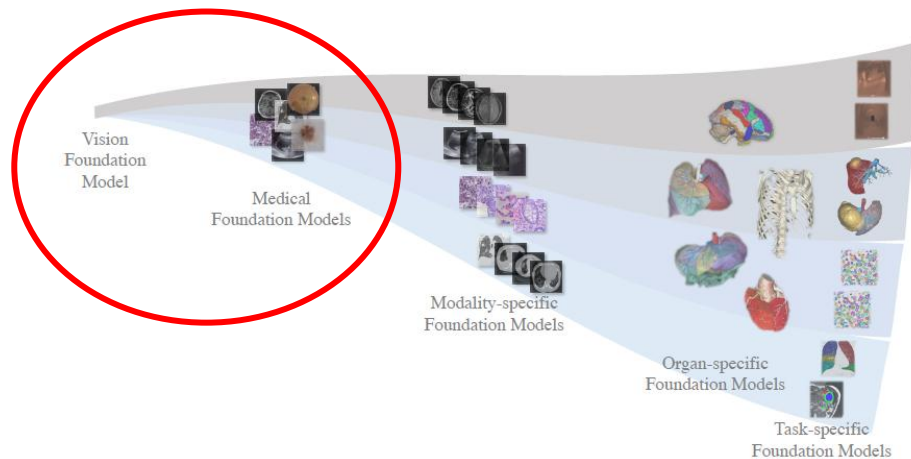
Generalist vs. Specialized (pre-training)



Huang et al. On The Challenges And Perspectives of Foundation Models For Medical Image Analysis. Media'24.

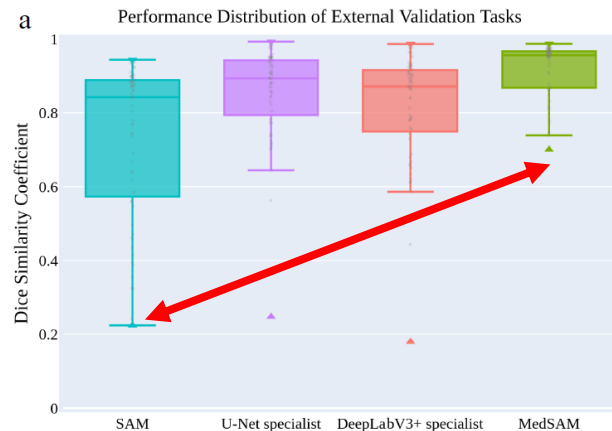
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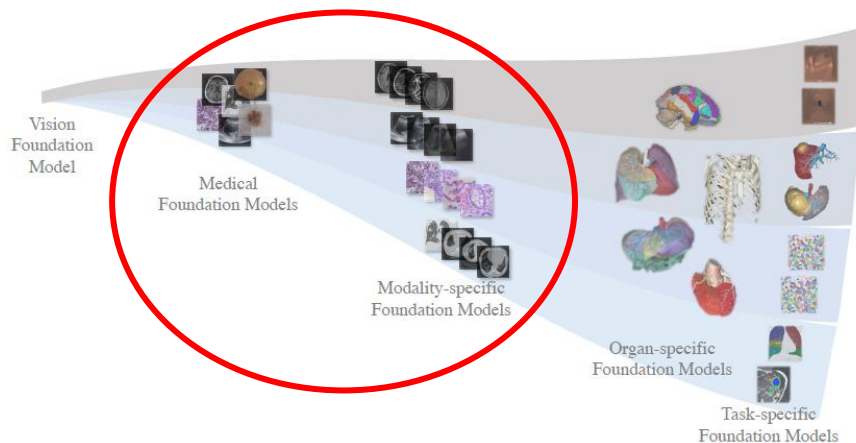
→ Medical better than General (natural image)



Ma et al. Segment Anything in Medical Images. Nat.Com.'24

Types of foundation models: a data perspective.

Generalist vs. Specialized (pre-training)

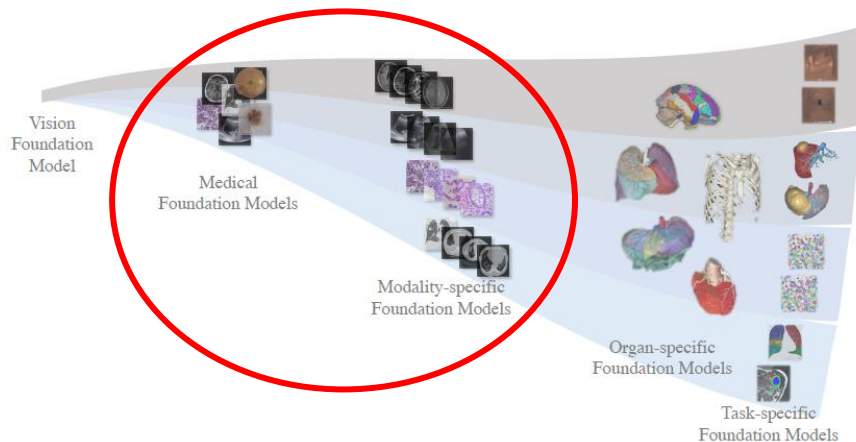


→ Modality better than Medical ?
(scarce empirical studies for segmentation)

Huang et al. On The Challenges And Perspectives of Foundation Models For Medical Image Analysis. MedIA'24.

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Generalist vs. Specialized (pre-training)



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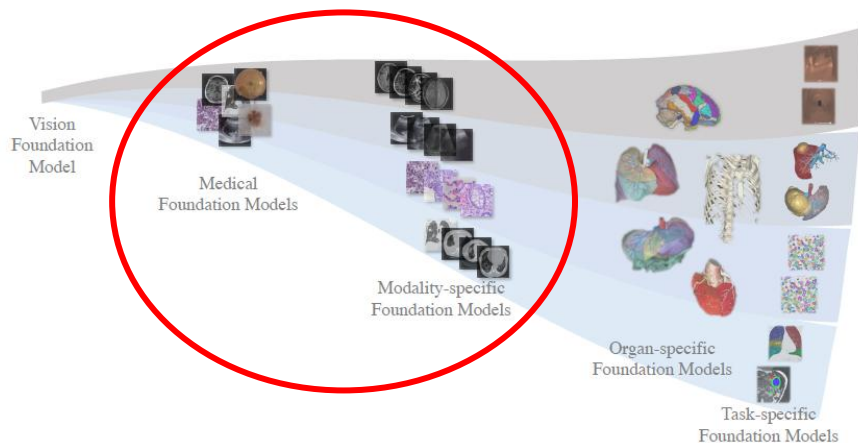
→ Modality better than Medical ?
(scarce empirical studies for segmentation)
BUT... On VLMs for classification it is the case.

(a) <i>Zero-shot</i>		MESSIDOR	FIVES	REFUGE	20x3	ODIR _{200x3}	MMAC	Avg.
CLIP	ViT-B/32	0.200	0.256	0.433	0.333	0.480	0.183	0.314
BiomedCLIP	ViT-B/16	0.207	0.415	0.624	0.617	0.583	0.274	0.453
FLAIR	RN50	0.604	0.735	0.883	0.983	0.667	0.400	0.712
(b) <i>Linear Probing</i>								
ImageNet	RN50	0.424	0.741	0.733	0.983	0.887	0.631	0.733
CLIP	ViT-B/32	0.491	0.800	0.720	0.950	0.917	0.642	0.753
BiomedCLIP	ViT-B/16	0.433	0.654	0.776	0.866	0.883	0.678	0.715
RETFound	ViT-B/16	0.457	0.765	0.747	0.950	0.887	0.547	0.725
FLAIR	RN50	0.719	0.879	0.843	1.000	0.935	0.740	0.852

Silva-Rodríguez et al. A Foundation Language-Image Model of the Retina: Encoding Expert Knowledge in Text Supervision. MedIA'25.

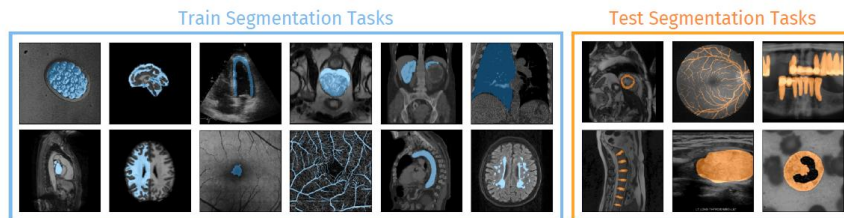
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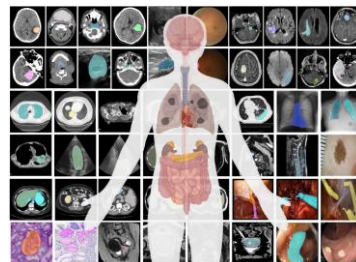


Huang et al. On The Challenges And Perspectives of Foundation Models For Medical Image Analysis. MedIA'24.

→ Modality better than Medical ?
(scarce empirical studies for segmentation)
BUT... Large domain GAP between modalities.



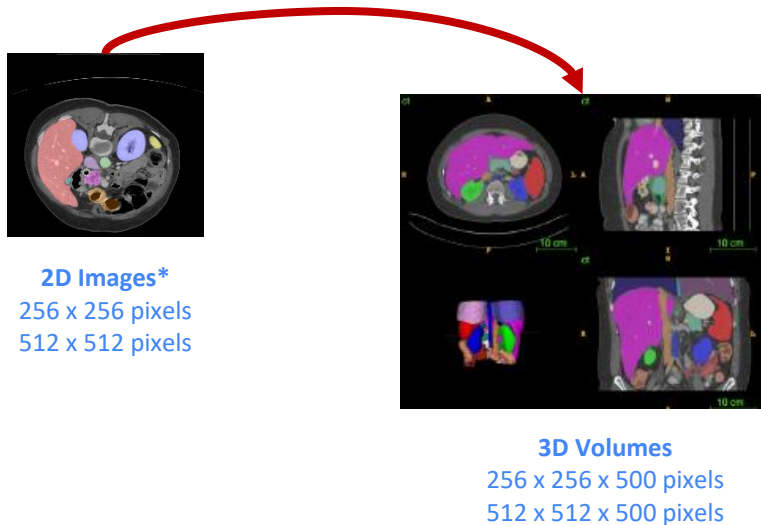
Butoi et al. Universeg: Universal medical image segmentation. ICCV'23.



Ma et al. Segment Anything in Medical Images. Nat.Com.'24

Types of foundation models: a data perspective.

2D vs. 3D (pre-training)

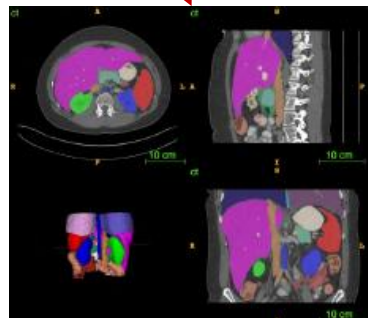


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2D vs. 3D (pre-training)

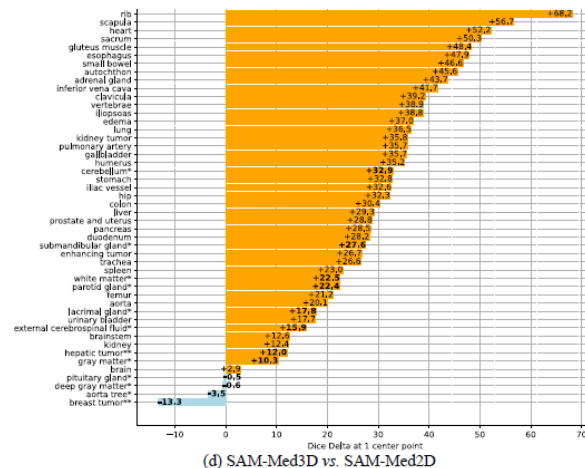


2D Images*
256 x 256 pixels
512 x 512 pixels



3D Volumes
256 x 256 x 500 pixels
512 x 512 x 500 pixels

→ Pre-training on 3D better than on 2D
(also, a limitation of natural image pre-training)

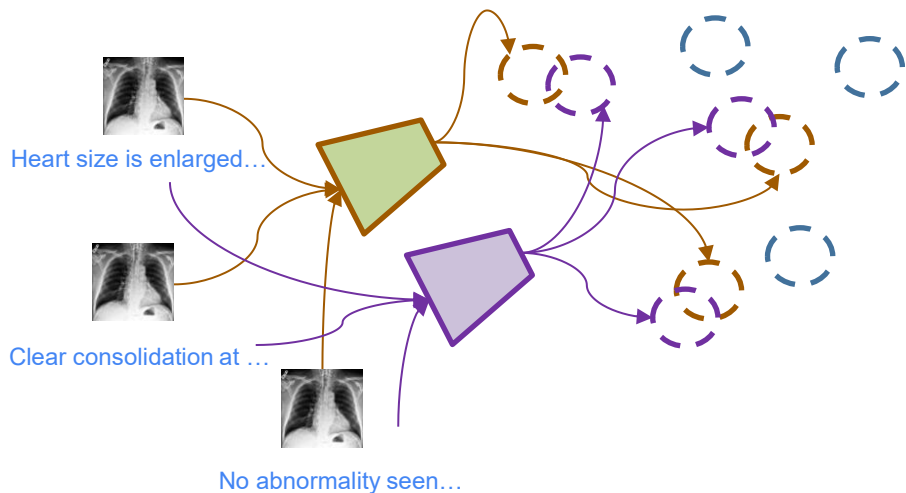


Wang et al. SAM-Med3D: Towards General-Purpose Segmentation Models for Volumetric Medical Images. ECCVw'24.

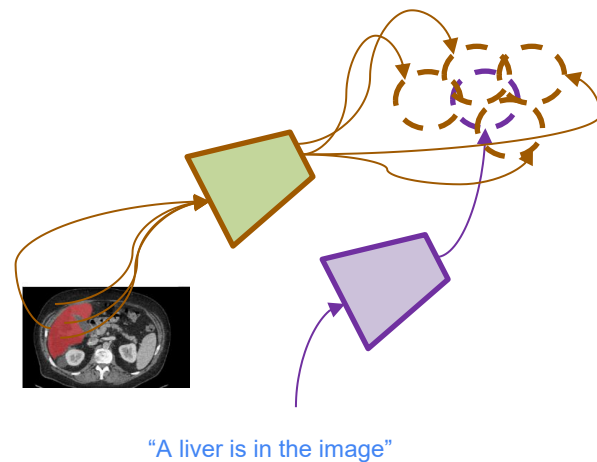
Types of foundation models: a data perspective.

Multimodal vs. Unimodal

Image-Level image-language pre-training



Segmentation image-language pre-training



Types of foundation models: a data perspective.

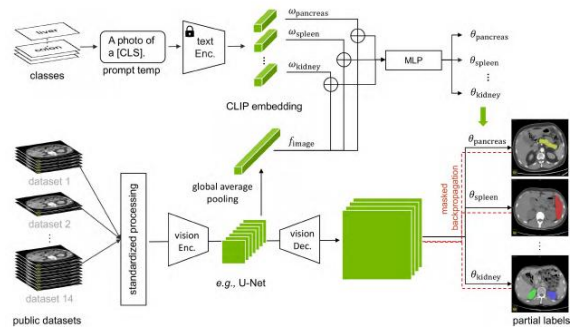
Multimodal vs. Unimodal

→ Why segmentation FMs in medical are mostly Unimodal?

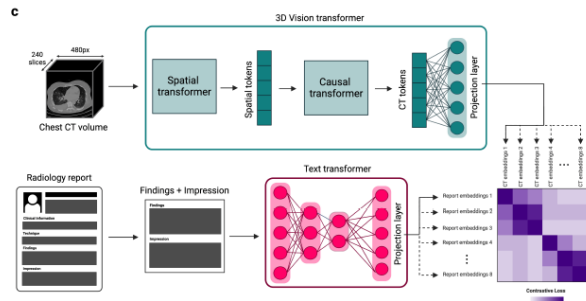
- Scarcity of grounding language annotations with masks.
- Already-existing large datasets with pixel/voxel annotations only.
- Unclear contribution of text modality in absence of open-vocabulary concepts.
- Some works include a CLIP-driven component, but its contribution is doubtful.
- To explore in lesion segmentation?



“A liver is in the image”



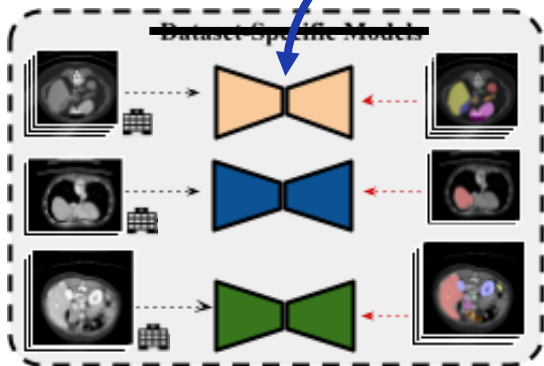
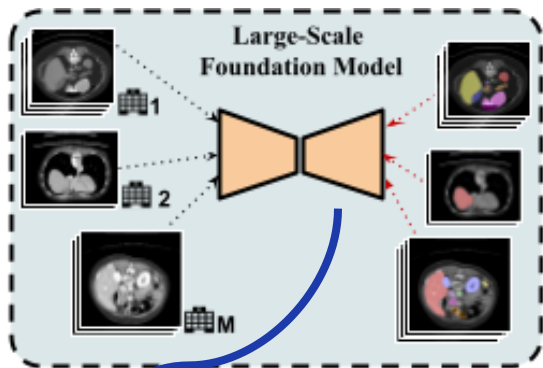
Liu et al. CLIP-Driven Universal Model for Organ Segmentation and Tumor Detection. ICCV'23.



Hamamci et al. Developing Generalist Foundation Models from a Multimodal Dataset for 3D Computed Tomography. ArXiv'24.

Foundation models for medical image segmentation

Trained with many
data / tasks / domains



+ Some target
domain feedback
(ideally small)

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Learning / usage objectives.

Zero-shot / Transfer Learning

ImageNet Philosophy

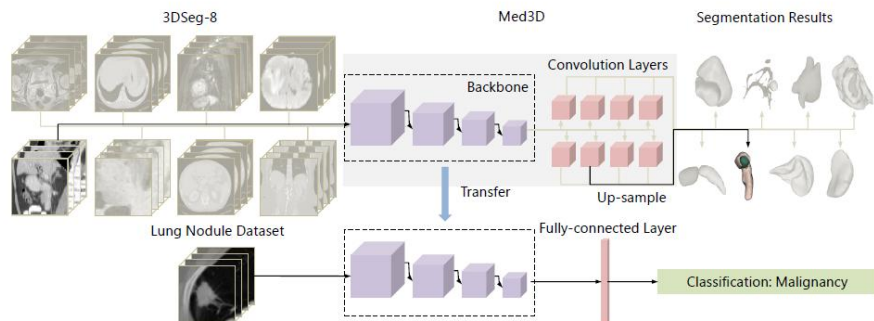
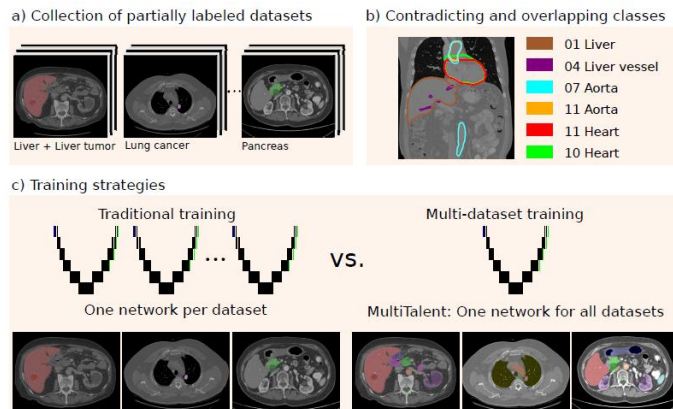


Figure 2: Framework of the proposed method.

Chen et al. Med3D: Transfer Learning for 3D Medical Image Analysis. ArXiv'19.



Ulrich et al. MultiTalent: A Multi-Dataset Approach to Medical Image Segmentation. MICCAI'23.

Med3D('19)

CLIP-Driven

MultiTalent

UniSeg

SuPreM

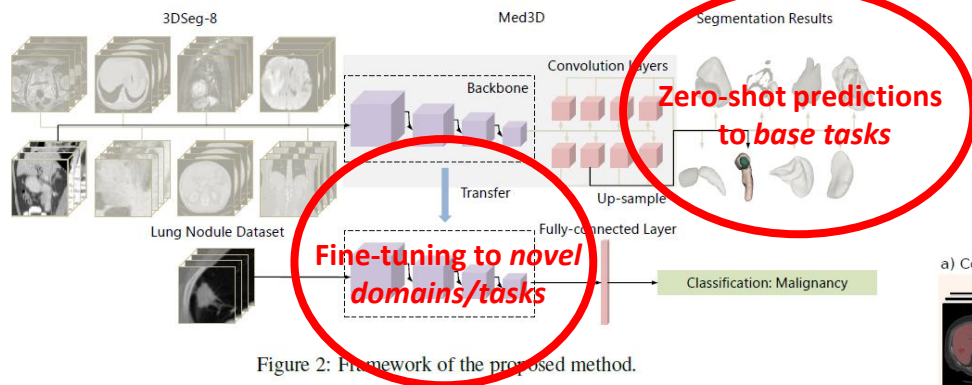
HERMES

FSEFT

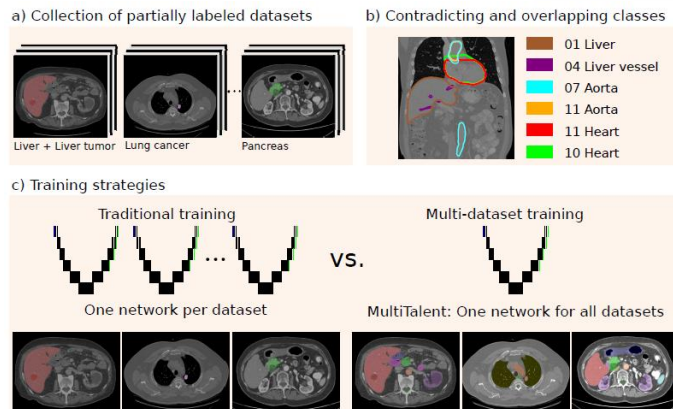
Learning / usage objectives.

Zero-shot / Transfer Learning

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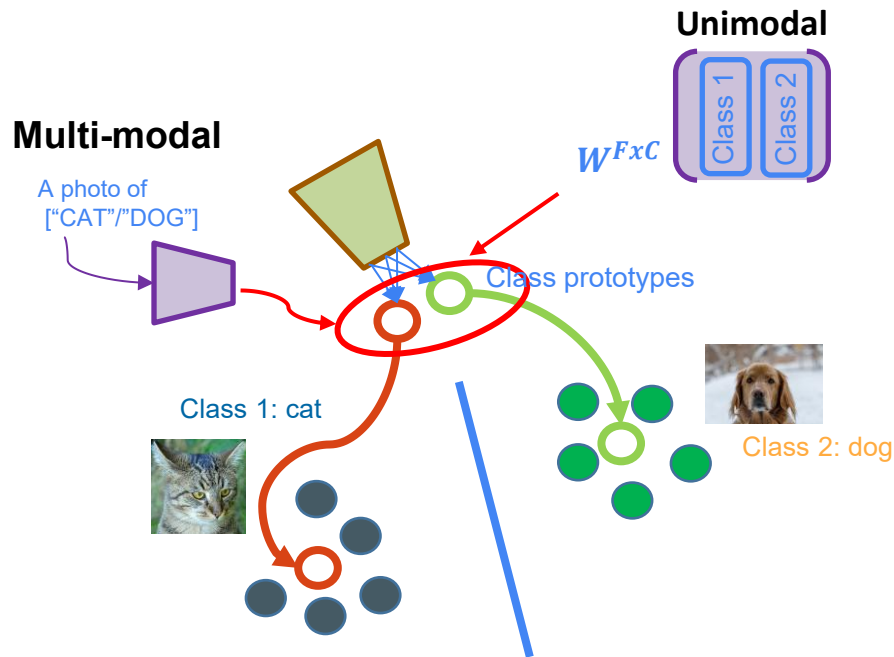
HERMES

FSEFT

Learning / usage objectives.

(Zero-shot: VLMs vs. Unimodal)

Zero-shot: not receiving any supervision from the target domain/task



Is zero-shot predictions to novel categories a realistic objective?

Undandarao et al. No Zero-Shot without Exponential Data: Pretraining Concept frequency Determines Multimodal Model Performance. NeurIPS'24.

Learning / usage objectives.

In Context Learning

“At the end of the day, practitioners won’t fine-tune”

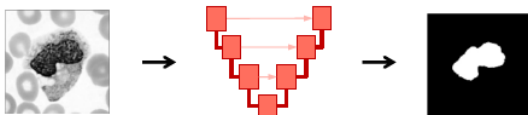
UniverSeg

Tyche

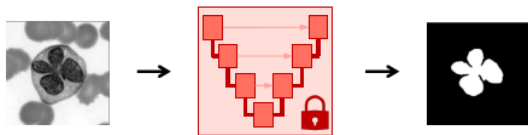
Iris

Traditional Approach

1. Design and train a task-specific model.

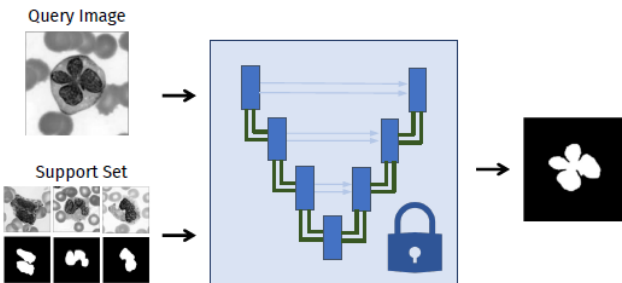


2. Predict new images with the trained model.

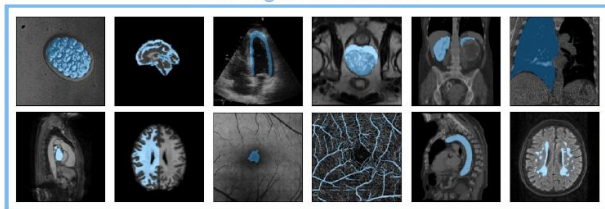


UniverSeg Approach

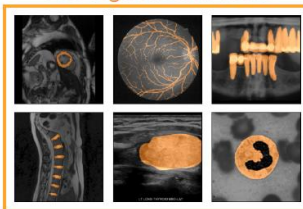
With a trained UniverSeg model, predict new images for the new task from a few labeled pairs without retraining.



Train Segmentation Tasks



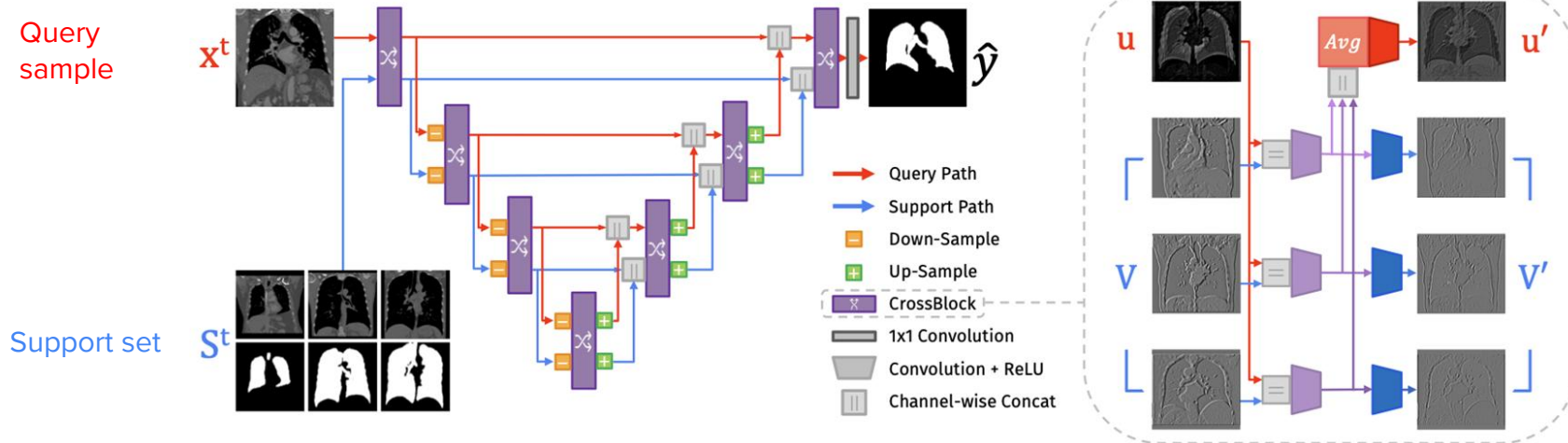
Test Segmentation Tasks



Learning / usage objectives.

In Context Learning

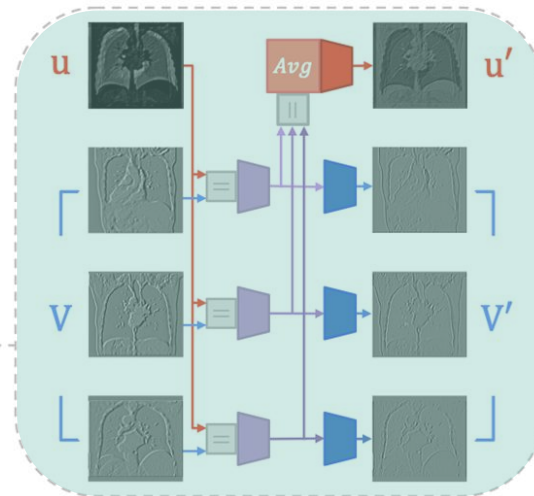
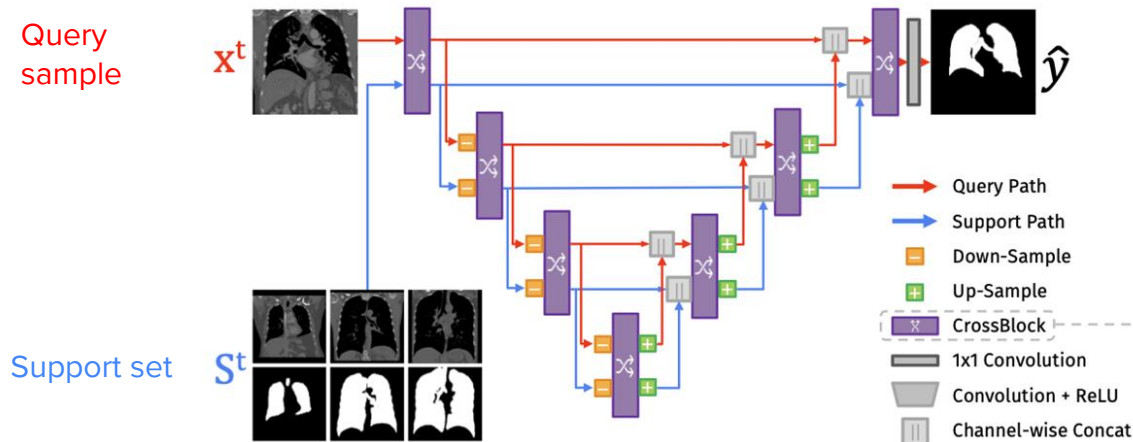
Main Idea



Learning / usage objectives.

In Context Learning

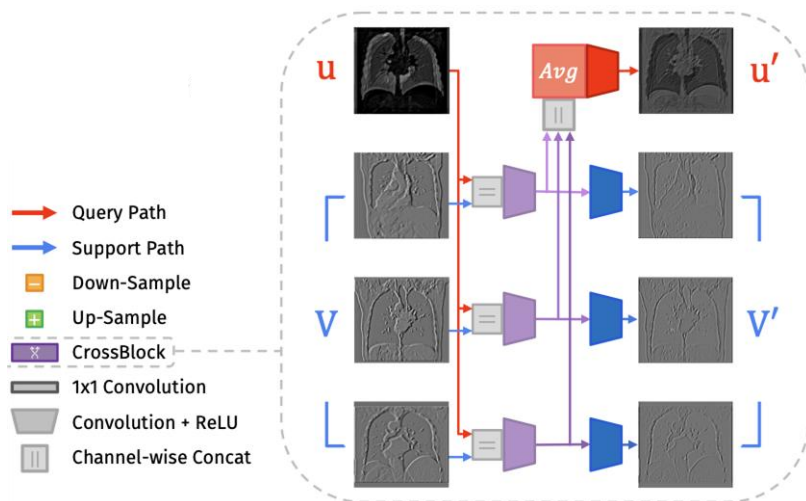
Main Idea



The representations from the query and support samples can interact at multiple scales

Learning / usage objectives.

In Context Learning



$\text{CrossBlock}(u, V; \theta_z, \theta_v) = (u', V')$, where: (2)

$$z_i = A(\text{CrossConv}(u, v_i; \theta_z)) \quad \text{for } i = 1, 2, \dots, n$$

$$u' = 1/n \sum_{i=1}^n z_i \quad \text{Query output: average across support}$$

$$v'_i = A(\text{Conv}(z_i; \theta_v)) \quad \text{for } i = 1, 2, \dots, n,$$

$$\text{CrossConv}(u, V; \theta_z) = \{z_i\}_{i=1}^n,$$

for $z_i = \text{Conv}(u || v_i; \theta_z)$,

Support samples
activation maps

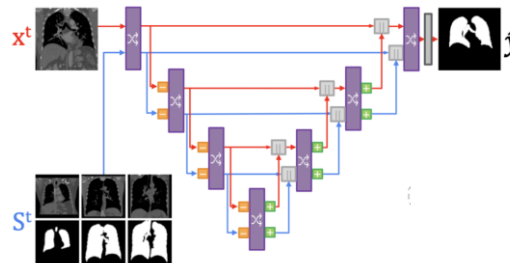
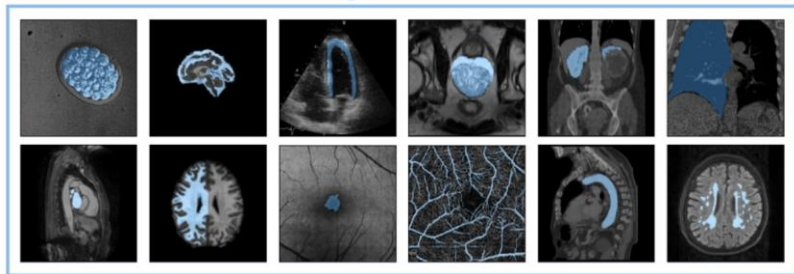
Concatenate query and
support activation maps

Learning / usage objectives.

In Context Learning

How is this trained? (Hint: based on meta-learning or *learning-to-learn*)

Train Segmentation Tasks

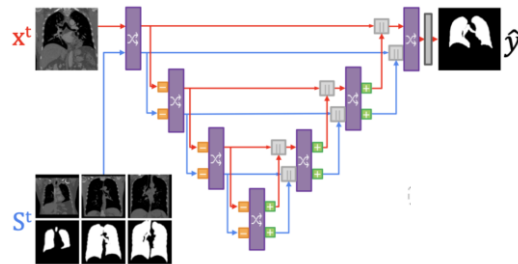
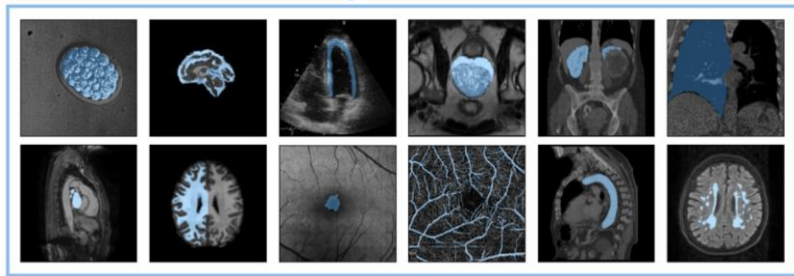


Learning / usage objectives.

In Context Learning

How is this trained? (Hint: based on meta-learning or *learning-to-learn*)

Train Segmentation Tasks



for $k = 1, \dots, \text{NumTrainSteps}$ **do**

$t \sim \mathcal{T}$

$(x_i^t, y_i^t) \sim t$

$S^t \leftarrow \{(x_j^t, y_j^t)\}_{j \neq i}^n$

$x_i^t, y_i^t \leftarrow \text{Aug}_t(x_i^t, y_i^t)$

$S^t \leftarrow \{\text{Aug}_t(x_j^t, y_j^t)\}_{j \neq i}^n$

$x_i^t, y_i^t, S^t \leftarrow \text{Aug}_T(x_i^t, y_i^t, S^t)$

$\hat{y}_i \leftarrow f_\theta(x_i^t, S^t)$

$\ell \leftarrow \mathcal{L}_{\text{seg}}(\hat{y}_i, y_i^t)$

$\theta \leftarrow \theta - \eta \nabla_\theta \ell$

end for

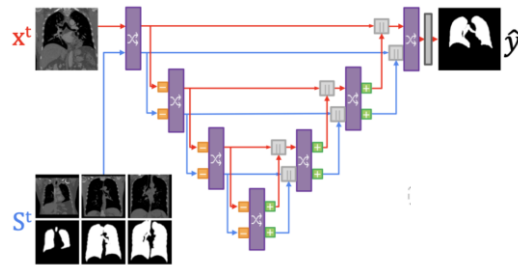
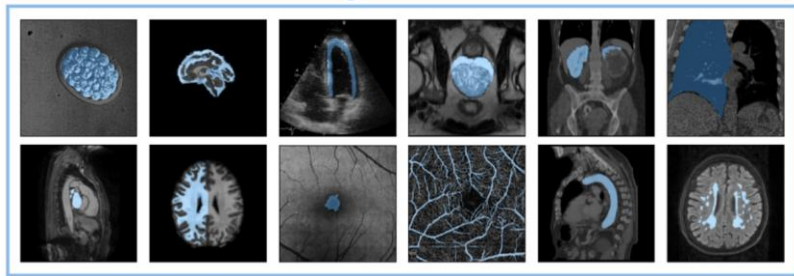
- ▷ Sample Task
- ▷ Sample Query
- ▷ Sample Support
- ▷ Augment Query
- ▷ Augment Support
- ▷ Task Aug
- ▷ Predict label map
- ▷ Compute loss
- ▷ Gradient step

Learning / usage objectives.

In Context Learning

How is this trained? (Hint: based on meta-learning or *learning-to-learn*)

Train Segmentation Tasks



for $k = 1, \dots, \text{NumTrainSteps}$ **do**

$t \sim \mathcal{T}$

▷ Sample Task

$(x_i^t, y_i^t) \sim t$

▷ Sample Query

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▷ Sample Support

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▷ Predict label map

$\ell \leftarrow \mathcal{L}_{\text{seg}}(\hat{y}_i, y_i^t)$

▷ Compute loss

$\theta \leftarrow \theta - \eta \nabla_\theta \ell$

▷ Gradient step

end for

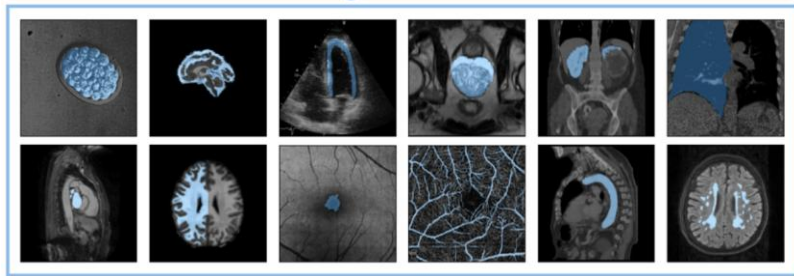
Among all training tasks

Learning / usage objectives.

In Context Learning

How is this trained? (Hint: based on meta-learning or *learning-to-learn*)

Train Segmentation Tasks



for $k = 1, \dots, \text{NumTrainSteps}$ **do**

$t \sim \mathcal{T}$

$(x_i^t, y_i^t) \sim t$

$S^t \leftarrow \{(x_j^t, y_j^t)\}_{j \neq i}^n$

$x_i^t, y_i^t \leftarrow \text{Aug}_t(x_i^t, y_i^t)$

$S^t \leftarrow \{\text{Aug}_t(x_j^t, y_j^t)\}_{j \neq i}^n$

$x_i^t, y_i^t, S^t \leftarrow \text{Aug}_T(x_i^t, y_i^t, S^t)$

$\hat{y}_i \leftarrow f_\theta(x_i^t, S^t)$

$\ell \leftarrow \mathcal{L}_{\text{seg}}(\hat{y}_i, y_i^t)$

$\theta \leftarrow \theta - \eta \nabla_\theta \ell$

end for

▷ Sample Task

▷ Sample Query

▷ Sample Support

▷ Augment Query

▷ Augment Support

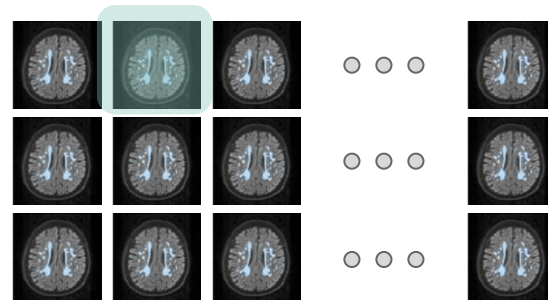
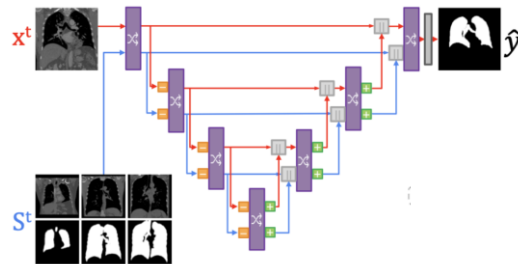
▷ Task Aug

▷ Predict label map

▷ Compute loss

▷ Gradient step

Among all training samples
from that task

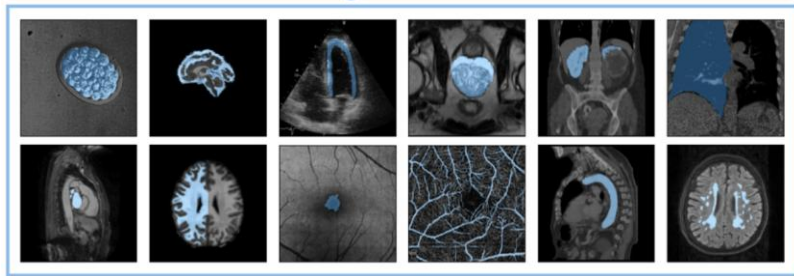


Learning / usage objectives.

In Context Learning

How is this trained? (Hint: based on meta-learning or *learning-to-learn*)

Train Segmentation Tasks



for $k = 1, \dots, \text{NumTrainSteps}$ **do**

$t \sim \mathcal{T}$

$(x_i^t, y_i^t) \sim t$

$S^t \leftarrow \{(x_j^t, y_j^t)\}_{j \neq i}^n$

$x_i^t, y_i^t \leftarrow \text{Aug}_t(x_i^t, y_i^t)$

$S^t \leftarrow \{\text{Aug}_t(x_j^t, y_j^t)\}_{j \neq i}^n$

$x_i^t, y_i^t, S^t \leftarrow \text{Aug}_T(x_i^t, y_i^t, S^t)$

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$\ell \leftarrow \mathcal{L}_{\text{seg}}(\hat{y}_i, y_i^t)$

$\theta \leftarrow \theta - \eta \nabla_\theta \ell$

end for

▷ Sample Task

▷ Sample Query

▷ Sample Support

▷ Augment Query

▷ Augment Support

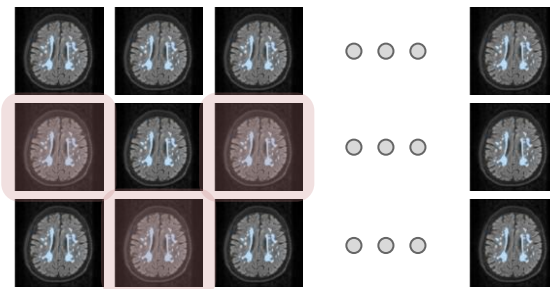
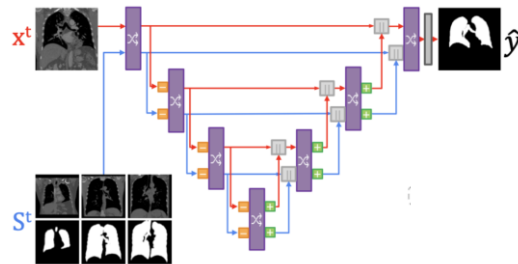
▷ Task Aug

▷ Predict label map

▷ Compute loss

▷ Gradient step

Among all training samples
from that task

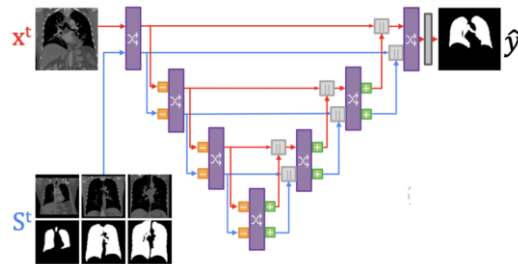
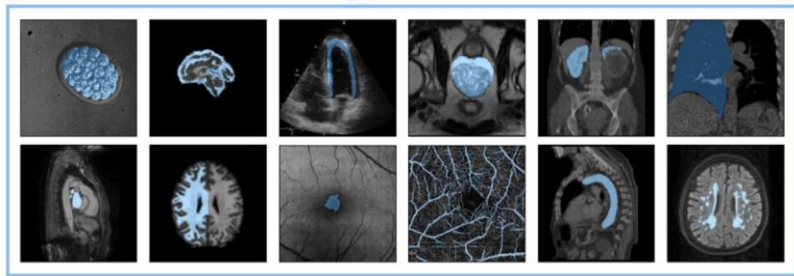


Learning / usage objectives.

In Context Learning

How is this trained? (Hint: based on meta-learning or *learning-to-learn*)

Train Segmentation Tasks



for $k = 1, \dots, \text{NumTrainSteps}$ **do**

$t \sim \mathcal{T}$

▷ Sample Task

$(x_i^t, y_i^t) \sim t$

▷ Sample Query

$S^t \leftarrow \{(x_j^t, y_j^t)\}_{j \neq i}^n$

▷ Sample Support

$x_i^t, y_i^t \leftarrow \text{Aug}_t(x_i^t, y_i^t)$

▷ Augment Query

$S^t \leftarrow \{\text{Aug}_t(x_j^t, y_j^t)\}_{j \neq i}^n$

▷ Augment Support

$x_i^t, y_i^t, S^t \leftarrow \text{Aug}_T(x_i^t, y_i^t, S^t)$

▷ Task Aug

$\hat{y}_i \leftarrow f_\theta(x_i^t, S^t)$

▷ Predict label map

$\ell \leftarrow \mathcal{L}_{\text{seg}}(\hat{y}_i, y_i^t)$

▷ Compute loss

$\theta \leftarrow \theta - \eta \nabla_\theta \ell$

▷ Gradient step

end for

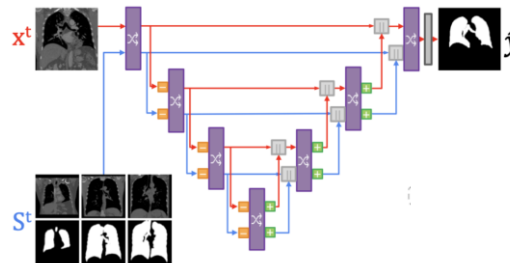
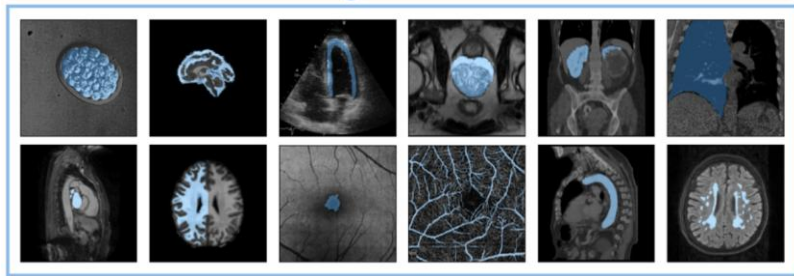
→ Images Augmentations

Learning / usage objectives.

In Context Learning

How is this trained? (Hint: based on meta-learning or *learning-to-learn*)

Train Segmentation Tasks



for $k = 1, \dots, \text{NumTrainSteps}$ **do**

$t \sim \mathcal{T}$

▷ Sample Task

$(x_i^t, y_i^t) \sim t$

▷ Sample Query

$S^t \leftarrow \{(x_j^t, y_j^t)\}_{j \neq i}^n$

▷ Sample Support

$x_i^t, y_i^t \leftarrow \text{Aug}_t(x_i^t, y_i^t)$

▷ Augment Query

$S^t \leftarrow \{\text{Aug}_t(x_j^t, y_j^t)\}_{j \neq i}^n$

▷ Augment Support

$x_i^t, y_i^t, S^t \leftarrow \text{Aug}_T(x_i^t, y_i^t, S^t)$

▷ Task Aug

$\hat{y}_i \leftarrow f_\theta(x_i^t, S^t)$

▷ Predict label map

$\ell \leftarrow \mathcal{L}_{\text{seg}}(\hat{y}_i, y_i^t)$

▷ Compute loss

$\theta \leftarrow \theta - \eta \nabla_\theta \ell$

▷ Gradient step

end for

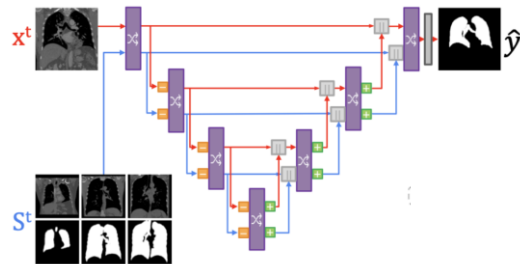
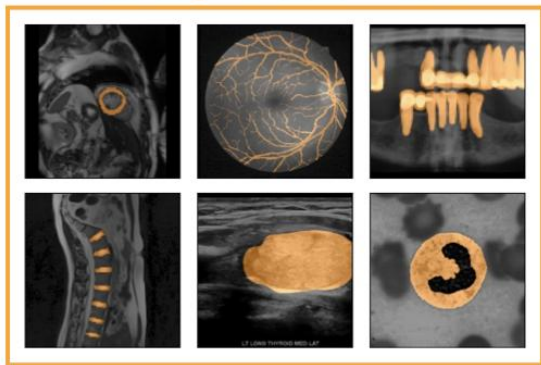
→ Standard (training) forward-backward steps

Learning / usage objectives.

In Context Learning

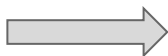
And what about inference?

Test Segmentation Tasks



For a given image x^t $\hat{y} = f_{\theta}(x^t, S^t)$

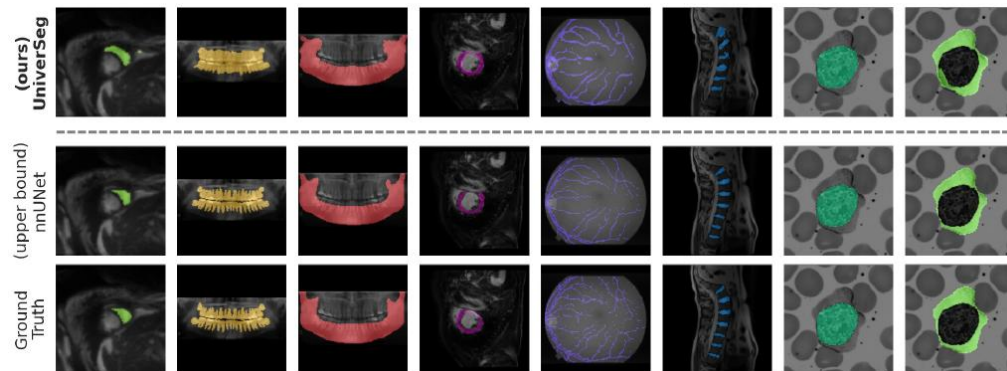
To make it more robust, multiple support sets are employed



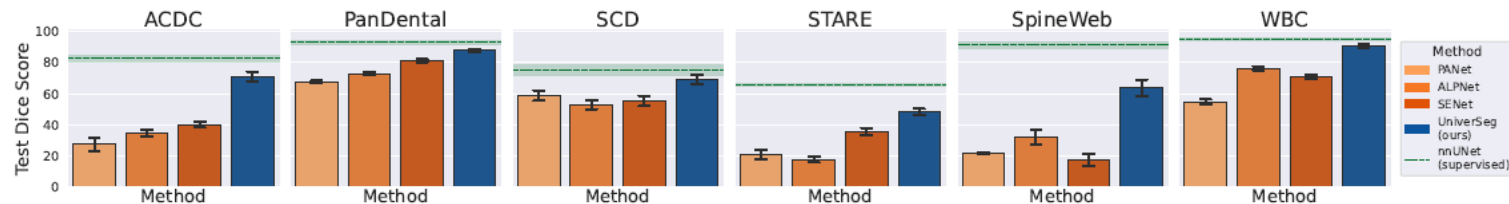
$$\hat{y} = \frac{1}{M} \sum_{m=1}^M f_{\theta}(x^t, S_m^t)$$

Learning / usage objectives.

In Context Learning

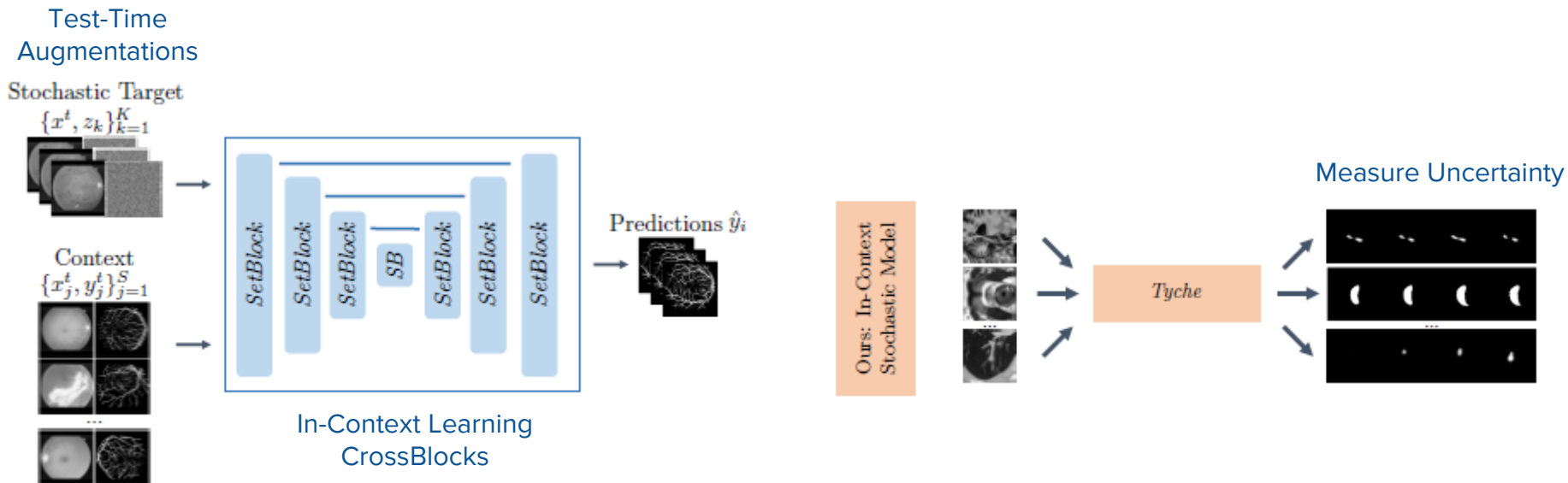


- ✓ Can tackle new tasks.
- ✓ Does not require fine-tuning.
- ✓ Promising performance.
- × Limited to the binary scenario.
- × Performance below dataset-specific models.
- × Unclear implementation on large 3D data.
- × Requires continuously employing the support set.



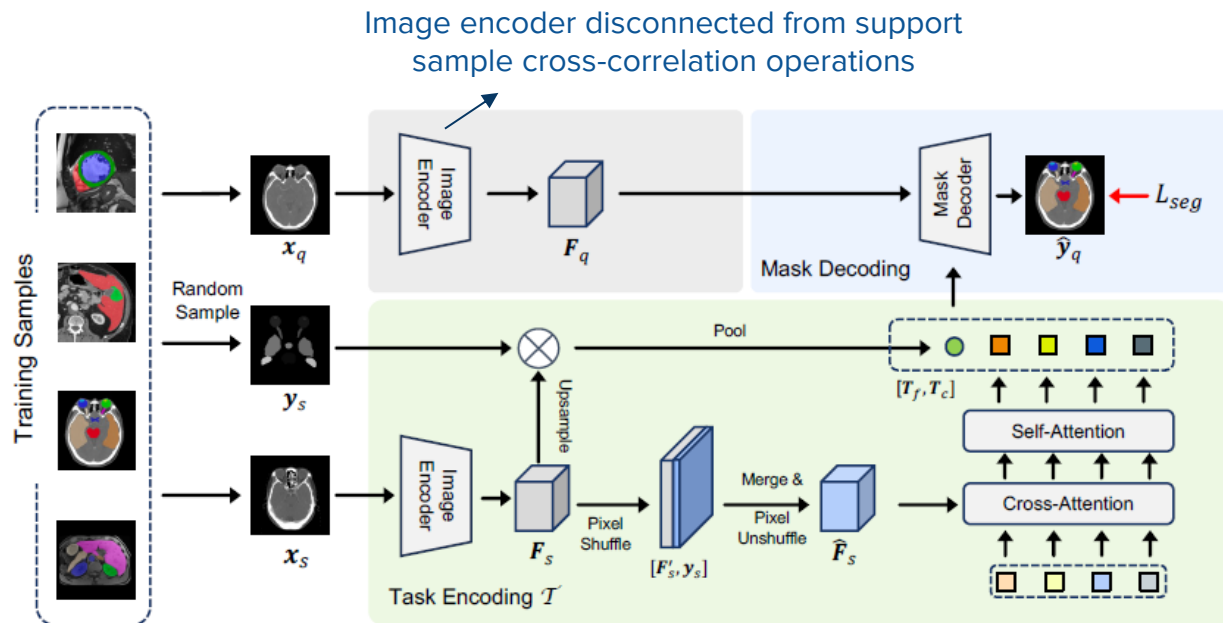
Learning / usage objectives.

In Context Learning



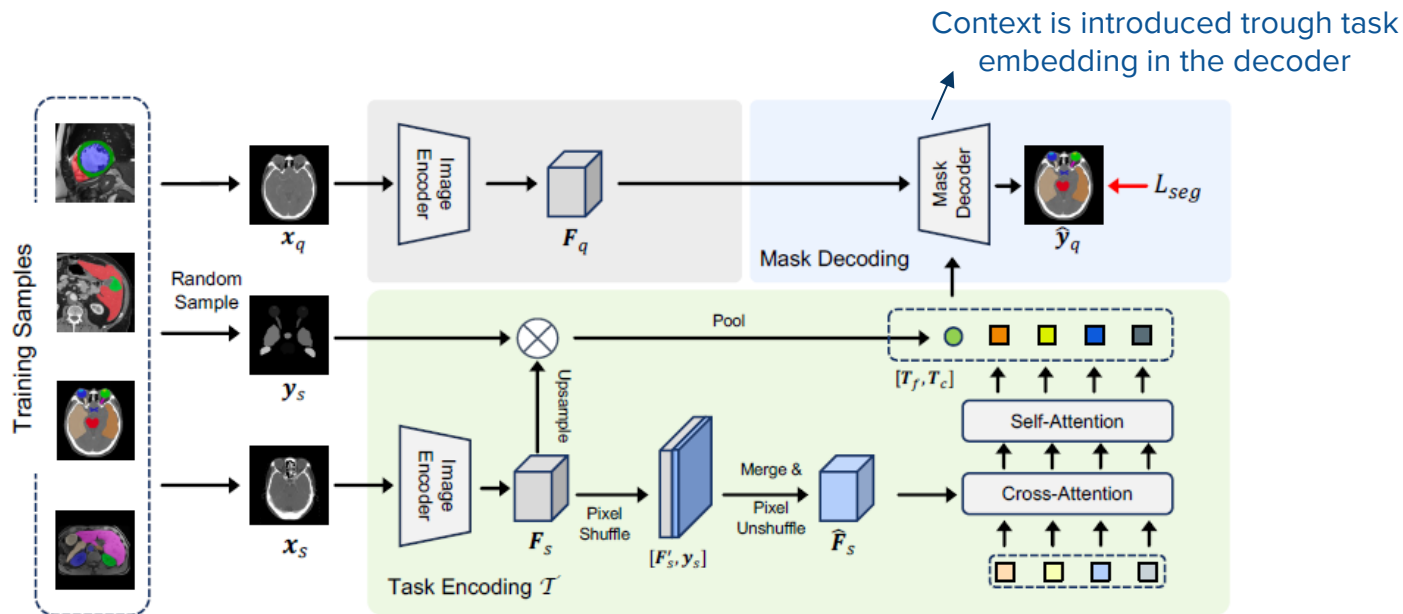
Learning / usage objectives.

In Context Learning



Learning / usage objectives.

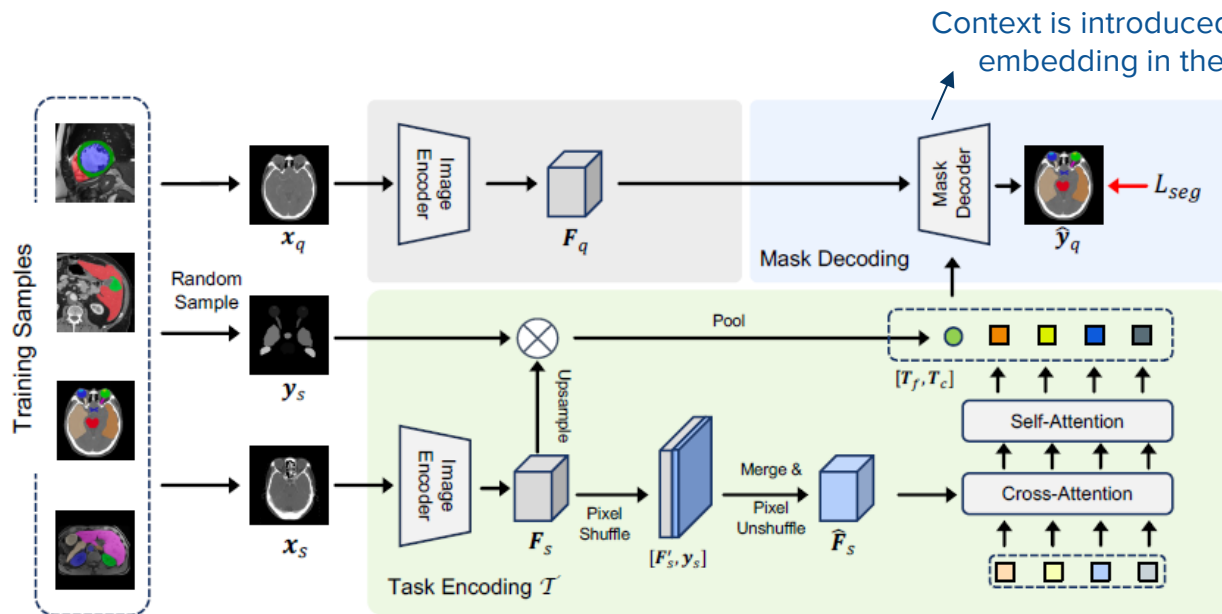
In Context Learning



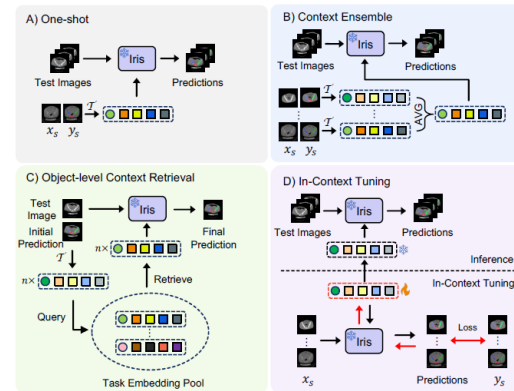
Learning / usage objectives.

Iris

In Context Learning

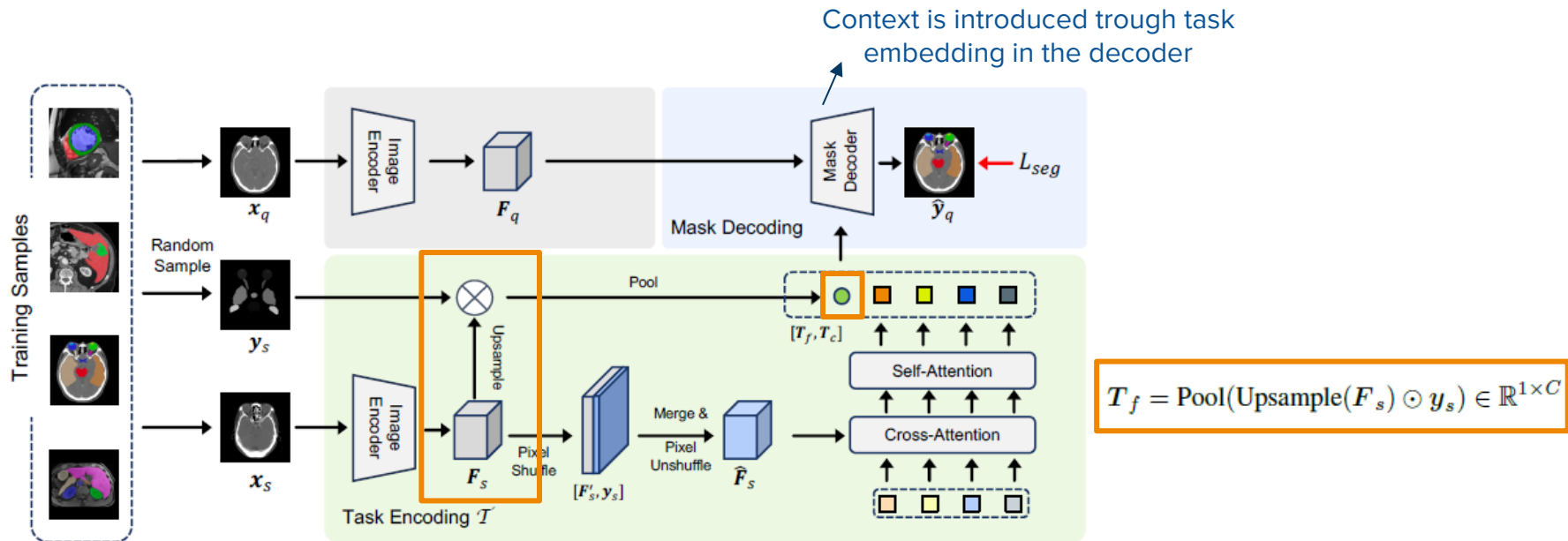


- ✓ Allows multi-class tasks.
- ✓ Disentangles the support set processing and inference – more flexible and efficient scenarios.



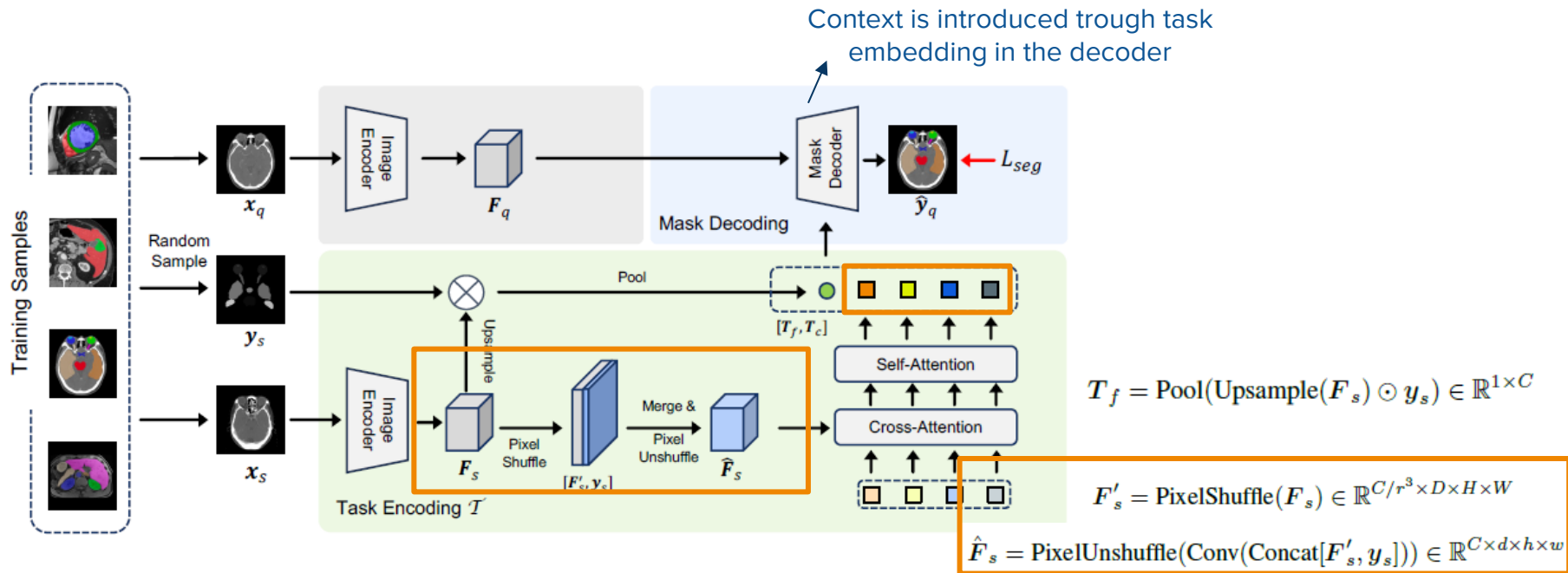
Learning / usage objectives.

In Context Learning



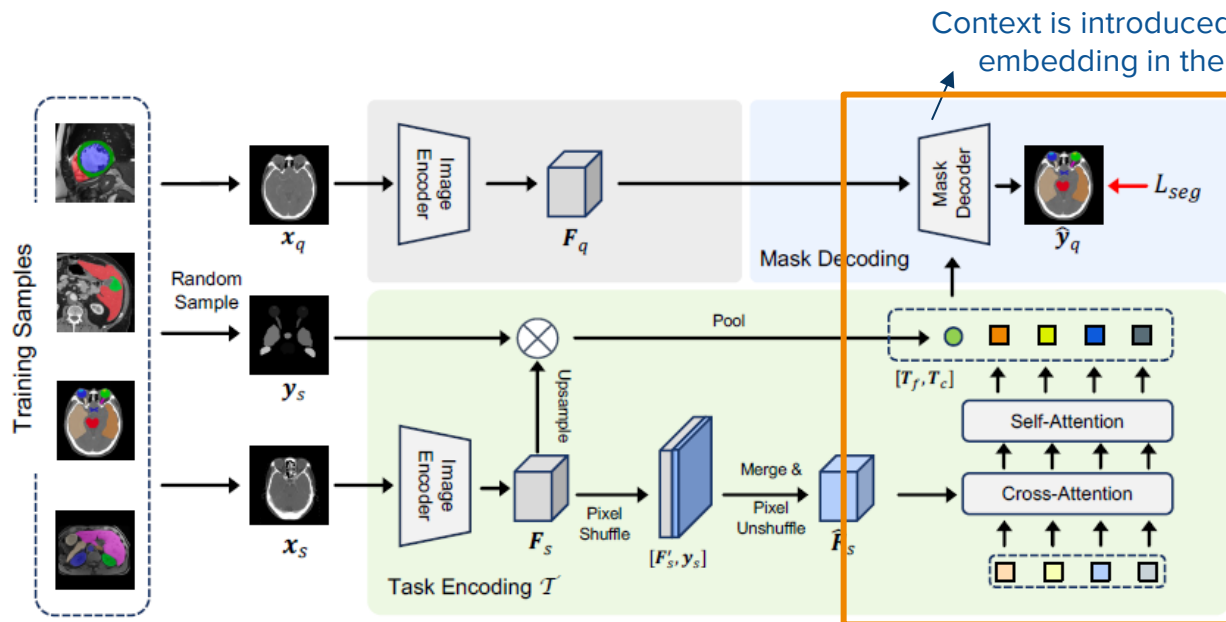
Learning / usage objectives.

In Context Learning



Learning / usage objectives.

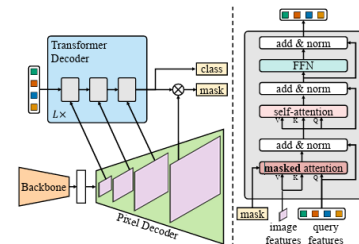
In Context Learning



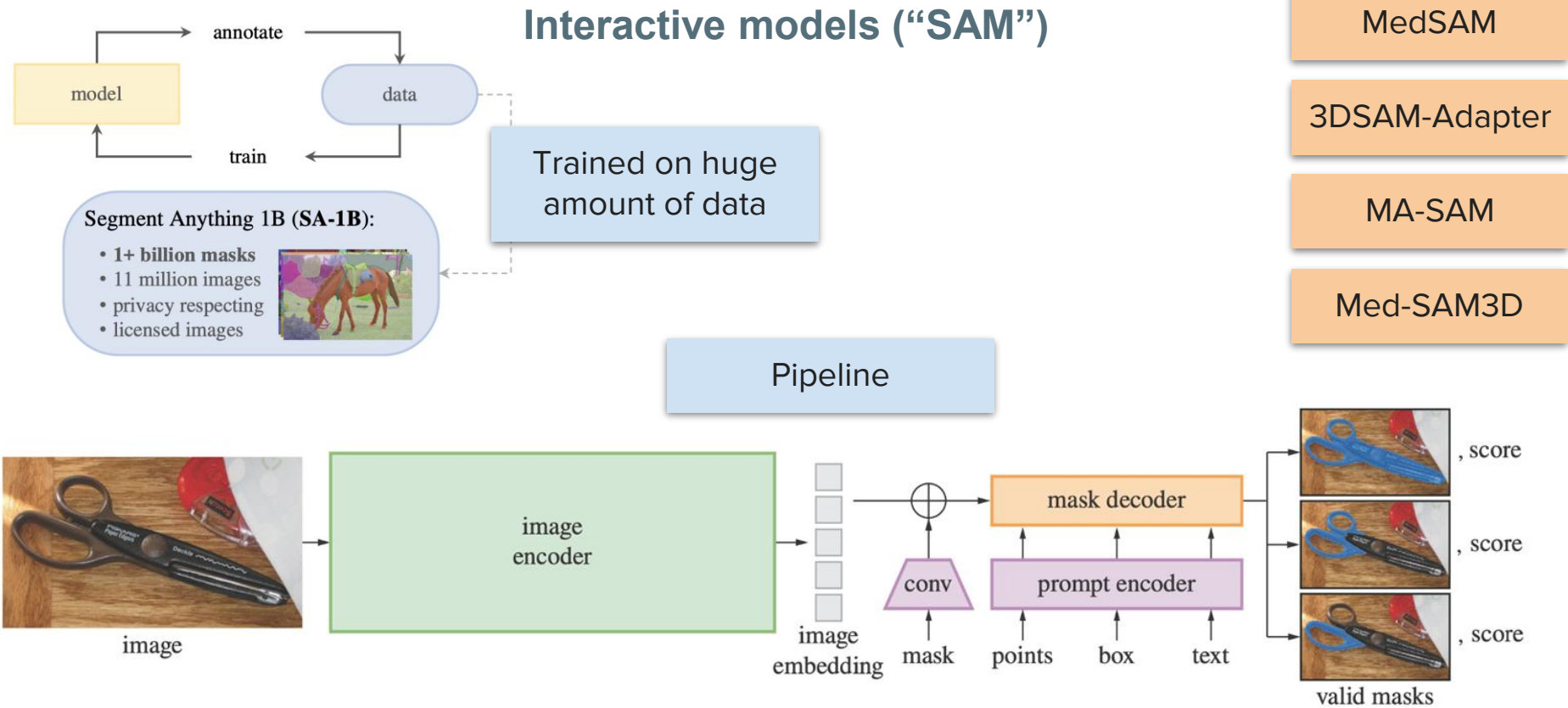
$$F'_q, T' = \text{CrossAttn}(F_q, T)$$

$$\hat{y}_q = D(F'_q, T') \in \{0, 1\}^{K \times D \times H \times W}$$

Decoder is a query-based Transformer



Learning / usage objectives.

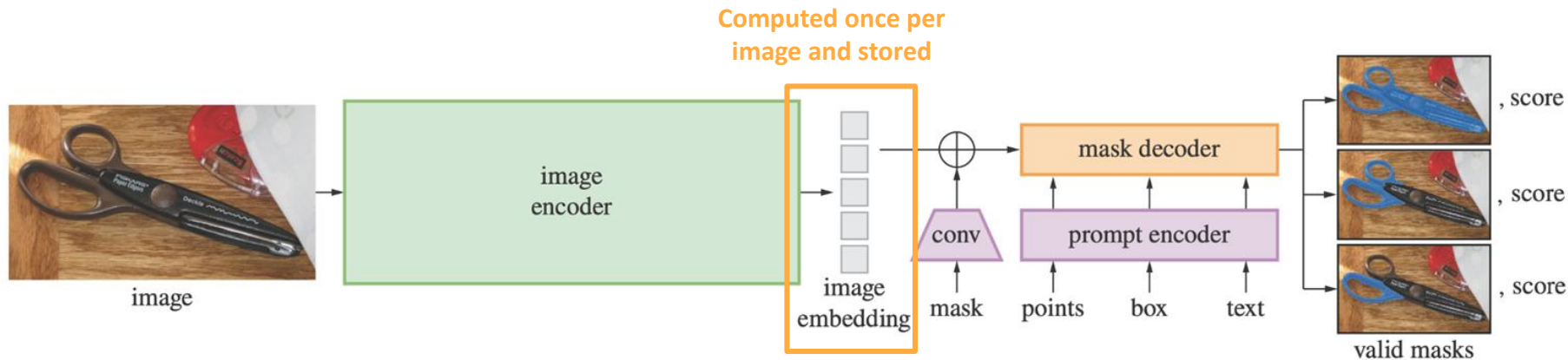


Learning / usage objectives.

SAM

Interactive models (“SAM”)

How is this trained?

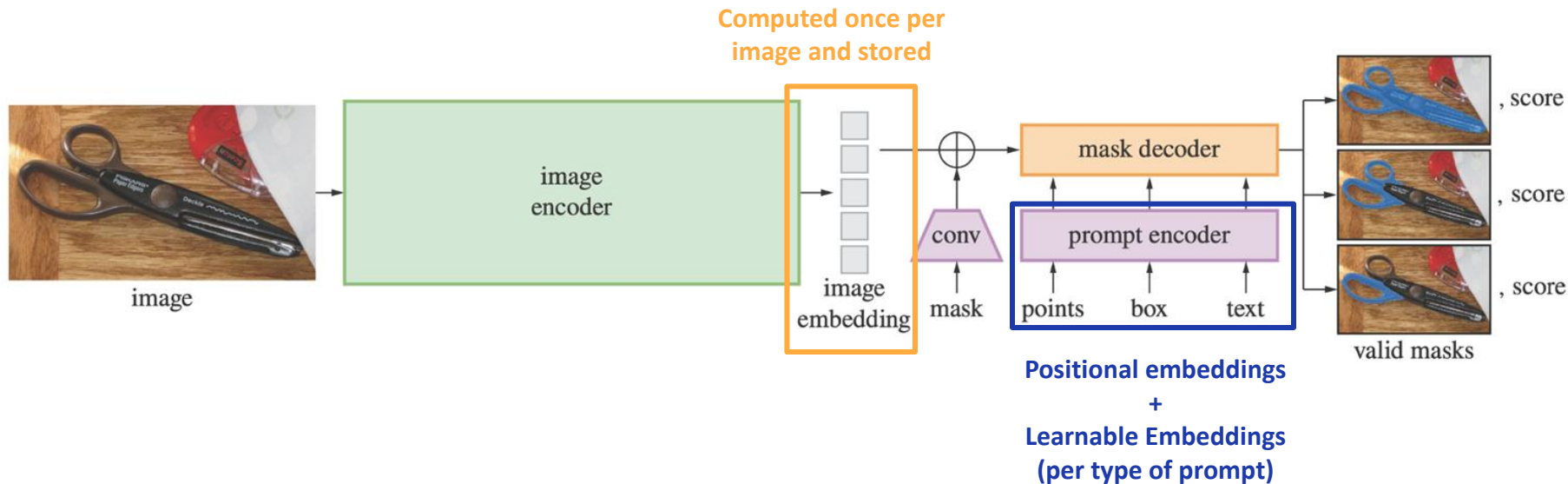


Learning / usage objectives.

SAM

Interactive models (“SAM”)

How is this trained?

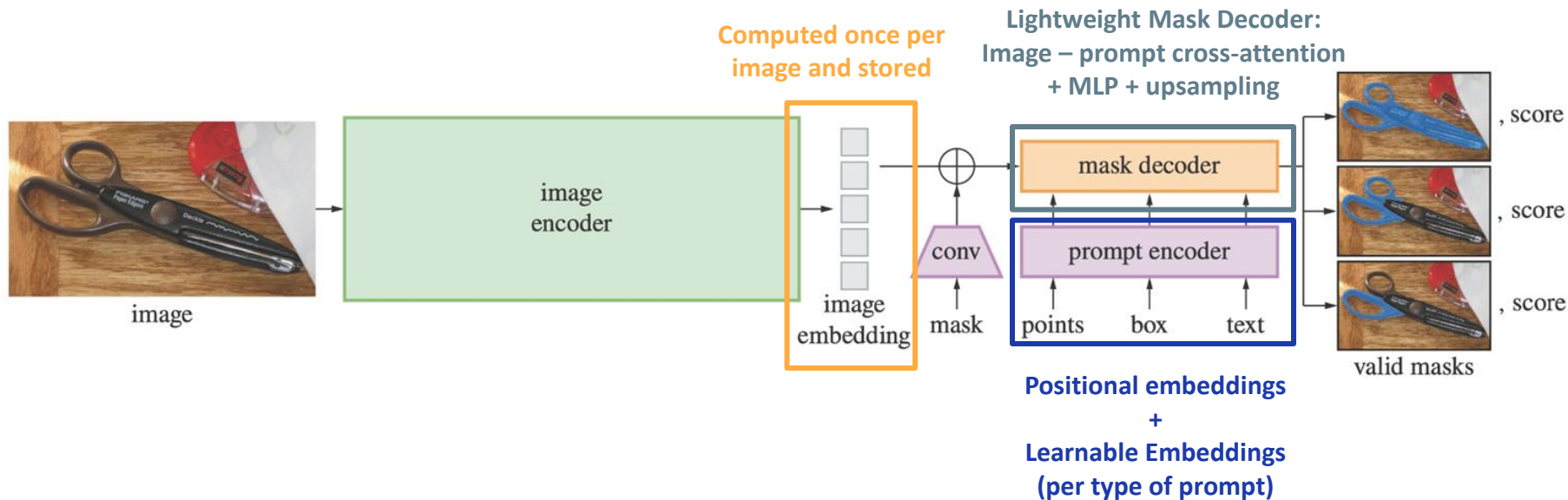


Learning / usage objectives.

SAM

Interactive models (“SAM”)

How is this trained?

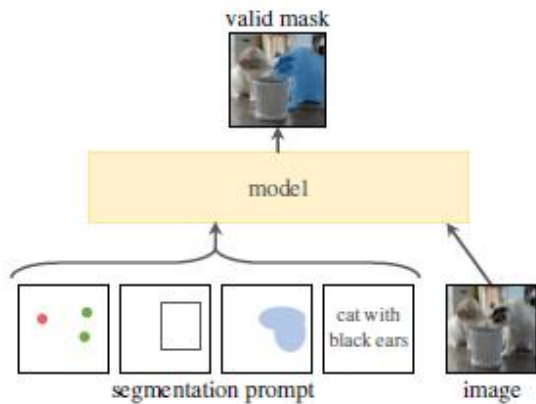


Learning / usage objectives.

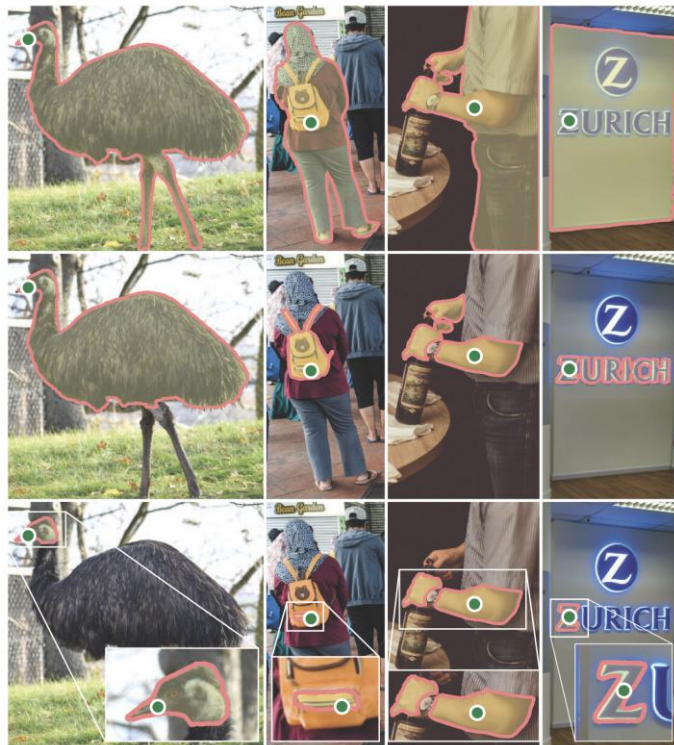
SAM

Interactive models (“SAM”)

And what about inference?

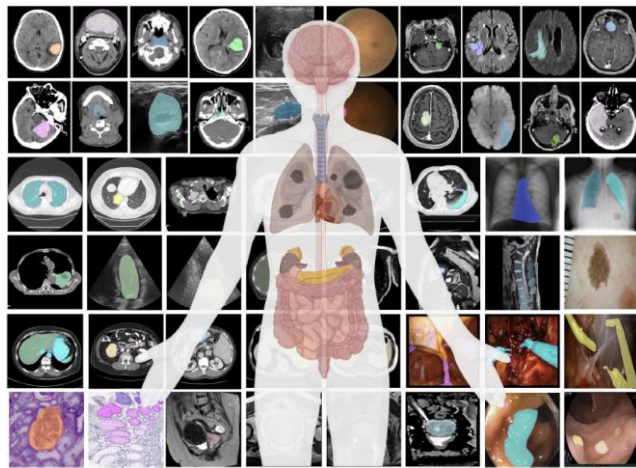


Remember: prompts on test data



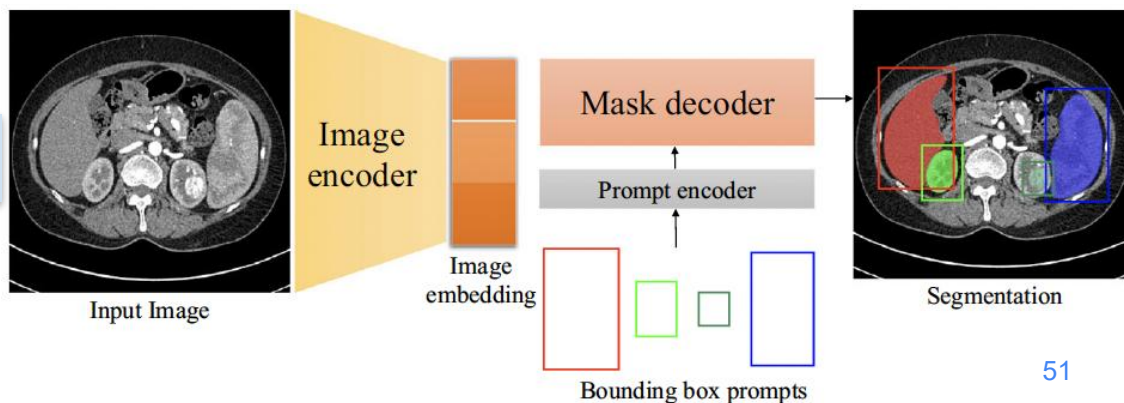
Learning / usage objectives.

Interactive models (“SAM”)



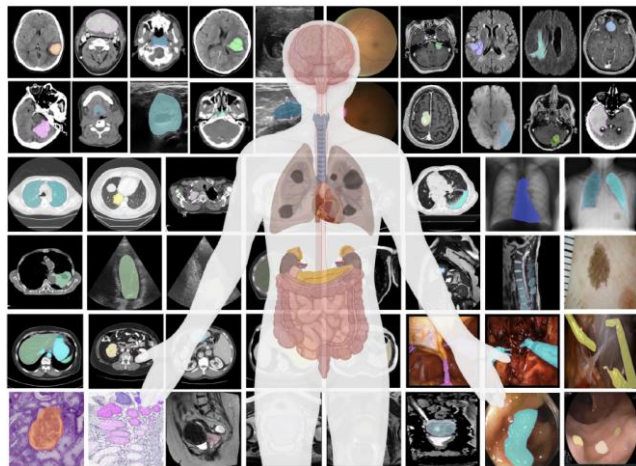
Fine-tuning SAM on huge amount of medical data

Pipeline



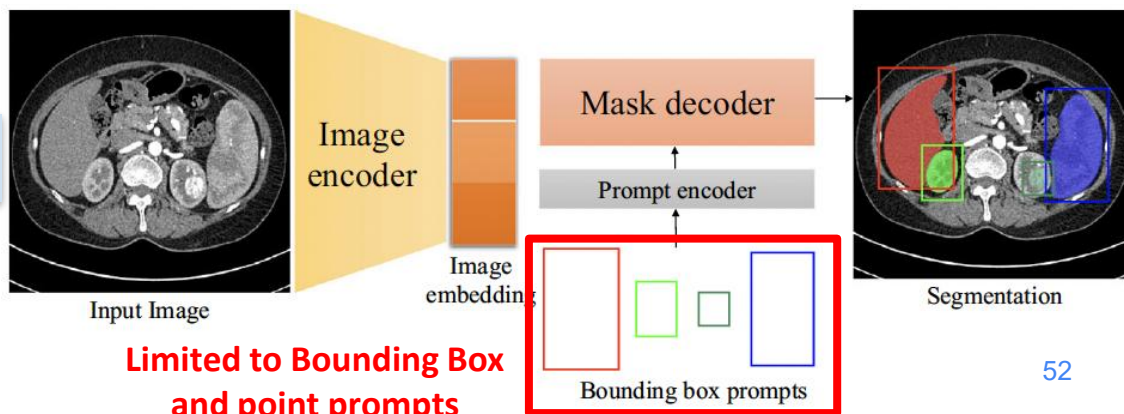
Learning / usage objectives.

Interactive models (“SAM”)



Trained on huge amount of data

Pipeline



How good is the DSC of this bounding box?

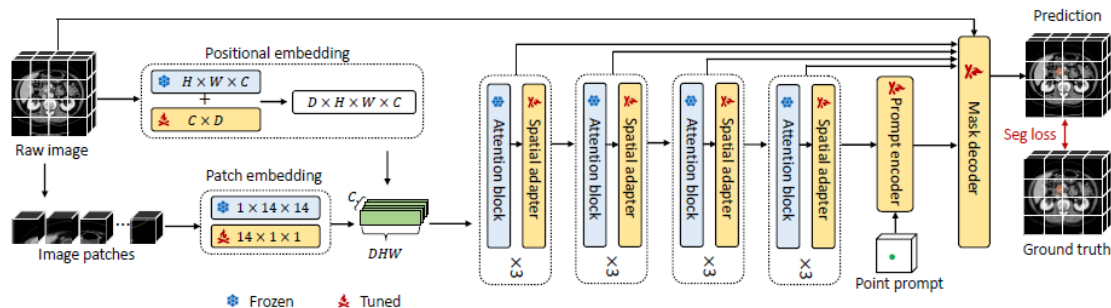
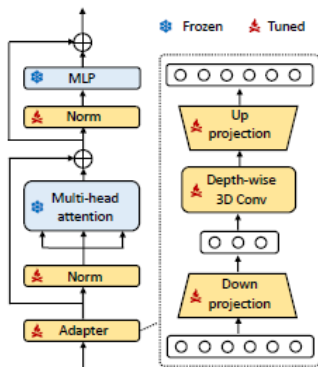
Limited to Bounding Box and point prompts

Learning / usage objectives.

3DSAM-Adapter

Interactive models (“SAM”)

Fine-tuning SAM via
Parameter-Efficient
Fine-Tuning



Gong et al. 3DSAM-adapter: Holistic Adaptation of SAM from 2D to 3D for Promptable Medical Image Segmentation. MedIA'24.

Learning / usage objectives.

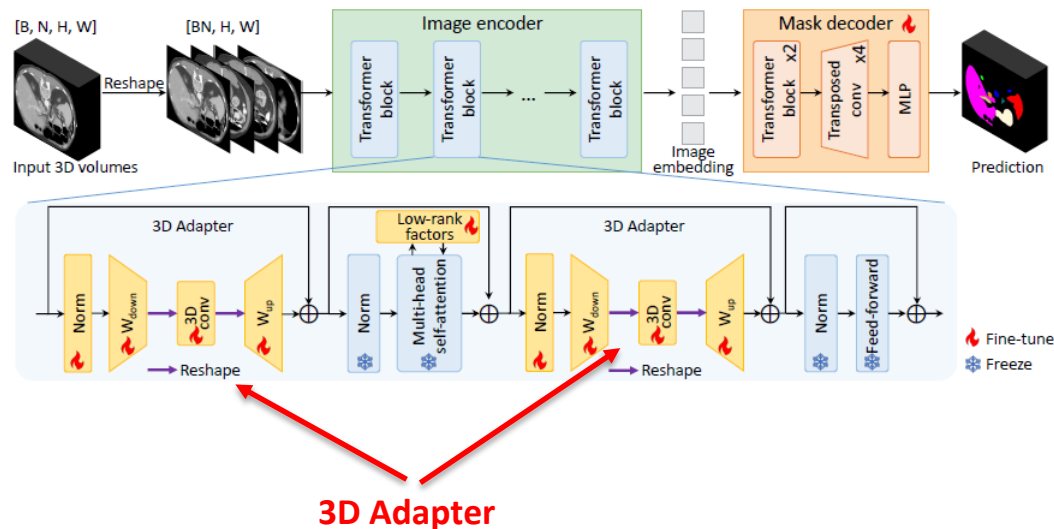
MA-SAM (3D)

Interactive models (“SAM”)

Fine-tuning SAM 2D
via Parameter-Efficient
Fine-Tuning to 3D

→ Adapt for promptable version.

Methods	Dice ↑	NSD ↑
nnU-Net (Isensee et al., 2021)	41.6	62.5
3D UX-Net (Lee et al., 2023)	34.8	52.6
SwinUNETR (Tang et al., 2022b)	40.6	60.0
nnFormer (Zhou et al., 2023a)	36.5	54.0
3DSAM-adapter (automatic) (Gong et al., 2023)	30.2	45.4
3DSAM-adapter (10 pts/scan) (Gong et al., 2023)	57.5	79.6
MA-SAM (automatic)	40.2	59.1
MA-SAM (1 tight 3D bbx/scan)	80.3	97.9
MA-SAM (1 relaxed 3D bbx/scan)	74.7	97.1



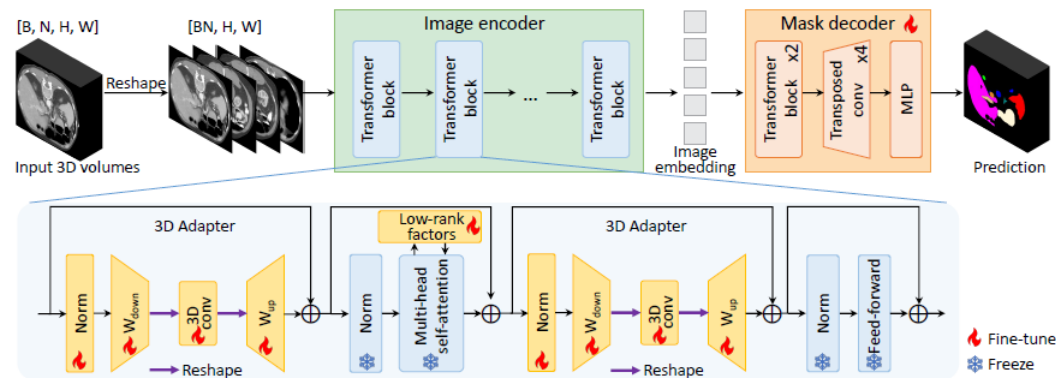
Learning / usage objectives.

MA-SAM (3D)

Interactive models (“SAM”)

Fine-tuning SAM 2D
via Parameter-Efficient
Fine-Tuning to 3D

→ Fine-tuning SAM.



Methods	Spleen	R.Kd	L.Kd	GB	Eso.	Liver	Stomach	Aorta	IVC	Veins	Pancreas	AG	Average
Dice [%] ↑													
nnU-Net (Isensee et al., 2021)	97.0	95.3	95.3	63.5	77.5	97.4	89.1	90.1	88.5	79.0	87.1	75.2	86.3
3D UX-Net (Lee et al., 2023)	94.6	94.2	94.3	59.3	72.2	96.4	73.4	87.2	84.9	72.2	80.9	67.1	81.4
SwinUNETR (Tang et al., 2022b)	95.6	94.2	94.3	63.6	75.5	96.6	79.2	89.9	83.7	75.0	82.2	67.3	83.1
nnFormer (Zhou et al., 2023a)	93.5	94.9	95.0	64.1	79.5	96.8	90.1	89.7	85.9	77.8	85.6	73.9	85.6
SAMed_h (Zhang and Liu, 2023)	95.3	92.1	92.9	62.1	75.3	96.4	90.2	87.6	79.8	74.2	77.9	61.0	82.1
MA-SAM (Ours)	96.7	95.1	95.4	68.2	82.1	96.9	92.8	91.1	87.5	79.8	86.6	73.9	87.2

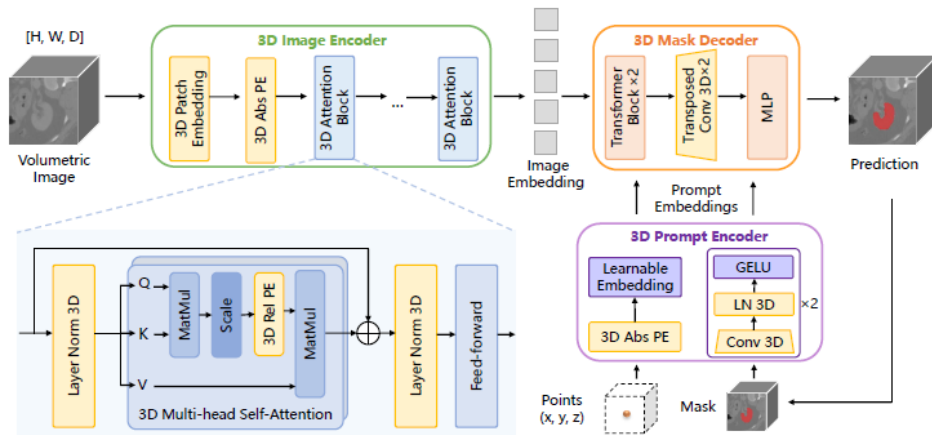
+0.9%

Learning / usage objectives.

Med-SAM3D

Training a 3D SAM
with Medical data
from Scratch

Interactive models (“SAM”)



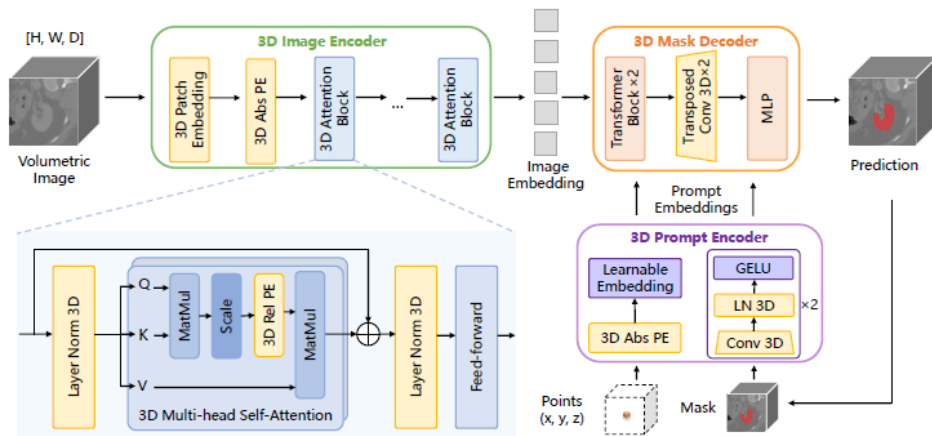
Model	Prompt	Inference Time (s)	Dice (%)		
			Seen	Unseen	Overall
SAM	N pts	$N(\tau + 0.13)$	16.79	11.73	16.15
SAM-Med2D	N pts	$N(\tau + 0.04)$	38.91	22.55	36.83
SAM-Med3D	1 pt	$\tau + 2$	81.98	37.02	76.27
SAM	$3N$ pts	$3N(\tau + 0.19)$	34.61	15.94	32.24
SAM-Med2D	$3N$ pts	$3N(\tau + 0.07)$	51.46	29.70	48.70
SAM-Med3D	3 pts	$3\tau + 3$	84.14	43.80	79.02
SAM	$5N$ pts	$5N(\tau + 0.25)$	49.39	21.86	45.89
SAM-Med2D	$5N$ pts	$5N(\tau + 0.10)$	51.89	30.41	49.17
SAM-Med3D	5 pts	$5\tau + 4$	84.62	46.26	79.75
SAM-Med3D	10 pts	$10\tau + 6$	85.19	49.92	80.71

Learning / usage objectives.

Med-SAM3D

Training a 3D SAM
with Medical data
from Scratch

Interactive models (“SAM”)



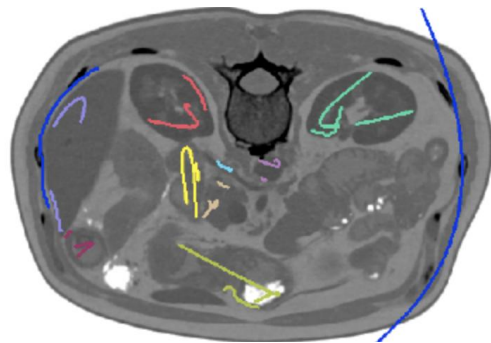
1 point for each N slices

Model	Prompt	Inference Time (s)	Dice (%)		
			Seen	Unseen	Overall
SAM	N pts	$N(\tau + 0.13)$	16.79	11.73	16.15
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SAM-Med3D	5 pts	$5\tau + 4$	84.62	46.26	79.75
SAM-Med3D	10 pts	$10\tau + 6$	85.19	49.92	80.71

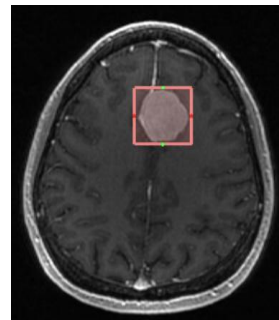
Improved over 2D version

Learning / usage objectives.

Interactive models (“SAM”)



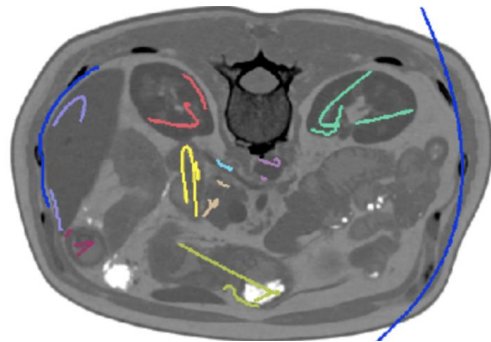
SAM is promptable
(i.e., requires user interaction
per EACH test image)



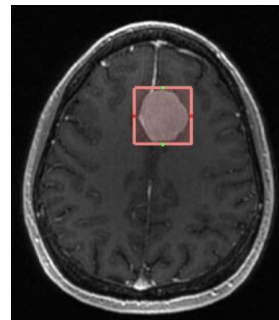
SAM only handles
binary segmentation
(one class at a time)

Learning / usage objectives.

Interactive models (“SAM”)



SAM is promptable
(i.e., requires user interaction
per EACH test image)



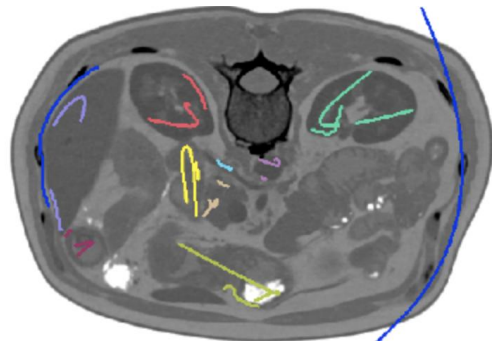
SAM only handles
binary segmentation
(one class at a time)

Dataset	Modality	Task-specific		General-purpose			
		UNETR [11]	nnU-Net [16]	SAM-Med2D [6] (<i>N</i> pts)	SegVol [8] (pt+text)	Ours (1 pt)	Ours (10 pts)
TotalSegmentator [36]	CT	75.05	85.22	38.26	-	84.68	87.59
KiTS21 [12]	CT	70.75	75.32	68.74	-	72.06	75.37
AMOS-CT [17]	CT	78.33	88.87	49.61	-	79.94	83.99
AMOS-MR [17]	MR	76.29	86.92	45.53	-	75.41	81.13
BTCV* [19]	CT	78.99	81.92	50.05	73.81	79.17	83.01
TDSC-ABUS23* [33]	US*	-	45.08	49.39	-	36.08	54.35

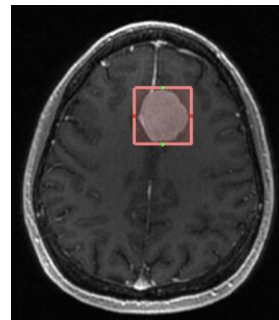
SAM yields sometimes
lower results to task-
specific models

Learning / usage objectives.

Interactive models (“SAM”)



SAM is promptable
(i.e., requires user interaction
per EACH test image)



SAM only handles
binary segmentation
(one class at a time)

Dataset	Modality	Task-specific		General-purpose			
		UNETR [11]	nnU-Net [16]	SAM-Med2D [6] (<i>N</i> pts)	SegVol [8] (pt+text)	Ours (1 pt)	Ours (10 pts)
TotalSegmentator [36]	CT	75.05	85.22	38.26	-	84.68	87.59
KiTS21 [12]	CT	70.75	75.32	68.74	-	72.06	75.37
AMOS-CT [17]	CT	78.33	88.87	49.61	-	79.94	83.99
AMOS-MR [17]	MR	76.29	86.92	45.53	-	75.41	81.13
BTCV* [19]	CT	78.99	81.92	50.05	73.81	79.17	83.01
TDSC-ABUS23* [33]	US*	-	45.08	49.39	-	36.08	54.35

SAM yields sometimes
lower results to task-
specific models

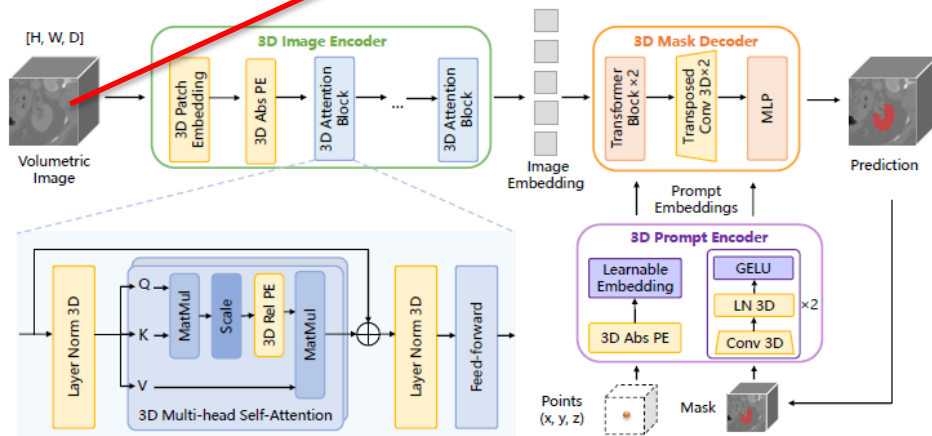
Learning / usage objectives.

Med-SAM3D

Other
Details

Interactive models (“SAM”)

Pre-computed ROI in whole-body scans



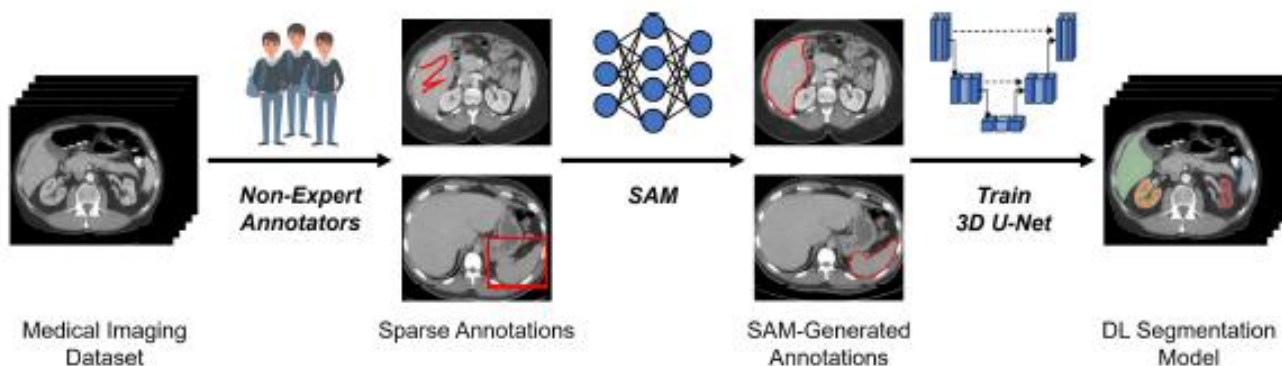
Model	Prompt	Inference Time (s)	Dice (%)		
			Seen	Unseen	Overall
SAM	N pts	$N(\tau + 0.13)$	16.79	11.73	16.15
SAM-Med2D	N pts	$N(\tau + 0.04)$	38.91	22.55	36.83
SAM-Med3D	1 pt	$\tau + 2$	81.98	37.02	76.27
SAM	$3N$ pts	$3N(\tau + 0.19)$	34.61	15.94	32.24
SAM-Med2D	$3N$ pts	$3N(\tau + 0.07)$	51.46	29.70	48.70
SAM-Med3D	3 pts	$3\tau + 3$	84.14	43.80	79.02
SAM	$5N$ pts	$5N(\tau + 0.25)$	49.39	21.86	45.89
SAM-Med2D	$5N$ pts	$5N(\tau + 0.10)$	51.89	30.41	49.17
SAM-Med3D	5 pts	$5\tau + 4$	84.62	46.26	79.75
SAM-Med3D	10 pts	$10\tau + 6$	85.19	49.92	80.71

Iterative random points over the error region
(explicit access to GT)

Learning / usage objectives.

Interactive models (“SAM”)

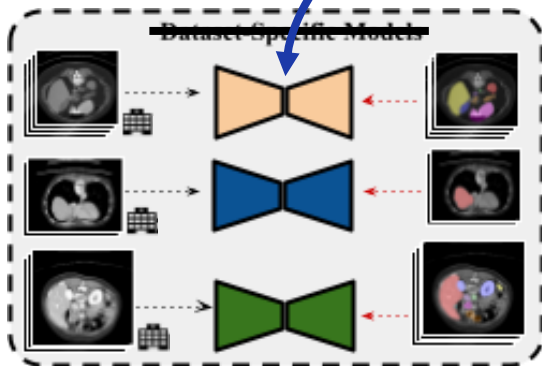
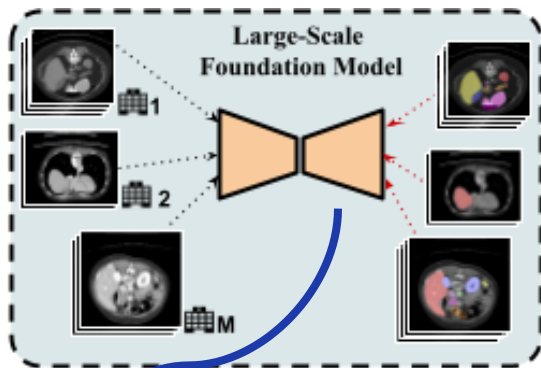
Applications in Active
Learning / Annotations



Kulkarni et al. Anytime, Anywhere, Anyone: Investigating the Feasibility of SAM for Crowd-Sourcing Medical Image Annotations. MIDL'24.

Foundation models for medical image segmentation

Trained with many
data / tasks / domains



+ Some target
domain feedback
(ideally small)

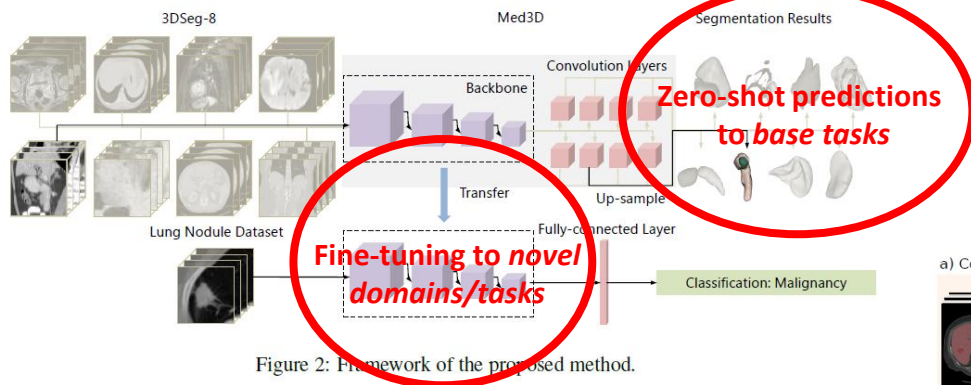
Organizing the mess!

1. Types of foundation models: a data perspective.
 - A. Generalist vs. Specialized
 - B. 2D vs. 3D
 - C. Multimodal vs. Unimodal
2. Learning/Usage Objectives
 - A. Zero-shot / Transfer Learning
 - B. In-Context Learning
 - C. Interactive Models ("SAM")
3. Zero-shot / Adaptation-oriented (3D data)
 - A. How to pre-train?
 - B. How useful are foundation models? Limitations on the adaptation stage
 - C. Few-shot Parameter-Efficient Fine-tuning

Learning / usage objectives.

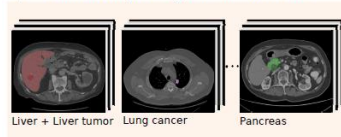
Zero-shot / Transfer Learning

ImageNet Philosophy

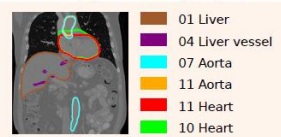


Chen et al. Med3D: Transfer Learning for 3D Medical Image Analysis. ArXiv'19.

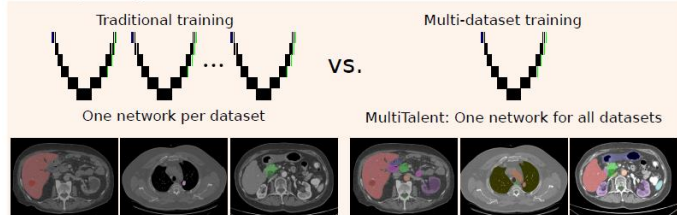
a) Collection of partially labeled datasets



b) Contradicting and overlapping classes



c) Training strategies



Ulrich et al. MultiTalEnt: A Multi-Dataset Approach to Medical Image Segmentation. MICCAI'23.

Med3D('19)

CLIP-Driven

MultiTalent

UniSeg

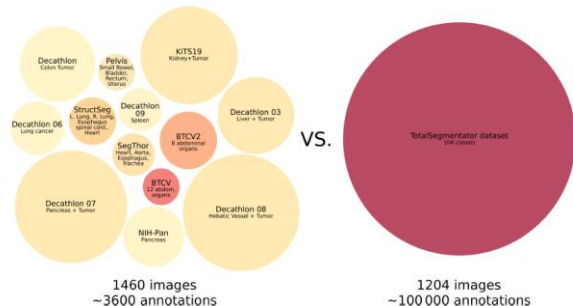
SuPreM

HERMES

FSEFT

Zero-shot /Adaptation Oriented (3D Data)

Why volumetric (and mostly CT)?



Ulrich et al. MultiTalent: A Multi-Dataset Approach to Medical Image Segmentation. MICCAI'23.

Med3D('19)

CLIP-Driven

MultiTalent

UniSeg

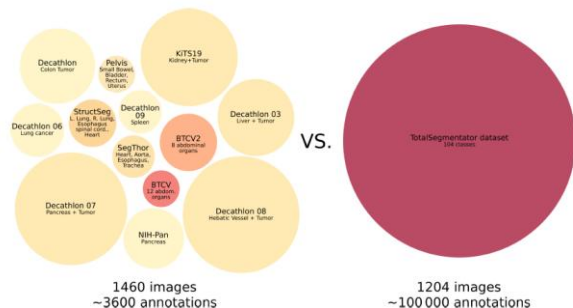
SuPreM

Datasets	# Targets	# Scans	Annotated Organs or Tumors
1. Pancreas-CT [62]	1	82	Pancreas
2. LiTS [3]	2	201	Liver, Liver Tumor*
3. KiTS [25]	2	300	Kidney, Kidney Tumor*
4. AbdomenCT-1K [45]	4	1,000	Spleen, Kidney, Liver, Pancreas
5. CT-ORG [60]	4	140	Lung, Liver, Kidneys and Bladder
6. CHAOS [73]	4	40	Liver, Left Kidney, Right Kidney, Spl
7-11. MSD CT Tasks [1]	9	947	Spl, Liver and Tumor*, Lung Tumor*, Pan and Tumor*, Hepatic Vessel and Tumor*
12. BTCV [37]	13	50	Spl, RKid, LKid, Gall, Eso, Liv, Sto, Aor, IVC, R&SVeins, Pan, RAG, LAG
13. AMOS22 [32]	15	500	Spl, RKid, LKid, Gall, Eso, Liv, Sto, Aor, IVC, Pan, RAG, LAG, Duo, Bla, Pro/UTE
14. WORD [44]	16	150	Spl, RKid, LKid, Gall, Eso, Liv, Sto, Pan, RAG, Duo, Col, Int, Rec, Bla, LFH, RFH
15. 3D-IRCADb [67]	13	20	Liv, Liv Cyst, RLung, LLung, Venous, PVein, Aor, Spl, RKid, LKid, Gall, IVC
16. TotalSegmentator [79]	104	1,024	Clavicula, Humerus, Scapula, Rib 1-12, Vertebrae C1-7, Vertebrae T1-9, Vertebrae L1-5, Hip, Sacrum, Femur, Aorta, Pulmonary Artery, Right Ventricle, Right Atrium, Left Atrium, Left Ventricle, Myocardium, PVein, SVein, IVC, Iliac Artery, Iliac Vena, Brain, Trachea, Lung Upper Lobe, Lung Middle Lobe, Lung Lower Lobe, AG, Spl, Liv, Gall, Pan, Kid, Eso, Sto, Duo, Small Bowel, Colon, Bla, Autochthon, Iliopsoas, Gluteus Minimus, Gluteus Medius, Gluteus Maximus
17. JHH (private)	21	5,038	Aor, AG, CBD, Celiac AA, Colon, duo, Gall, IVC, Lkid, RKid, Liv, Pan, Pan Duct, SMA, Small bowel, Spl, Sto, Veins, Kid LtRV, Kid RtRV, CBD Stent, PDAC*, PanNET*, Pancreatic Cyst*

Liu et al. CLIP-Driven Universal Model for Organ Segmentation and Tumor Detection. ICCV'23.

Zero-shot /Adaptation Oriented (3D Data)

Why volumetric (and mostly CT)?



Ulrich et al. MultiTalent: A Multi-Dataset Approach to Medical Image Segmentation. MICCAI'23.

- A good number of annotated scans publicly available. (current models are pre-trained with 2K CTs)
- Anatomical morphology is natural 3D.
- Labeling at voxel level is tremendously costly for practitioners (10 min per structure).
- Enormous potential of FMs to address inter-center, inter-scan and demographics variabilities.

Med3D('19)

CLIP-Driven

MultiTalent

UniSeg

SuPreM

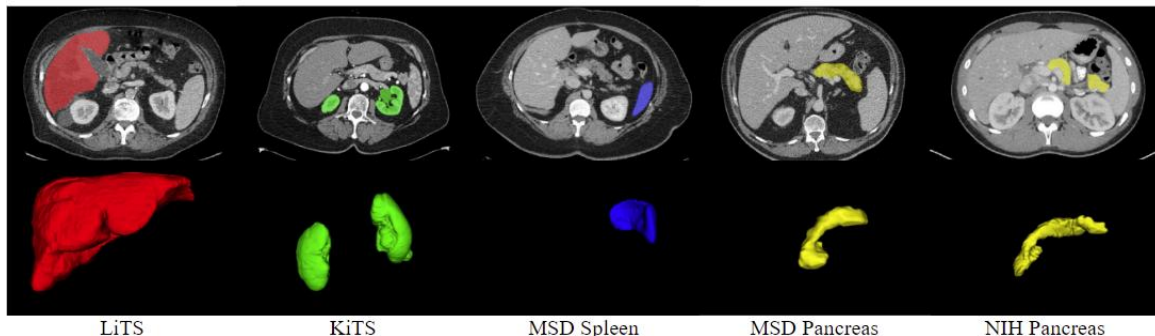
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Liu et al. CLIP-Driven Universal Model for Organ Segmentation and Tumor Detection. ICCV'23.

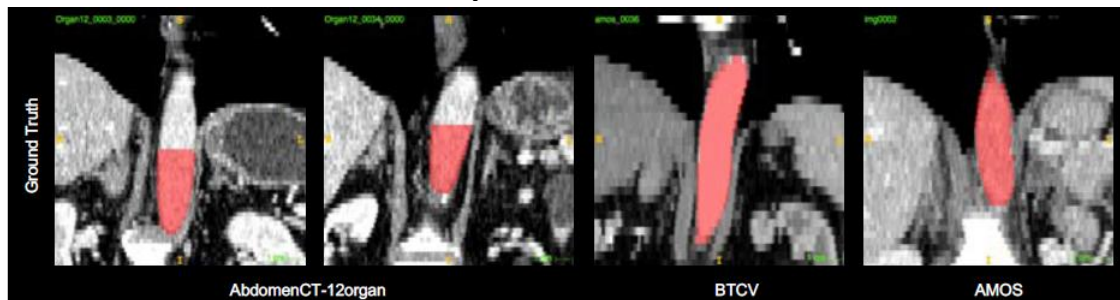
Zero-shot /Adaptation Oriented (3D Data)

Challenges of Dataset Assembling

Partially-labeled datasets



Inconsistent annotation protocols



Med3D('19)

CLIP-Driven

MultiTalent

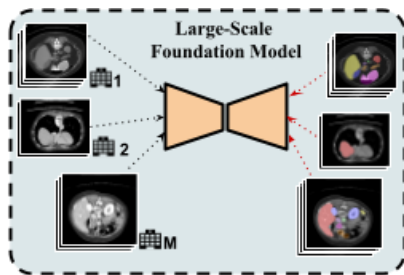
UniSeg

SuPreM

Zero-shot /Adaptation Oriented (3D Data)

MultiTalent

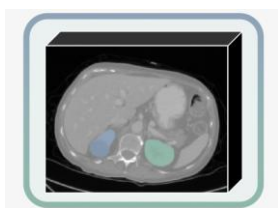
FSEFT



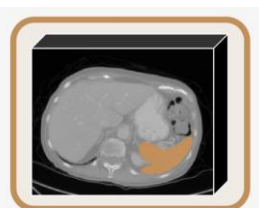
How to pre-train? Masked CE

Assembly Dataset with
Partial Labels

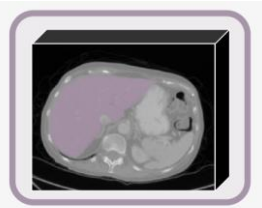
$$\mathcal{D}_T = \{(\mathbf{X}_n, \mathbf{Y}_n, \mathbf{w}_n)\}_{n=1}^N$$



Dataset A: kidney



Dataset B: spleen



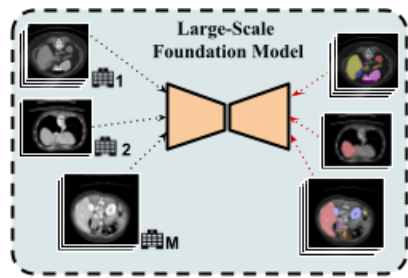
Dataset D: liver



Zero-shot /Adaptation Oriented (3D Data)

MultiTalent

FSEFT



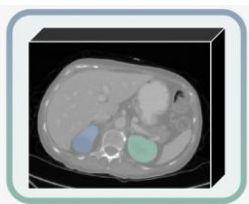
How to pre-train? Masked CE

Total Number of
Categories

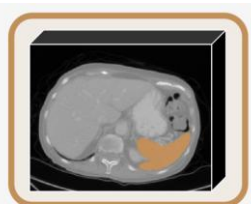
$$w^c = [0, 1, 1, 0, 0, 0, 1, 0, 0]$$

Assembly Dataset with
Partial Labels

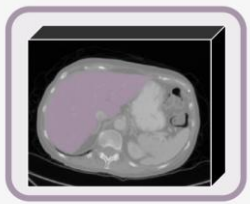
$$\mathcal{D}_T = \{(\mathbf{X}_n, \mathbf{Y}_n, \mathbf{w}_n)\}_{n=1}^N$$



Dataset A: kidney



Dataset B: spleen

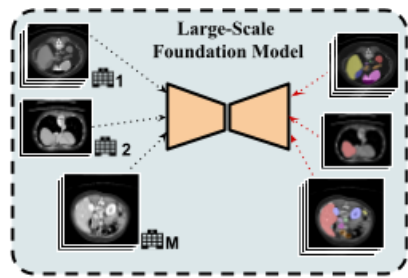


Dataset D: liver

Zero-shot /Adaptation Oriented (3D Data)

MultiTalent

FSEFT



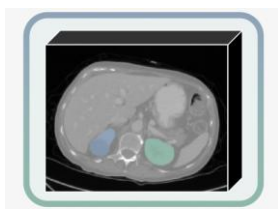
How to pre-train? Masked CE

Assembly Dataset with
Partial Labels

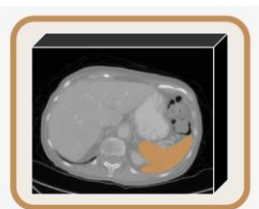
Annotated on its dataset

$$w^c = [0, 1, 1, 0, 0, 0, 1, 0, 0]$$

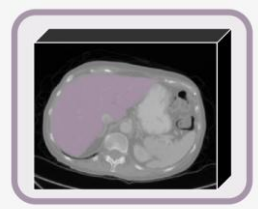
$$\mathcal{D}_T = \{(\mathbf{X}_n, \mathbf{Y}_n, \mathbf{w}_n)\}_{n=1}^N$$



Dataset A: kidney



Dataset B: spleen

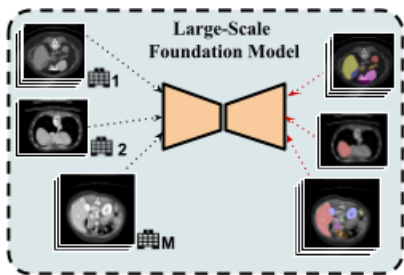


Dataset D: liver

Zero-shot /Adaptation Oriented (3D Data)

MultiTalent

FSEFT



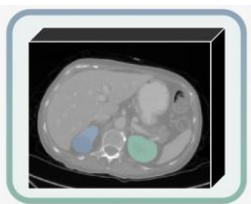
How to pre-train? Masked CE

NOT annotated on its
dataset

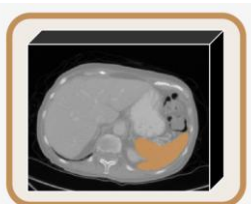
$$w^c = [0, 1, 1, 0, 0, 0, 1, 0, 0]$$

Assembly Dataset with
Partial Labels

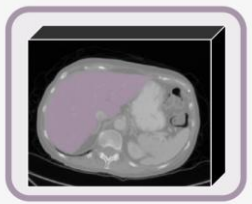
$$\mathcal{D}_T = \{(\mathbf{X}_n, \mathbf{Y}_n, \mathbf{w}_n)\}_{n=1}^N$$



Dataset A: kidney



Dataset B: spleen

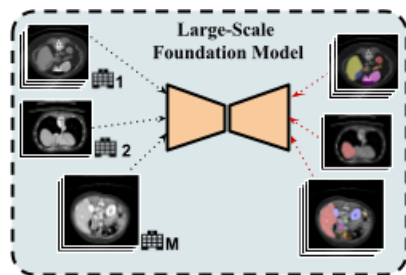


Dataset D: liver

Zero-shot /Adaptation Oriented (3D Data)

MultiTalent

FSEFT



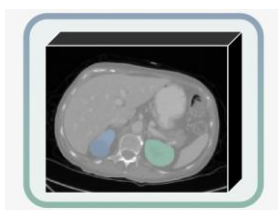
How to pre-train? Masked CE

1. Forward Encoder-Decoder

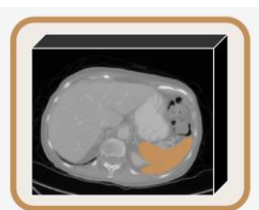
$$\mathbf{Z}_n = \theta_f(\mathbf{X}_n)$$

Assembly Dataset with
Partial Labels

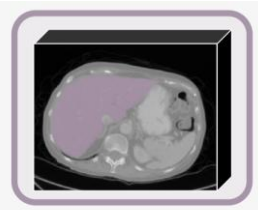
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Dataset A: kidney



Dataset B: spleen

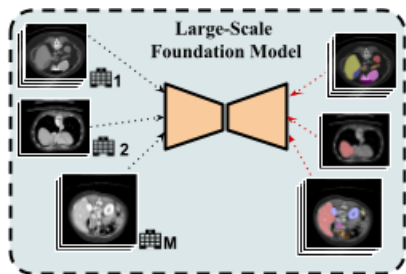


Dataset D: liver

Zero-shot /Adaptation Oriented (3D Data)

MultiTalent

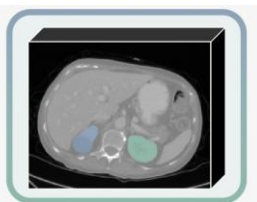
FSEFT



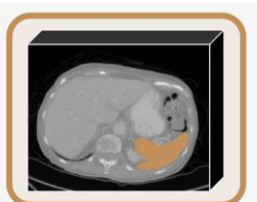
How to pre-train? Masked CE

Assembly Dataset with
Partial Labels

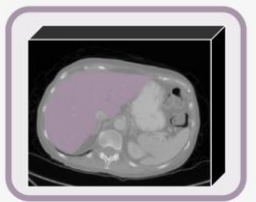
$$\mathcal{D}_T = \{(\mathbf{X}_n, \mathbf{Y}_n, \mathbf{w}_n)\}_{n=1}^N$$



Dataset A: kidney



Dataset B: spleen



Dataset D: liver

1. Forward Encoder-Decoder

$$\mathbf{Z}_n = \theta_f(\mathbf{X}_n)$$

2. Forward Classifier + Sigmoid activation

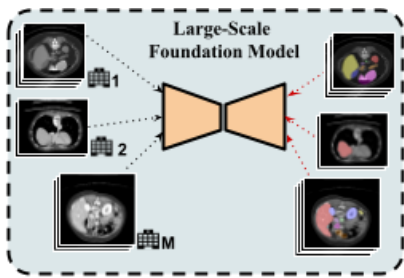
$$\hat{\mathbf{Y}}_n = \sigma(\theta_c(\mathbf{Z}_n))$$

Disentangle prediction
for each task
(softmax might affect not-
annotated categories)

Zero-shot /Adaptation Oriented (3D Data)

MultiTalent

FSEFT



Assembly Dataset with
Partial Labels

$$\mathcal{D}_T = \{(\mathbf{X}_n, \mathbf{Y}_n, \mathbf{w}_n)\}_{n=1}^N$$



How to pre-train? Masked CE

1. Forward Encoder-Decoder

$$\mathbf{Z}_n = \theta_f(\mathbf{X}_n)$$

2. Forward Classifier + Sigmoid activation

$$\hat{\mathbf{Y}}_n = \sigma(\theta_c(\mathbf{Z}_n))$$

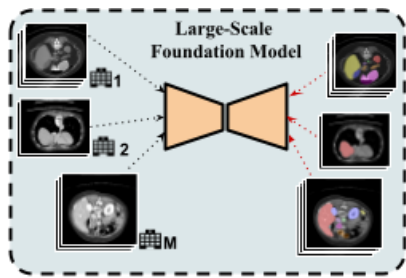
3. Compute any masked segmentation loss, and update

$$\min_{\theta_f, \theta_c} \frac{1}{\sum_k \mathbf{w}_{n,k}} \sum_k \mathbf{w}_{n,k} \mathcal{L}_{SEG}(\mathbf{Y}_{n,k}, \hat{\mathbf{Y}}_{n,k}), \quad n = 1, \dots, N$$

Zero-shot /Adaptation Oriented (3D Data)

MultiTalent

FSEFT



How to pre-train? Masked CE

Assembly Dataset with
Partial Labels

$$\mathcal{D}_T = \{(\mathbf{X}_n, \mathbf{Y}_n, \mathbf{w}_n)\}_{n=1}^N$$



1. Forward Encoder-Decoder

$$\mathbf{Z}_n = \theta_f(\mathbf{X}_n)$$

2. Forward Classifier + Sigmoid activation

$$\hat{\mathbf{Y}}_n = \sigma(\theta_c(\mathbf{Z}_n))$$

3. Compute any masked segmentation loss, and update

$$L = \sum_c \left(\mathbb{1}_c^{(k)} \frac{1}{I} \sum_z BCE(\hat{y}_{z,c}^{(k)}, y_{z,c}^{(k)}) - \frac{2 \sum_z \mathbb{1}_c^{(k)} \hat{y}_{z,c}^{(k)} y_{z,c}^{(k)}}{\sum_z \mathbb{1}_c^{(k)} \hat{y}_{z,c}^{(k)} + \sum_z \mathbb{1}_c^{(k)} y_{z,c}^{(k)}} \right)$$

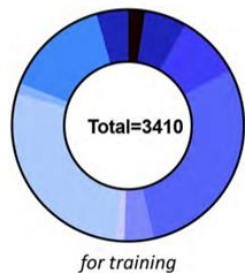
Zero-shot /Adaptation Oriented (3D Data)

CLIP-Driven

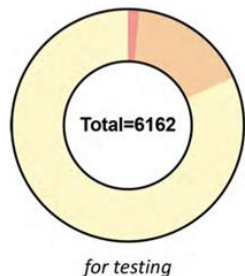
SuPreM

How to pre-train? Masked CE

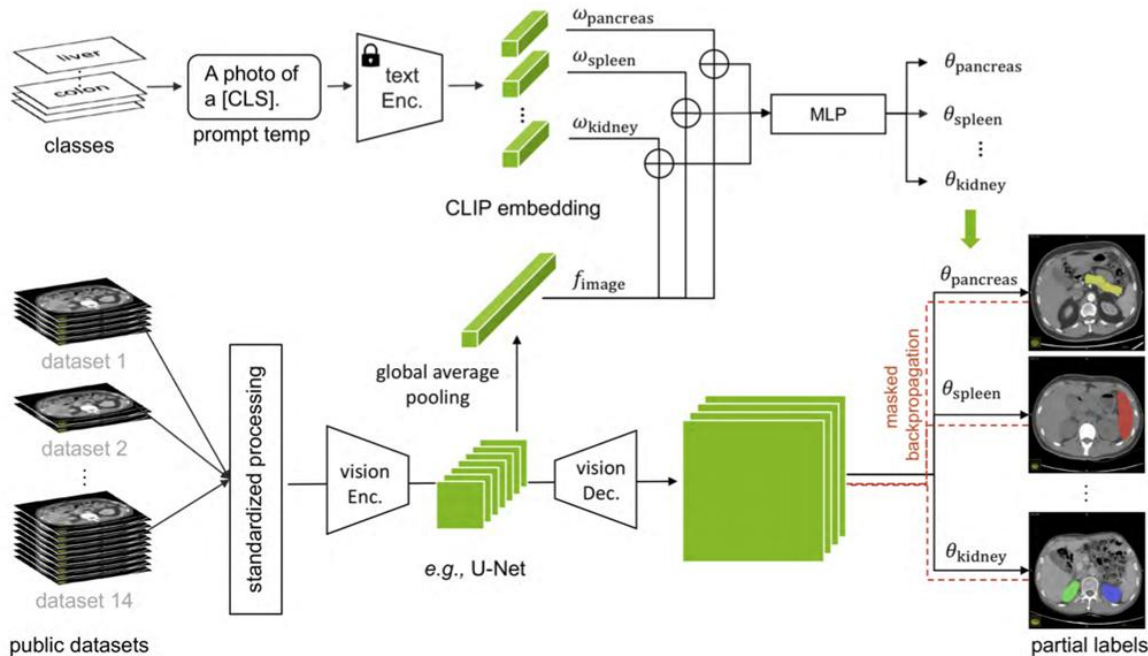
Main idea



- 82 Pancreas-CT (1;0)
- 201 LiTS (1;1)
- 300 KiTS (1;1)
- 1000 AbdomenCT-1K (4;0)
- 140 CT-ORG (4;0)
- 40 CHAOS (4;0)
- 947 MSD (7;4)
- 50 BTCV (13;0)
- 500 AMOS (15;0)
- 150 WORD (16;0)



- 100 3D-IRCADb (13;0)
- 1024 TotalSegmentator (104;0)
- 5038 JHH (21;0)



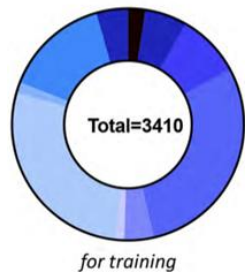
Zero-shot /Adaptation Oriented (3D Data)

CLIP-Driven

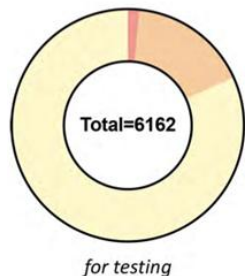
How to pre-train? CLIP-Driven

SuPreM

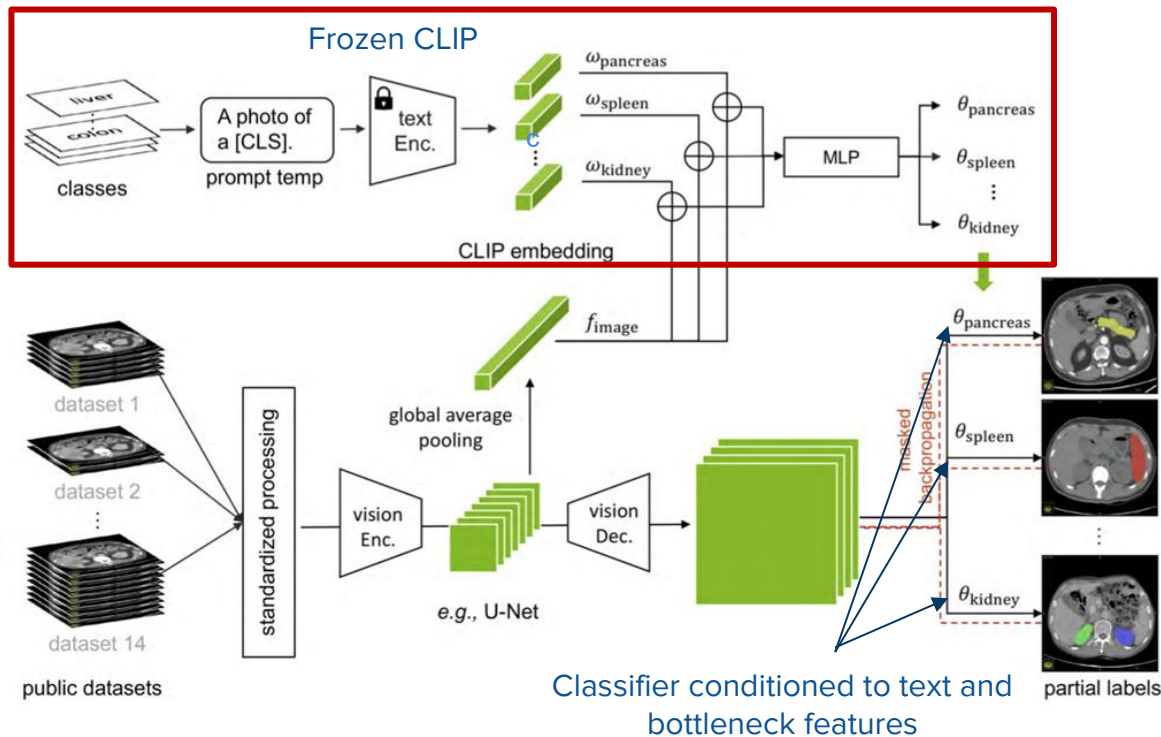
Main idea



- 82 Pancreas-CT (1;0)
- 201 LiTS (1;1)
- 300 KiTS (1;1)
- 1000 AbdomenCT-1K (4;0)
- 140 CT-ORG (4;0)
- 40 CHAOS (4;0)
- 947 MSD (7;4)
- 50 BTCV (13;0)
- 500 AMOS (15;0)
- 150 WORD (16;0)



- 100 3D-IRCADb (13;0)
- 1024 TotalSegmentator (104;0)
- 5038 JHH (21;0)

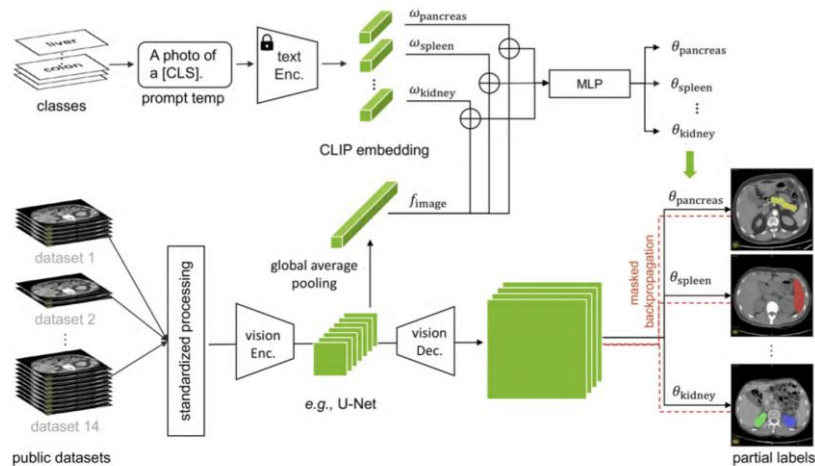


Zero-shot /Adaptation Oriented (3D Data)

CLIP-Driven

How to pre-train? CLIP-Driven

SuPreM



Zero-shot /Adaptation Oriented (3D Data)

CLIP-Driven

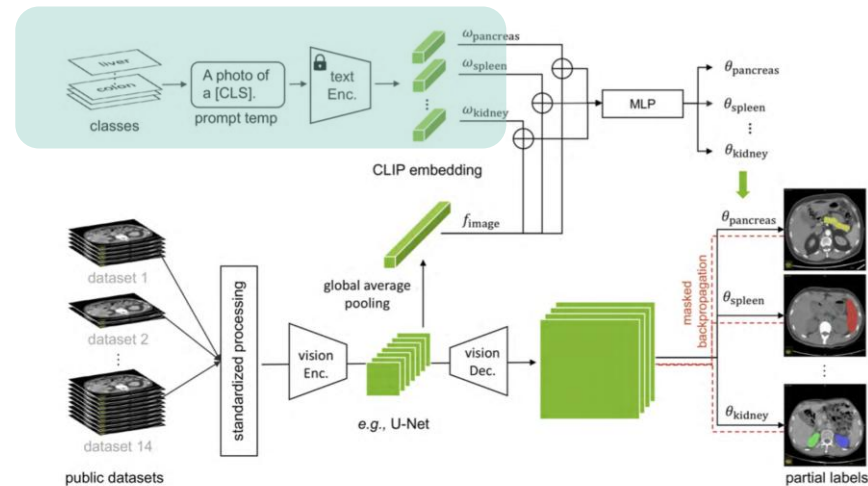
How to pre-train? CLIP-Driven

SuPreM

Text branch

(generates text embedding for class k)

$\mathbf{W}_k$



Zero-shot /Adaptation Oriented (3D Data)

CLIP-Driven

How to pre-train? CLIP-Driven

SuPreM

Text branch

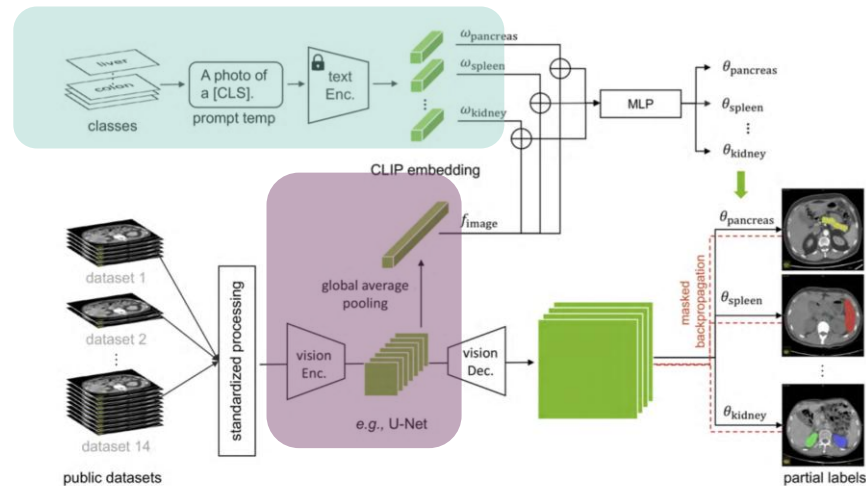
(generates text embedding for class k)

$\mathbf{w}_k$

Visual branch-encoder

(generates visual embedding for volume x)

$\mathbf{f}$



Zero-shot /Adaptation Oriented (3D Data)

CLIP-Driven

How to pre-train? CLIP-Driven

SuPreM

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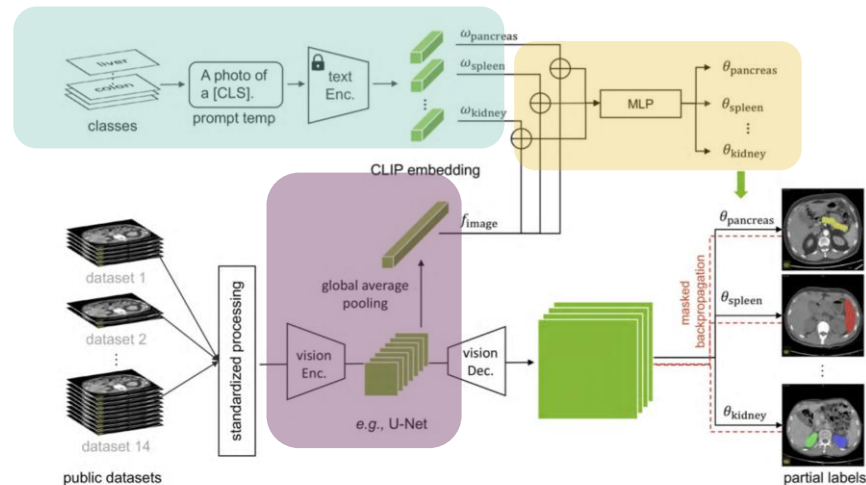
$\mathbf{f}$

Text-based controller MLP

(generates class parameters)

$$\theta_k = MLP(\mathbf{w}_k \oplus \mathbf{f})$$

$$\theta_k = \{\theta_{k_1}, \theta_{k_2}, \theta_{k_3}\}$$



Zero-shot /Adaptation Oriented (3D Data)

CLIP-Driven

SuPreM

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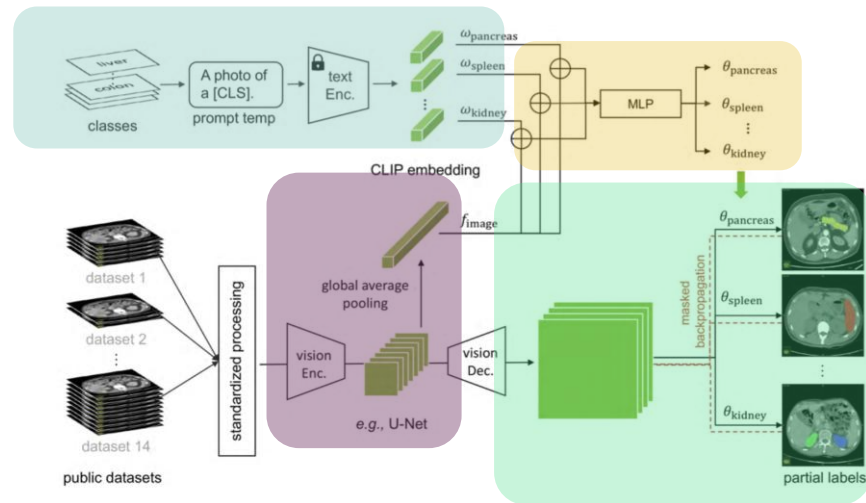
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$$\theta_k = \{\theta_{k_1}, \theta_{k_2}, \theta_{k_3}\}$$

Visual branch-decoder

(generates visual embedding for image x)

$$\mathbf{P}_k = \text{sigmoid}(((\mathbf{F} * \theta_{k_1}) * \theta_{k_2}) * \theta_{k_3})$$



Zero-shot /Adaptation Oriented (3D Data)

CLIP-Driven

SuPreM

How to pre-train? CLIP-Driven

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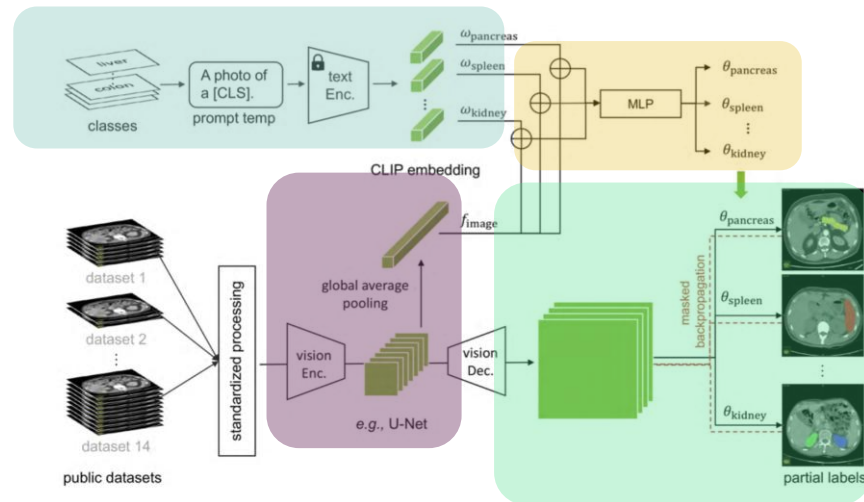
Visual branch-decoder

(generates visual embedding for image x)

Training loss

$$\mathcal{L} = \sum_{k=1}^K \mathbf{1}_{\{k \in y\}} \cdot \text{BCE}_k$$

$$\mathbf{P}_k = \text{sigmoid}(((\mathbf{F} * \theta_{k_1}) * \theta_{k_2}) * \theta_{k_3})$$



Zero-shot /Adaptation Oriented (3D Data)

CLIP-Driven

SuPreM

How to pre-train? CLIP-Driven

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Visual branch-decoder

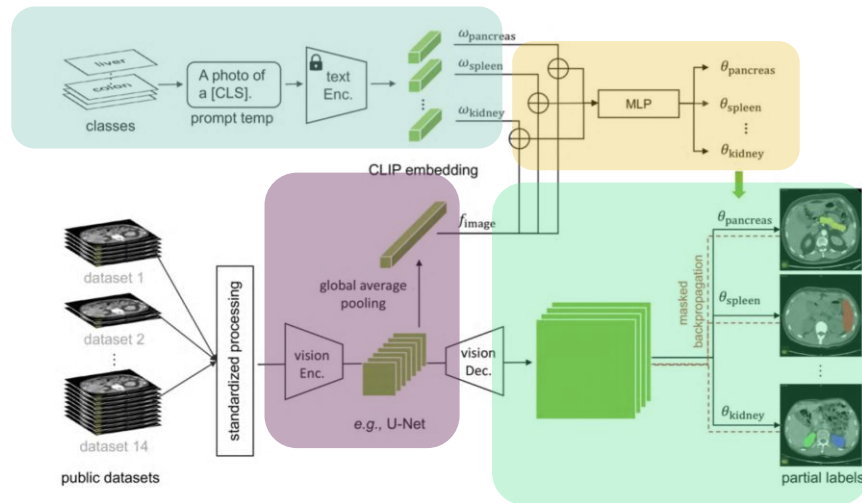
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Training loss

$$\mathcal{L} = \sum_{k=1}^K \mathbf{1}_{\{k \in y\}} \cdot \text{BCE}_k$$

→ How can the text part contribute if using a frozen generalist model?



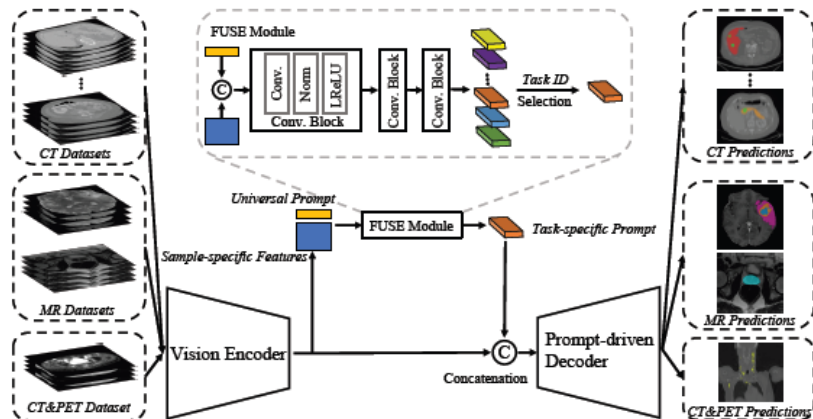
Zero-shot /Adaptation Oriented (3D Data)

UniSeg

Hermes

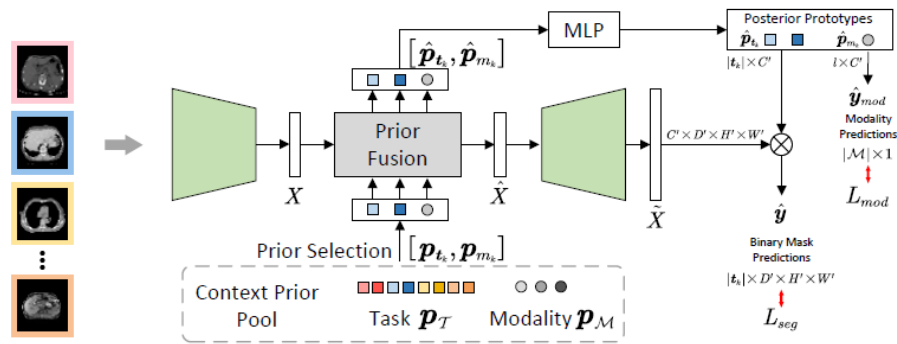
How to pre-train? Prompt-Driven

Main idea



Ye et al. UniSeg: A Prompt-driven Universal Segmentation Model as well as A Strong Representation Learner. MICCAI'23.

- **Objective:** condition the segmentation to high level features related to **tasks/domains**.
- **Prompt selection** is a learnable operations to operate during **inference**.



Gao et al. Training Like a Medical Resident: Context-Prior Learning Toward Universal Medical Image Segmentation. CVPR'24.

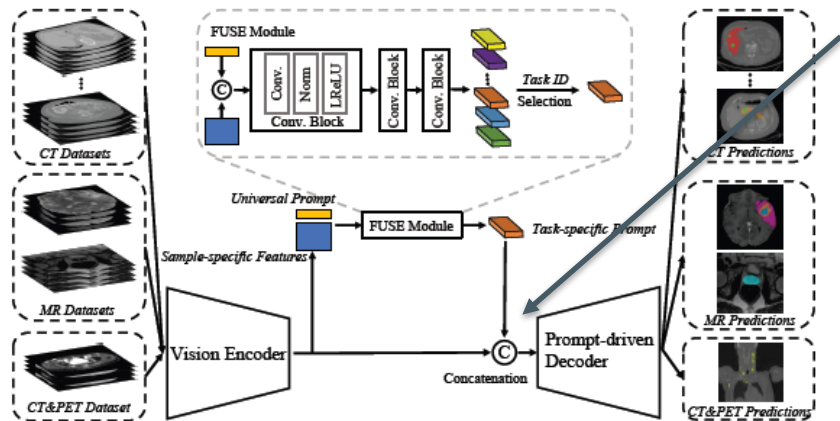
Zero-shot /Adaptation Oriented (3D Data)

UniSeg

Hermes

How to pre-train? Prompt-Driven

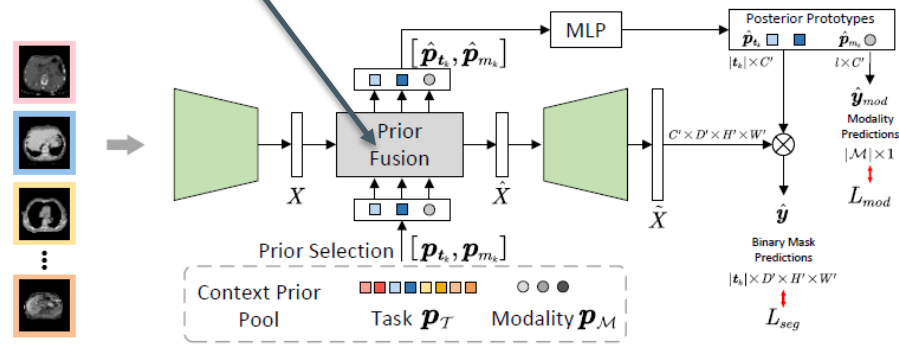
Main idea



Ye et al. UniSeg: A Prompt-driven Universal Segmentation Model as well as A Strong Representation Learner. MICCAI'23.

Conditioning on decoder path

Conditioning on classifier



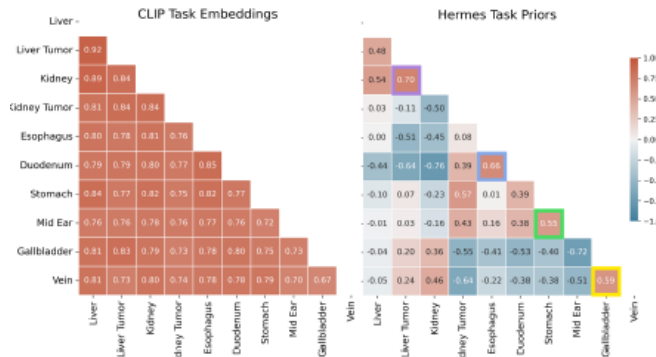
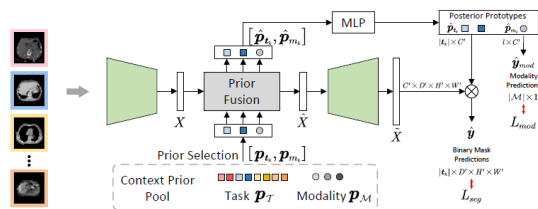
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Zero-shot /Adaptation Oriented (3D Data)

How to pre-train? Prompt-Driven

UniSeg

Hermes



Prompt Similarity among tasks

Setting	Model	1%		10%		50%		100%	
Scratch	ResUNet	Pan	Tumor	Pan	Tumor	Pan	Tumor	Pan	Tumor
		44.60	7.67	74.47	23.90	78.89	44.52	80.45	51.06
Transfer	ResUNet (AMOS CT)	56.08	8.31	77.15	25.53	80.53	46.16	81.23	52.21
	ResUNet (KiTS)	52.68	9.28	75.11	27.33	79.07	45.72	79.23	50.64
	DeSD [60] (10,594 CT)	67.82	13.89	78.11	35.82	80.95	50.23	81.97	59.11
	DoDNet [63]	66.62	11.97	76.83	31.92	80.82	47.79	81.41	53.62
	CLIP-Driven [44]	67.95	12.12	77.49	32.37	80.92	48.92	81.45	54.71
	UniSeg [61]	69.05	12.35	77.33	33.87	80.93	49.63	81.96	55.58
	Hermes-R	72.71	16.73	79.12	44.31	81.14	55.31	82.73	61.41

How to pretrain? Self-supervised pre-training

-
- | Method | Average DSC | Improvement (+) |
|--------------------|-------------|-----------------|
| mU-Net (dynamic) | ~69.3 | +2.98 |
| mU-Net (fixed) | ~70.3 | +1.97 |
| Volume Contrastive | ~69.3 | - |
| Volume Fusion | ~70.9 | - |
| Models Genesis | ~71.8 | - |
| Spark3D (ours) | ~72.3 | - |

3. Train a model to restore the original sub-volume (x_i')

Take the pre-trained **encoder** for target classification tasks
Take the pre-trained **encoder-decoder** for target segmentation tasks

The diagram illustrates the proposed framework, showing the data flow and architecture. At the top, a "Mix-up Unlabeled Data Pool" contains "Xrays" and "CTs". A "Sample" is drawn from this pool, consisting of a pair of images (x_1, x_2) and a label (T). The label T is a vector of size T , where T_1 and T_2 are the labels for x_1 and x_2 respectively. The images x_1 and x_2 are processed by a "Pyramid U-like Transformer" and an "EMA" (Exponential Moving Average) block. The output of the transformer is a vector of size T , which is then processed by a "Projector" to produce a vector of size T . The output of the EMA block is a vector of size T , which is then processed by a "Projector" to produce a vector of size T . The final output is a vector of size T , which is then processed by a "Projector" to produce a vector of size T . The diagram also shows a "Stage i: Transformer Block" and a "Transformer Layer" with various components like "Switchable Patch Embed (SPE)", "3D 3D Patch Embed", "2D 2D Patch Embed", "Norm", "Spatial Reduction", "MSA", "FFN", and "xh". A legend on the right defines the symbols used in the diagram.

- T : Data Augmentation
- Patch token
- SSL token
- Position Embed
- Element-wise Sum
- FFN: Feed-Forward Network
- MSA: Multi-head Self-attention

The diagram illustrates the Swin Transformer Encoder architecture for self-supervised learning. It starts with an 'Input CT' (Computed Tomography scan) which is processed into 'Sub-Volumes' (x_i and x_j). These sub-volumes are then processed by a 'Patch Partition' block, which outputs 'Coutout = Rot'. The output is then fed into a 'Swin Transformer Encoder'. The encoder's output is used for three self-supervised heads: $\mathcal{L}_{inpaint}$ (Inpainting), $\mathcal{L}_{contrast}$ (Contrastive), and $\mathcal{L}_{rot}$ (Rotation). The 'L_inpaint' and 'L_rot' heads are shown as separate blocks, while 'L_contrast' is shown as a dashed box containing the 'Inpainting' and 'Rotation' heads.

88

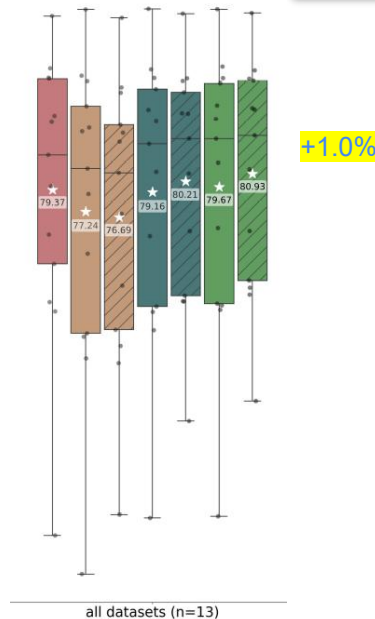
Zero-shot /Adaptation Oriented (3D Data)

Benefits of supervised foundation models?

- × **Transferability via full fine-tuning of the pre-trained model.**
- × **Access to hundreds of labeled volumes for adaptation.**
- × **Does not leverage its knowledge on known categories.**

	name	backbone	params	pre-trained data	performance [†]
self-supervised	Models Genesis (Zhou et al., 2019)	U-Net	19.08M	623 CT volumes	90.1
	UniMISS (Xie et al., 2022)	nnU-Net	61.79M	5,022 CT&MRI volumes	92.9
	NV*	Swin UNETR	62.19M	1,000 CT volumes	93.2
	NV*	Swin UNETR	62.19M	3,000 CT volumes	93.4
	NV (Tang et al., 2022)	Swin UNETR	62.19M	5,050 CT volumes	93.8
	NV*	Swin UNETR	62.19M	5,050 CT volumes	94.2
supervised	NV*	Swin UNETR	62.19M	9,262 CT volumes	94.3
	Med3D (Chen et al., 2019b)	Residual U-Net	85.75M	1,638 CT volumes	91.4
	DoDNet (Zhang et al., 2021)	U-Net	17.29M	920 CT volumes	93.8
	DoDNet*	U-Net	17.29M	920 CT volumes	94.4
	Universal Model (Liu et al., 2023b)	U-Net	19.08M	2,100 CT volumes	-
	Universal Model (Liu et al., 2023b)	Swin UNETR	62.19M	2,100 CT volumes	94.1
	SuPreM*	U-Net	19.08M	2,100 CT volumes	95.4
	SuPreM*	Swin UNETR	62.19M	2,100 CT volumes	94.6
	SuPreM*	SegResNet	470.13M	2,100 CT volumes	94.0

+0.8%



SuPreM

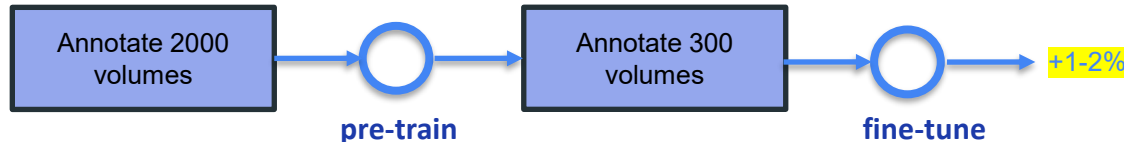
MultiTalent

Ulrich et al. MultiTalent: A Multi-Dataset Approach to Medical Image Segmentation. MICCAI'23.

Zero-shot /Adaptation Oriented (3D Data)

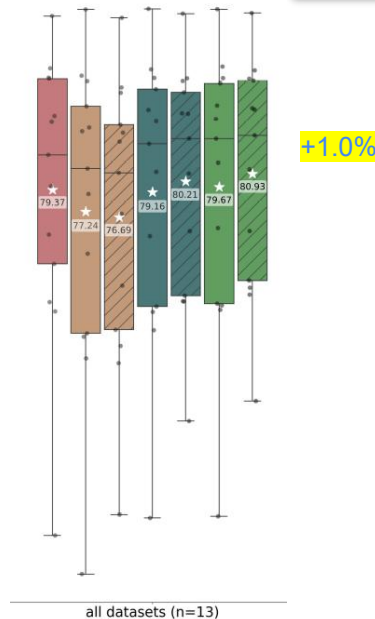
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Ulrich et al. MultiTalent: A Multi-Dataset Approach to Medical Image Segmentation. MICCAI'23.

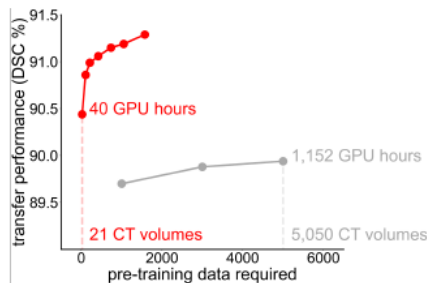
Zero-shot /Adaptation Oriented (3D Data)

SuPreM

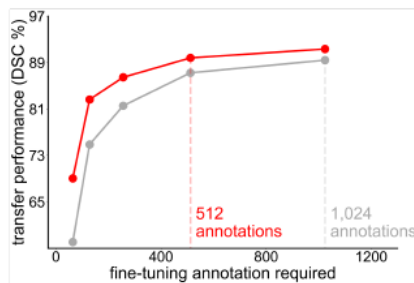
Benefits of supervised foundation models

→ SuPreM models are pre-trained on a curated dataset with 25 fully-annotated structures.

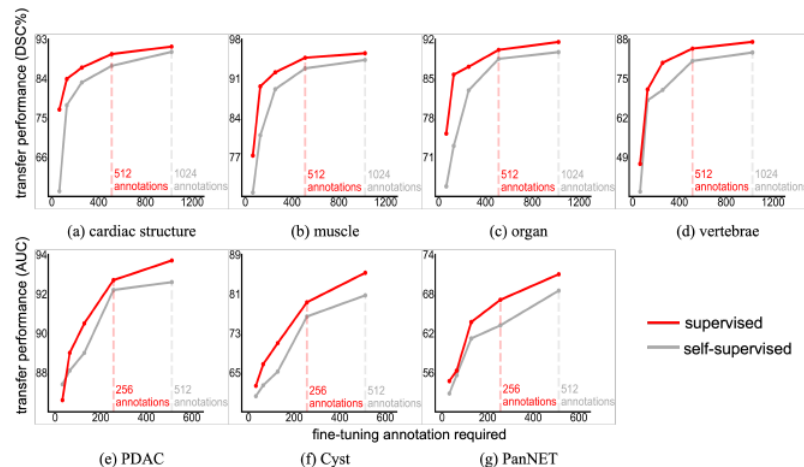
- ✓ **Supervised pre-training is orders of magnitude more data-efficient than self-supervision.**
- ✓ **This holds even when transferring to unseen structures.**



(a) data & computational efficiency in *pre-training*



(b) annotation & learning efficiency in *fine-tuning*

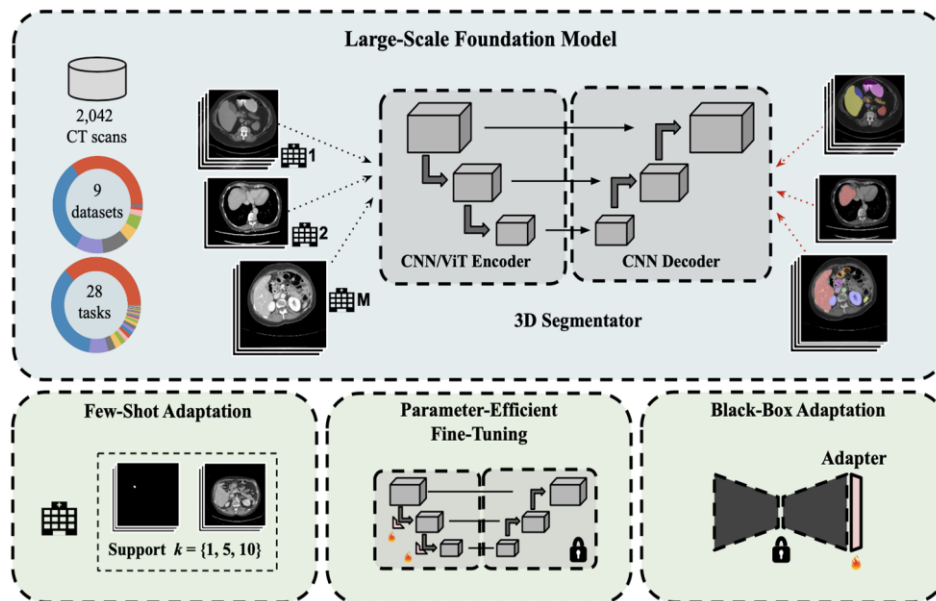


Zero-shot /Adaptation Oriented (3D Data)

FSEFT

Few-Shot Efficient Fine-Tuning

Main idea (how to adapt a pre-trained large-scale model efficiently)

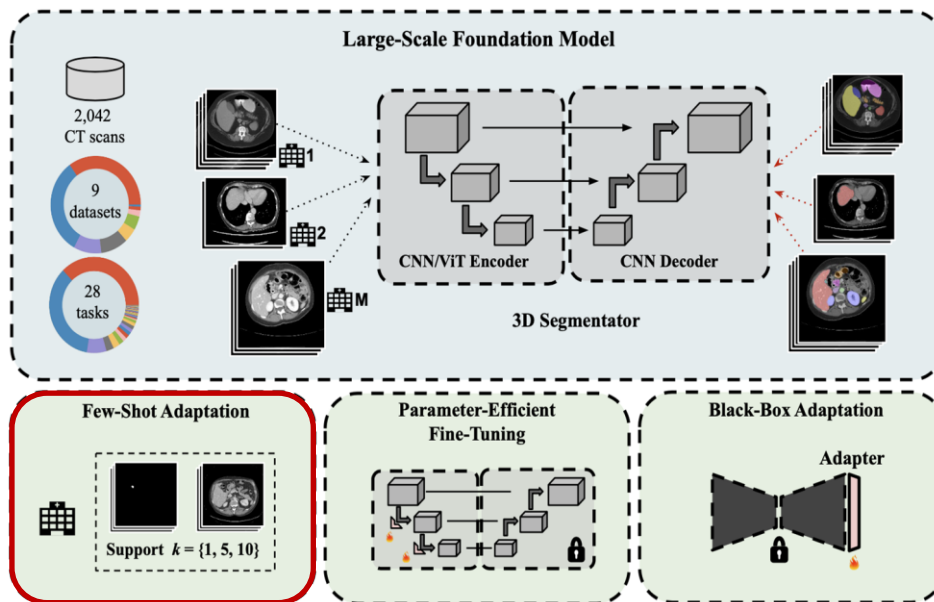


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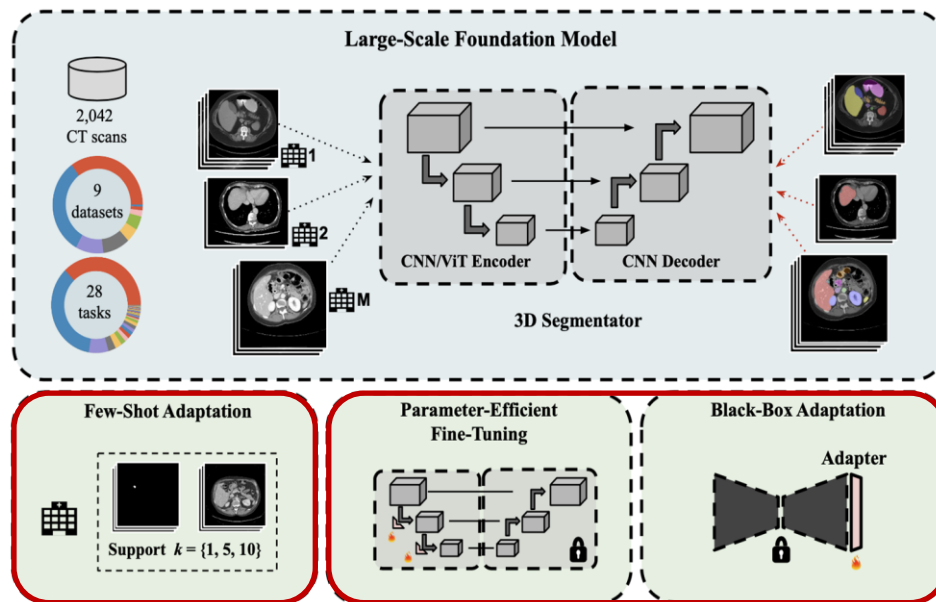
Presence of few annotated volumes for adaptation

Zero-shot /Adaptation Oriented (3D Data)

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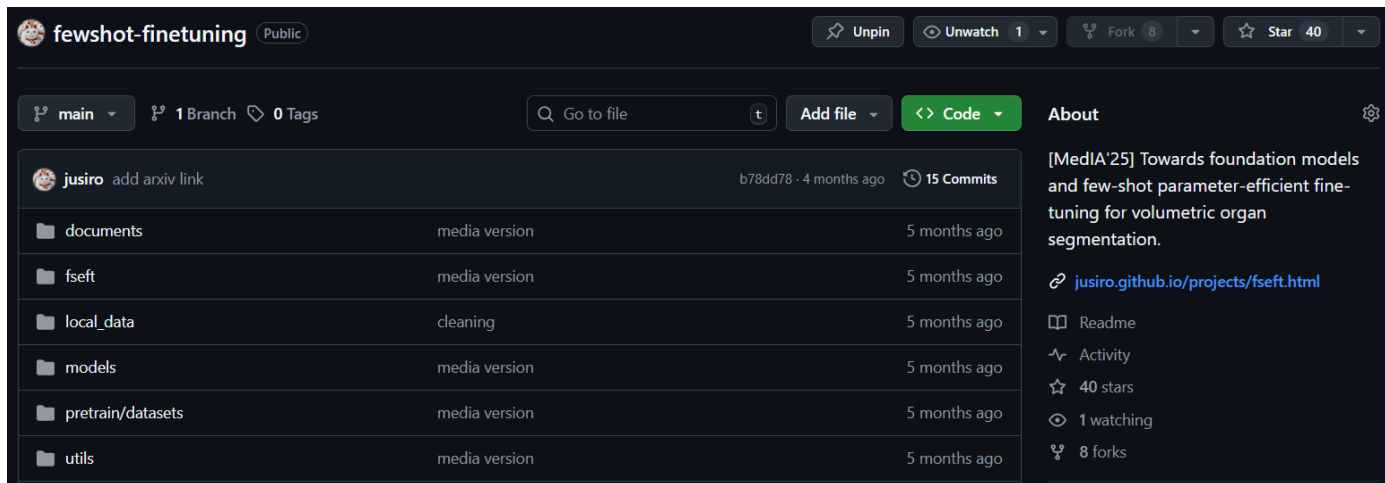


Presence of few annotated volumes for adaptation

Being computationally efficient, allowing for commodity GPUs

Adaptation code and model weights publicly available

<https://github.com/jusiro/fewshot-finetuning>



The screenshot shows the GitHub repository page for 'fewshot-finetuning'. The repository is public and has 40 stars, 8 forks, and 1 watch. The main branch is 'main'. The repository description is '[Media'25] Towards foundation models and few-shot parameter-efficient fine-tuning for volumetric organ segmentation.' The repository contains several folders: 'documents', 'fseft', 'local_data', 'models', 'pretrain/datasets', and 'utils'. The 'documents' folder is highlighted. The repository was created by 'jusiro' and has 15 commits. The repository is linked to a project page: jusiro.github.io/projects/fseft.html. The repository also has a README, activity, and 8 forks.

File/Folder	Version	Time
documents	media version	5 months ago
fseft	media version	5 months ago
local_data	cleaning	5 months ago
models	media version	5 months ago
pretrain/datasets	media version	5 months ago
utils	media version	5 months ago

Zero-shot /Adaptation Oriented (3D Data)

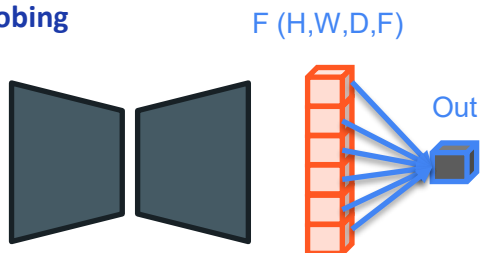
Few-Shot Efficient Fine-Tuning

FSEFT

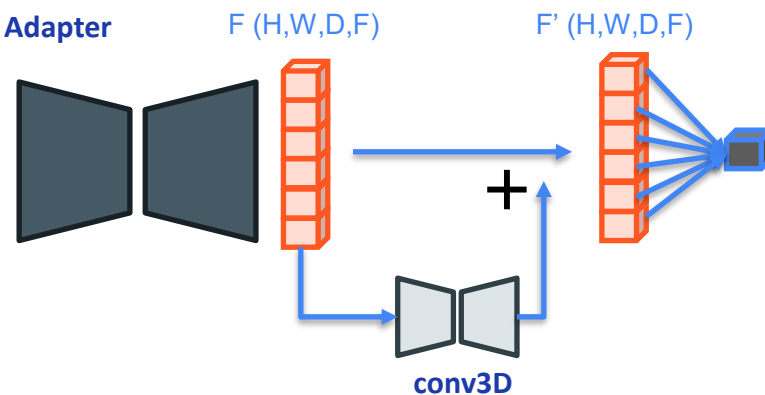


Black-box Adapters

Linear Probing



Spatial Adapter



Zero-shot /Adaptation Oriented (3D Data)

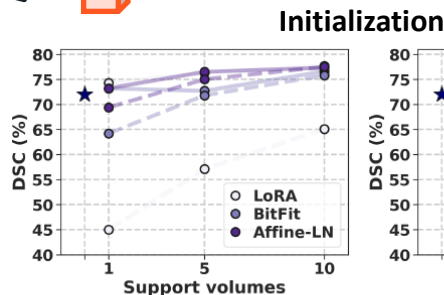
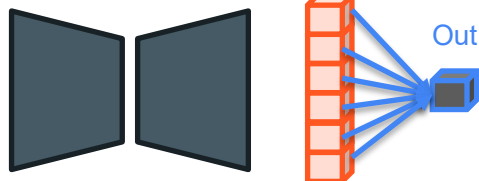
FSEFT

Few-Shot Efficient Fine-Tuning

Black-box Adapters

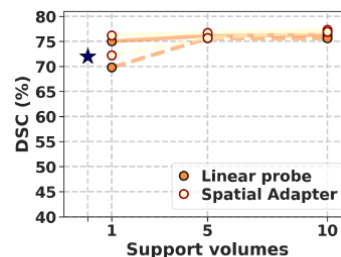
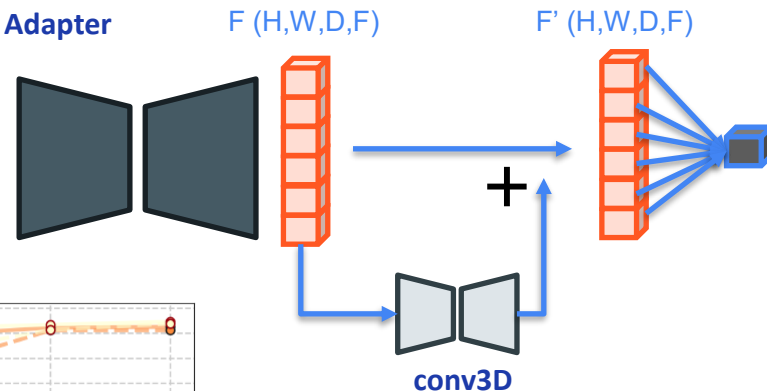


Linear Probing



(a) PEFT

Spatial Adapter



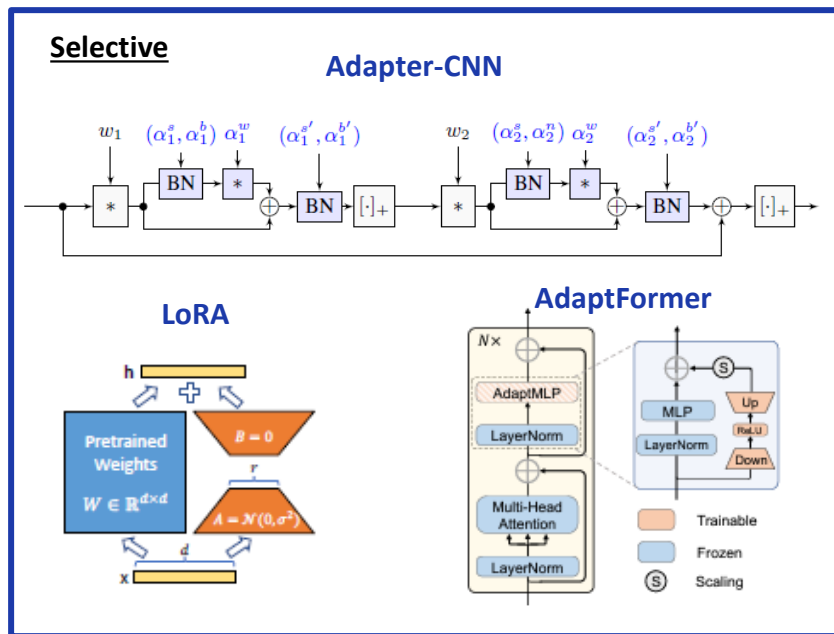
(b) Black-box

Zero-shot /Adaptation Oriented (3D Data)

FSEFT

Few-Shot Efficient Fine-Tuning

Parameter-Efficient Fine-Tuning (for the Encoder)



Zero-shot /Adaptation Oriented (3D Data)

FSEFT

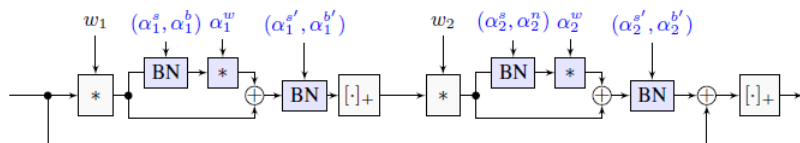
Few-Shot Efficient Fine-Tuning

Parameter-Efficient Fine-Tuning (for the Encoder)

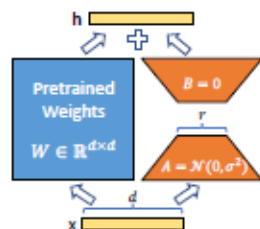


Selective

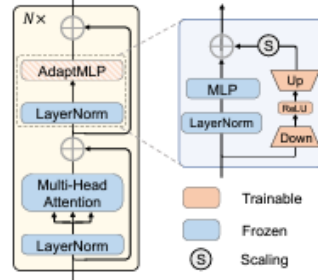
Adapter-CNN



LoRA



AdaptFormer



Additive

Affine-BN/LN

$$y = \frac{x - \mathbb{E}[x]}{\sqrt{\text{Var}[x] + \epsilon}} * \gamma + \beta$$

BitFit (only-bias)

Zero-shot /Adaptation Oriented (3D Data)

FSEFT

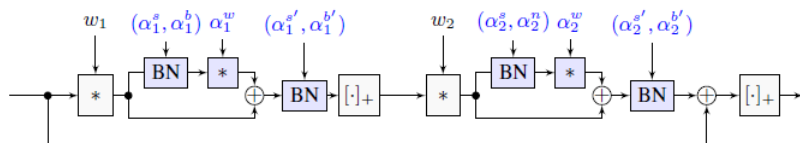
Few-Shot Efficient Fine-Tuning



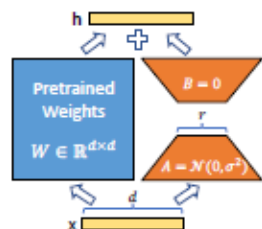
Parameter-Efficient Fine-Tuning (for the Encoder)

Selective

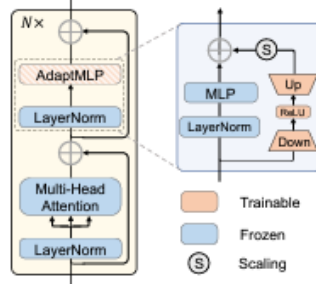
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$$y = \frac{x - \mathbb{E}[x]}{\sqrt{\text{Var}[x] + \epsilon}} * \gamma + \beta$$

BitFit (only-bias)

What to do with the Decoder?

(millions of parameters)

→ **Base** categories: frozen.

→ **New** categories: fine-tuned.

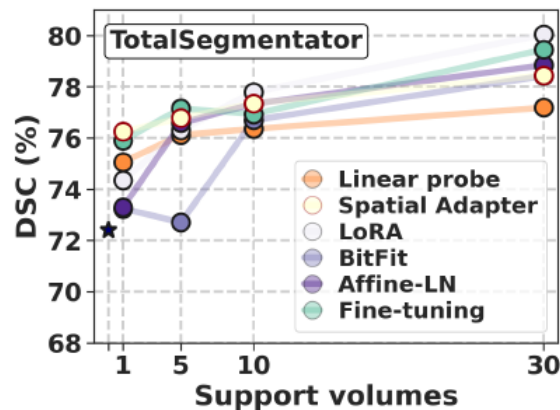


Zero-shot /Adaptation Oriented (3D Data)

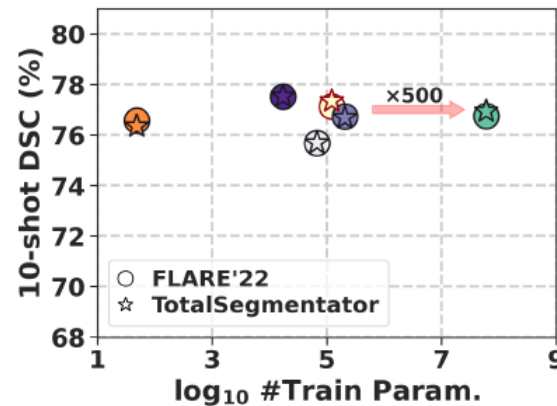
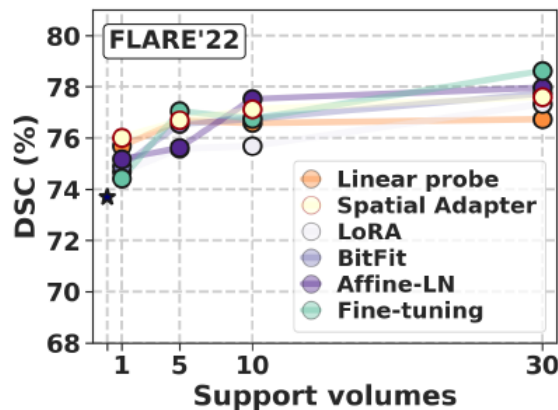
Few-Shot Efficient Fine-Tuning

Transferability to known tasks (domain shift)

FSEFT



(a) Data-efficient adaptation



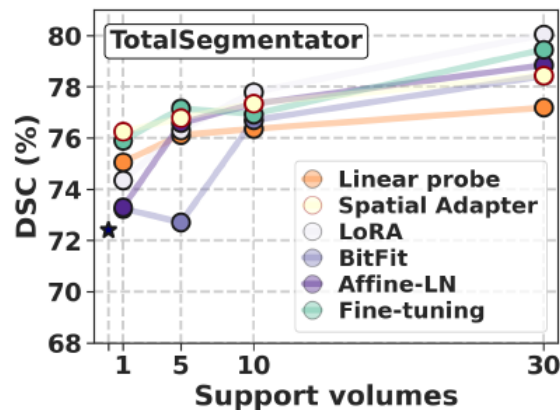
(b) Parameter efficiency

Zero-shot /Adaptation Oriented (3D Data)

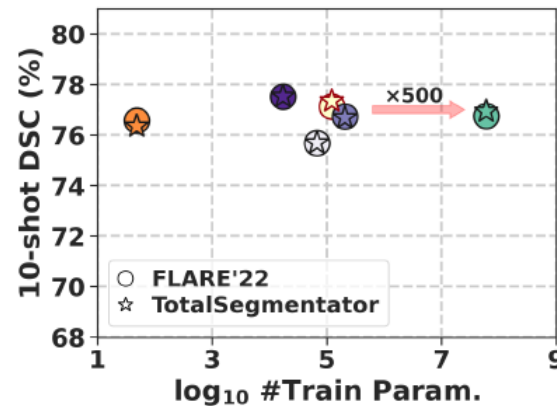
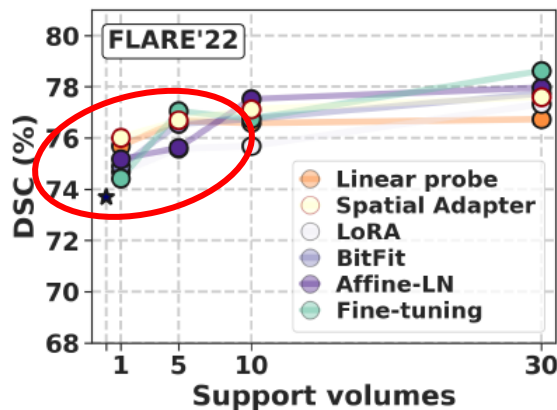
Few-Shot Efficient Fine-Tuning

Transferability to known tasks (domain shift)

FSEFT



(a) Data-efficient adaptation



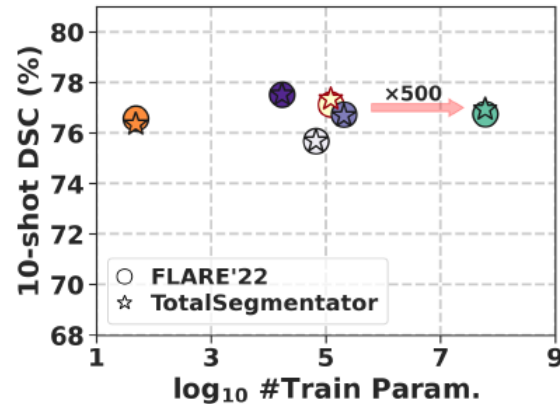
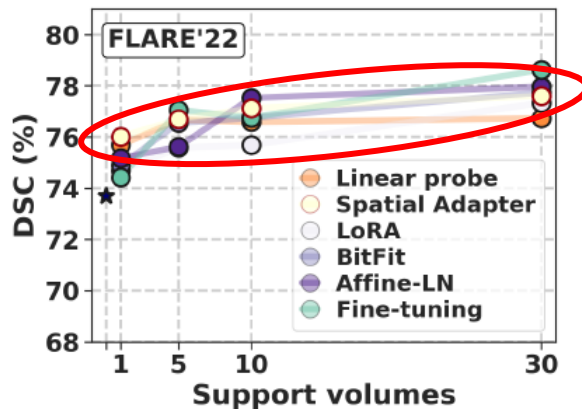
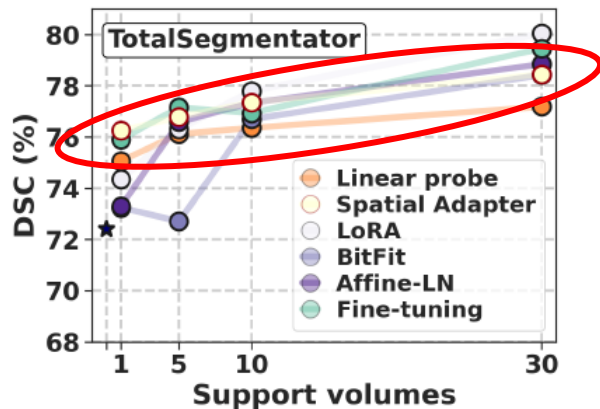
Fine-tuning is not always the best but interestingly is competitive.

Zero-shot /Adaptation Oriented (3D Data)

Few-Shot Efficient Fine-Tuning

Transferability to known tasks (domain shift)

FSEFT



(a) Data-efficient adaptation

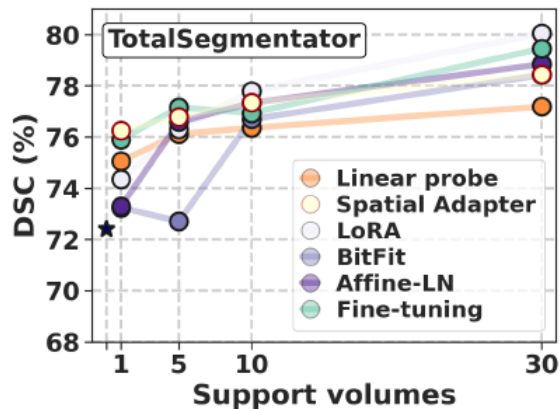
Black-box methods are competitive in the very low-shot regime.

Zero-shot /Adaptation Oriented (3D Data)

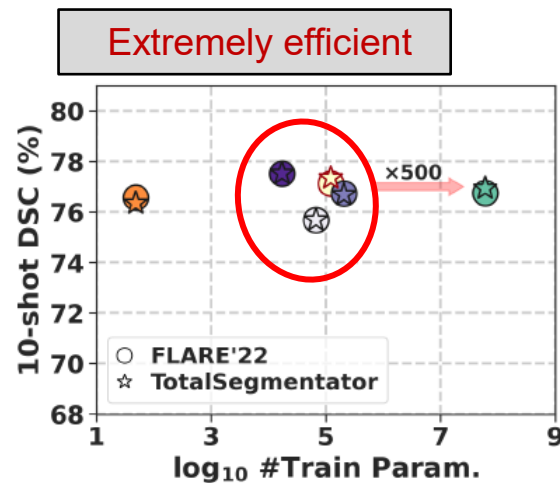
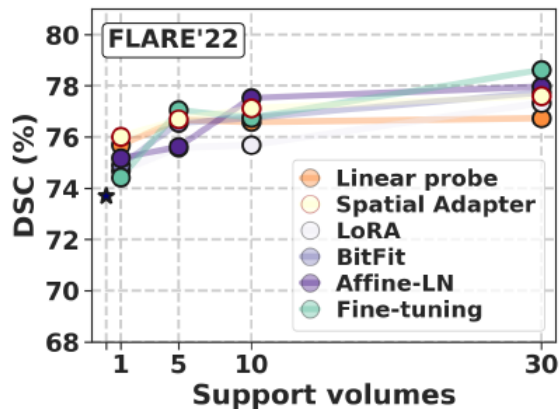
Few-Shot Efficient Fine-Tuning

Transferability to known tasks (domain shift)

FSEFT



(a) Data-efficient adaptation



(b) Parameter efficiency

Zero-shot /Adaptation Oriented (3D Data)

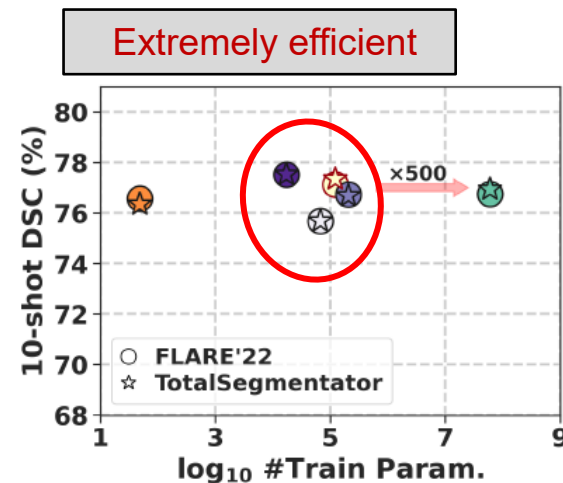
Few-Shot Efficient Fine-Tuning

Transferability to known tasks (domain shift)

FSEFT



Method	Category	TotalSegmentator		FLARE'22	
		#Param.	T(min)	#Param.	T(min)
Fine-tuning (Tang et al., 2022)	FULL	62.1M	15	62.1M	50
Fine-tuning (<i>Ours</i>)		62.1M	8	62.1M	35
Decoder	PEFT	19.6M	7	19.6M	32
Bitfit (Ben-Zaken et al., 2021)		210.7K	5	211.1K	29
LoRA (Hu et al., 2022)		68.1K	6	69.4K	25
AdaptFormer (Chen et al., 2022a)		47.6K	7	48.1K	24
Affine-LN (Basu et al., 2024)		17.3K	5	17.7K	25
Linear probe	BB	49	4	490	7
Spatial Adapter		124.4K	5	124.9K	11



(b) Parameter efficiency

Zero-shot /Adaptation Oriented (3D Data)

FSEFT

Few-Shot Efficient Fine-Tuning



Transferability to known tasks (domain shift)

Setting	Method	Spl	lKid	Gall	Eso	Liv	Pan	Sto	Duo	Aor	Avg.
5-shot	PEFT	CNN-Adapter (Rebuffi et al., 2018)	47.69	39.58	40.52	53.05	55.08	43.17	28.47	35.73	47.55
		Bias (Cai et al., 2020)	71.16	69.54	70.16	55.86	71.03	79.60	51.25	69.04	69.62
	BB	Affine-BN (Frankle et al., 2021)	69.22	72.33	65.66	52.68	67.61	75.50	45.08	66.52	66.84
		Linear probe	93.91	75.59	75.94	50.50	80.29	68.19	57.18	77.18	88.48
		Spatial Adapter	91.78	77.71	80.89	52.30	90.00	78.83	83.27	80.37	89.08
10-shot	PEFT	CNN-Adapter (Rebuffi et al., 2018)	57.32	61.79	42.96	55.61	52.21	52.77	39.96	34.97	54.09
		Bias (Cai et al., 2020)	72.79	76.14	83.37	59.65	73.97	79.68	60.65	73.46	74.72
	BB	Affine-BN (Frankle et al., 2021)	72.15	74.06	77.15	58.65	72.31	77.08	61.74	63.94	92.43
		Linear probe	91.22	75.63	77.48	50.02	80.87	69.17	56.28	77.63	85.29
		Spatial Adapter	95.40	83.76	81.29	52.49	90.75	78.57	81.97	81.09	90.33

(a) 3D-UNet

Setting	Method	Spl	lKid	Gall	Eso	Liv	Pan	Sto	Duo	Aor	Avg.
5-shot	PEFT	BitFit (Ben-Zaken et al., 2021)	88.76	85.91	79.42	50.22	92.17	73.64	62.81	69.30	77.01
		LoRA (Hu et al., 2022)	61.31	46.52	52.50	46.43	80.50	66.86	38.66	54.15	57.81
	BB	AdaptFormer (Chen et al., 2022a)	87.57	86.05	60.17	51.79	90.11	76.73	68.29	74.49	93.12
		Affine-LN (Basu et al., 2024)	88.14	83.81	76.10	50.04	91.89	75.46	64.41	71.91	90.91
		Linear probe	94.62	91.86	82.98	49.29	93.54	78.86	72.43	77.30	88.77
10-shot	PEFT	Spatial Adapter	95.34	88.13	85.08	55.56	94.27	78.84	75.33	78.17	87.40
		BitFit (Ben-Zaken et al., 2021)	95.16	86.54	84.86	56.93	93.58	72.03	69.26	75.47	90.44
	BB	LoRA (Hu et al., 2022)	63.97	54.53	59.25	55.33	84.03	77.72	58.72	73.89	80.59
		AdaptFormer (Chen et al., 2022a)	91.36	84.03	77.78	54.10	93.14	76.05	70.08	77.58	93.25
		Affine-LN (Basu et al., 2024)	87.21	87.36	80.84	55.80	93.65	76.98	66.78	75.66	92.50
10-shot	BB	Linear probe	95.26	91.63	82.15	52.69	93.37	69.93	71.70	77.20	88.70
		Spatial Adapter	95.83	89.44	81.61	56.24	94.40	77.69	76.03	79.54	84.66

(b) Swin-UNETR

Black-box methods hold their performance when directly applied to SuPreM models and 3D CNNs.

Zero-shot /Adaptation Oriented (3D Data)

FSEFT

Few-Shot Efficient Fine-Tuning

Transferability to novel tasks (new organs)



Setting	Method	Lung*	Heart [†]	Gluteus [‡]	Avg.
FULL	Fine-tuning (Tang et al. 2022)	19.59	53.14	55.37	42.70
	Fine-tuning (<i>Ours</i>)	31.01	60.79	65.35	52.38
	BitFit (Ben-Zaken et al. 2021)	14.79	48.90	39.43	34.28
	LoRA (Hu et al. 2022)	13.80	50.55	46.36	38.49
PEFT	AdaptFormer (Chen et al. 2022a)	18.82	53.35	48.61	40.26
	Affine-LN (Basu et al. 2024)	16.92	58.38	46.07	40.46
	Decoder fine-tuning	25.98	65.69	64.23	51.97
	+BitFit (Ben-Zaken et al. 2021)	26.17	65.78	64.34	52.10
	+LoRA (Hu et al. 2022)	26.16	76.12	69.89	57.39
	+AdaptFormer (Chen et al. 2022a)	23.84	72.32	69.79	55.32
	+Affine-LN (Basu et al. 2024)	26.09	65.91	64.53	52.18
BB	Linear Probe	9.35	9.19	7.52	8.68
	Spatial Adapter	10.08	14.66	12.75	12.50

* Avg. of five: upper/lower lobe left, upper/lower lobe right, middle lobe.

[†] Avg. of five: myocardium, atrium/ventricle left, atrium/ventricle right.

[‡] Avg. of six: maximus left/right, medius left/right, minimus left/right.

Black-box methods are not competitive.

Zero-shot /Adaptation Oriented (3D Data)

FSEFT

Few-Shot Efficient Fine-Tuning

Transferability to novel tasks (new organs)



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	LoRA (Hu et al. 2022)	13.80	50.55	46.36	38.49
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	Affine-LN (Basu et al. 2024)	16.92	58.38	46.07	40.46
	Decoder fine-tuning	25.98	65.69	64.23	51.97
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	+LoRA (Hu et al. 2022)	26.16	76.12	69.89	57.39
	+AdaptFormer (Chen et al. 2022a)	23.84	72.32	69.79	55.32
BB	+Affine-LN (Basu et al. 2024)	26.09	65.91	64.53	52.18
	Linear Probe	9.35	9.19	7.52	8.68
	Spatial Adapter	10.08	14.66	12.75	12.50

Additive PEFT outperform
Selective methods

* Avg. of five: upper/lower lobe left, upper/lower lobe right, middle lobe.

† Avg. of five: myocardium, atrium/ventricle left, atrium/ventricle right.

‡ Avg. of six: maximus left/right, medius left/right, minimus left/right.

Zero-shot /Adaptation Oriented (3D Data)

FSEFT

Few-Shot Efficient Fine-Tuning

Transferability to novel tasks (new organs)

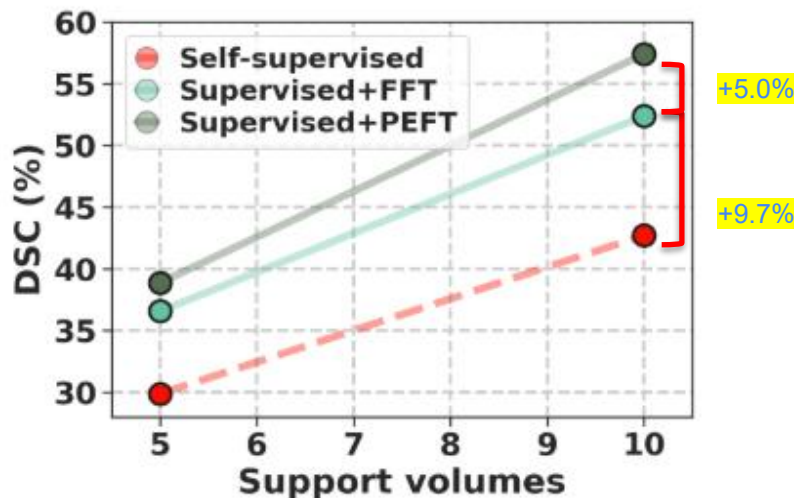


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	LoRA (Hu et al. 2022)	13.80	50.55	46.36	38.49
PEFT	AdaptFormer (Chen et al. 2022a)	18.82	53.35	48.61	40.26
	Affine-LN (Basu et al. 2024)	16.92	58.38	46.07	40.46
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	Spatial Adapter	10.08	14.66	12.75	12.50

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‡ Avg. of six: maximus left/right, medius left/right, minimus left/right.



Zero-shot /Adaptation Oriented (3D Data)

ARENA

Few-Shot Efficient Fine-Tuning

Challenges of PEFT in low-shot regimes

Method	Natural								Specialized						Structured										Overall Mean	Tunable Params
	CIFAR-100	Caltech101	DTD	Flowers102	Pets	SVHN	Sun397	Mean	Camelyon	EuroSAT	Resisc45	Retinopathy	Mean	Clevr-Count	Clevr-Dist	DMLab	KITTI-Dist	dSpr-Loc	dSpr-Ori	sNORB-Azim	sNORB-Elev	Mean				
Linear	78.1	86.6	65.7	98.9	89.3	41.5	53.2	72.5	83.1	90.0	74.9	74.6	80.6	37.5	35.1	36.5	64.6	16.2	29.4	17.3	23.7	32.5	61.9	0		
Full	62.4	89.9	61.9	97.4	85.8	88.9	36.8	76.7	81.6	88.1	81.6	73.6	81.2	56.2	60.9	48.2	77.9	68.5	46.6	31.0	28.3	52.2	70.0	85.8		
VPT-Shallow	80.2	88.7	67.9	99.1	89.6	77.0	54.2	79.4	81.8	90.3	77.2	74.4	80.9	42.2	52.4	38	66.5	52.4	43.1	15.2	23.2	41.6	67.3	0.07		
VPT-Deep	84.8	91.5	69.4	99.1	91.0	85.6	54.7	81.8	86.4	94.9	84.2	73.9	84.9	79.3	62.4	48.5	77.9	80.3	56.4	33.2	43.8	60.2	75.6	0.43		
BitFit	86.5	90.5	70.3	98.9	91.0	91.2	54.2	82.6	86.7	95.0	85.3	75.5	85.6	77.2	63.2	51.2	79.2	78.6	53.9	30.1	34.7	58.5	75.6	0.1		
DiffFit	86.3	90.2	71.2	99.2	91.7	91.2	56.1	83.2	85.8	94.1	80.9	75.2	84.0	80.1	63.4	50.9	81.0	77.8	52.8	30.7	35.5	59.0	75.4	0.14		
LayerNorm	86.0	89.7	72.2	99.1	91.4	90.0	56.1	83.0	84.7	93.8	83.0	75.2	84.2	77.5	62.2	49.9	78.1	78.0	52.1	24.3	34.4	57.1	74.7	0.04		
SSF	86.6	89.8	68.8	99.1	91.4	91.2	56.5	82.8	86.1	94.5	83.2	74.8	84.7	80.1	63.6	53.0	81.4	85.6	52.1	31.9	37.2	60.6	76.0	0.21		
Pfeif. Adapter	86.3	91.5	72.1	99.2	91.4	88.5	55.7	83.0	86.2	95.5	85.3	76.2	85.8	83.1	65.2	51.4	80.2	83.3	56.6	33.8	41.1	61.8	76.9	0.67		
Houl. Adapter	84.3	92.1	72.3	98	91.7	90.0	55.4	83.2	88.7	95.3	86.5	75.2	86.4	82.9	63.6	53.8	79.6	84.4	54.3	34.2	44.3	62.1	77.2	0.77		
AdaptFormer	85.8	91.8	70.5	99.2	91.8	89.4	56.7	83.2	86.8	95.0	86.5	76.3	86.2	82.9	64.1	52.8	80.0	84.7	53.0	33.0	41.4	61.5	76.9	0.46		
RepAdapter	86.0	92.5	69.1	99.1	90.9	90.9	55.4	82.9	86.9	95.3	86.0	75.4	85.9	82.5	63.5	51.4	80.2	85.4	52.1	35.7	41.7	61.6	76.8	0.53		
Convpass	85.0	92.1	72.0	99.3	91.3	90.8	55.9	83.5	87.7	95.8	85.9	75.9	86.3	82.3	65.2	53.8	78.1	86.5	55.3	38.6	45.1	63.1	77.6	0.49		
LoRA	85.7	92.6	69.8	99.1	90.5	88.5	55.5	82.6	87.5	94.9	85.9	75.7	86.0	82.9	63.9	51.8	79.9	86.6	47.2	33.4	42.5	61.0	76.5	0.55		
FacT_TT	85.8	91.8	71.5	99.3	91.1	90.8	55.9	83.4	87.7	94.9	85.0	75.6	85.8	83.0	64.0	49.0	79.3	85.8	53.1	32.8	43.7	61.3	76.8	0.13		
FacT_TK	86.2	92.5	71.8	99.1	90.1	91.2	56.5	83.4	85.8	95.5	86.0	75.7	85.8	82.7	65.1	51.5	78.9	86.7	53.1	27.8	40.8	60.8	76.6	0.23		
Relative Std Dev	0.81	1.13	1.78	0.34	0.54	1.82	1.24	0.54	1.20	0.59	1.95	0.83	0.94	2.67	1.50	3.22	1.37	4.11	4.46	11.02	9.30	2.70	1.09	-		

Zero-shot /Adaptation Oriented (3D Data)

ARENA

Few-Shot Efficient Fine-Tuning

Challenges of PEFT in low-shot regimes

Method	Natural								Specialized					Structured										Overall Mean	Tunable Params
	CIFAR-100	Caltech101	DTD	Flowers102	Pets	SVHN	Sun397	Mean	Camelyon	EuroSAT	Resisc45	Retinopathy	Mean	Clevr-Count	Clevr-Dist	DMLab	KITTI-Dist	dSpr-Loc	dSpr-Ori	sNORB-Azim	sNORB-Elev	Mean			
Linear	78.1	86.6	65.7	98.9	89.3	41.5	53.2	72.5	83.1	90.0	74.9	74.6	80.6	37.5	35.1	36.5	64.6	16.2	29.4	17.3	23.7	32.5	61.9	0	
Full	62.4	89.9	61.9	97.4	85.8	88.9	36.8	76.7	81.6	88.1	81.6	73.6	81.2	56.2	60.9	48.2	77.9	68.5	46.6	31.0	28.3	52.2	70.0	85.8	
VPT-Shallow	80.2	88.7	67.9	99.1	89.6	77.0	54.2	79.4	81.8	90.3	77.2	74.4	80.9	42.2	52.4	38	66.5	52.4	43.1	15.2	23.2	41.6	67.3	0.07	
VPT-Deep	84.8	91.5	69.4	99.1	91.0	85.6	54.7	81.8	86.4	94.9	84.2	73.9	84.9	79.3	62.4	48.5	77.9	80.3	56.4	33.2	43.8	60.2	75.6	0.43	
BitFit	86.5	90.5	70.3	98.9	91.0	91.2	54.2	82.6	86.7	95.0	85.3	75.5	85.6	77.2	63.2	51.2	79.2	78.6	53.9	30.1	34.7	58.5	75.6	0.1	
DiffFit	86.3	90.2	71.2	99.2	91.7	91.2	56.1	83.2	85.8	94.1	80.9	75.2	84.0	80.1	63.4	50.9	81.0	77.8	52.8	30.7	35.5	59.0	75.4	0.14	
LayerNorm	86.0	89.7	72.2	99.1	91.4	90.0	56.1	83.0	84.7	93.8	83.0	75.2	84.2	77.5	62.2	49.9	78.1	78.0	52.1	24.3	34.4	57.1	74.7	0.04	
SSF	86.6	89.8	68.8	99.1	91.4	91.2	56.5	82.8	86.1	94.5	83.2	74.8	84.7	80.1	63.6	53.0	81.4	85.6	52.1	31.9	37.2	60.6	76.0	0.21	
Pfeif. Adapter	86.3	91.5	72.1	99.2	91.4	88.5	55.7	83.0	86.2	95.5	85.3	76.2	85.8	83.1	65.2	51.4	80.2	83.3	56.6	33.8	41.1	61.8	76.9	0.67	
Houl. Adapter	84.3	92.1	72.3	98	91.7	90.0	55.4	83.2	88.7	95.3	86.5	75.2	86.4	82.9	63.6	53.8	79.6	84.4	54.3	34.2	44.3	62.1	77.2	0.77	
AdaptFormer	85.8	91.8	70.5	99.2	91.8	89.4	56.7	83.2	86.8	95.0	86.5	76.3	86.2	82.9	64.1	52.8	80.0	84.7	53.0	33.0	41.4	61.5	76.9	0.46	
RepAdapter	86.0	92.5	69.1	99.1	90.9	90.9	55.4	82.9	86.9	95.3	86.0	75.4	85.9	82.5	63.5	51.4	80.2	85.4	52.1	35.7	41.7	61.6	76.8	0.53	
Convpass	85.0	92.1	72.0	99.3	91.3	90.8	55.9	83.5	87.7	95.8	85.9	75.9	86.3	82.3	65.2	53.8	78.1	86.5	55.3	38.6	45.1	63.1	77.6	0.49	
LoRA	85.7	92.6	69.8	99.1	90.5	88.5	55.5	82.6	87.5	94.9	85.9	75.7	86.0	82.9	63.9	51.8	79.9	86.6	47.2	33.4	42.5	61.0	76.5	0.55	
FacT_TT	85.8	91.8	71.5	99.3	91.1	90.8	55.9	83.4	87.7	94.9	85.0	75.6	85.8	83.0	64.0	49.0	79.3	85.8	53.1	32.8	43.7	61.3	76.8	0.13	
FacT_TK	86.2	92.5	71.8	99.1	90.1	91.2	56.5	83.4	85.8	95.5	86.0	75.7	85.8	82.7	65.1	51.5	78.9	86.7	53.1	27.8	40.8	60.8	76.6	0.23	
Relative Std Dev	0.81	1.13	1.78	0.34	0.54	1.82	1.24	0.54	1.20	0.59	1.95	0.83	0.94	2.67	1.50	3.22	1.37	4.11	4.46	11.02	9.30	2.70	1.09	-	

Zero-shot /Adaptation Oriented (3D Data)

ARENA

Few-Shot Efficient Fine-Tuning

Challenges of PEFT in low-shot regimes

With careful hyper-parameter tuning, all PEFT methods perform similar in average.

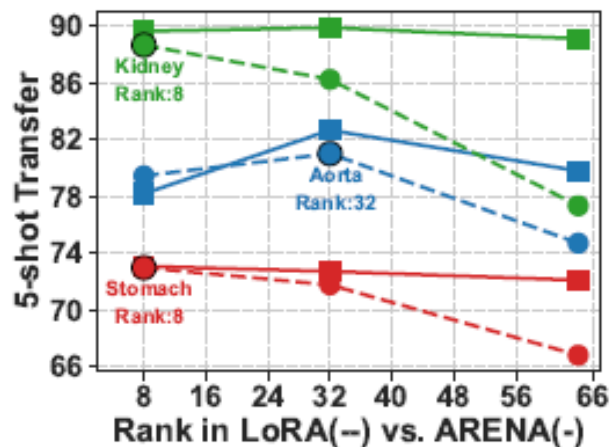
Method	Natural								Specialized						Structured										Overall Mean	Tunable Params
	CIFAR-100	Caltech101	DTD	Flowers102	Pets	SVHN	Sun397	Mean	Camelyon	EuroSAT	Resisc45	Retinopathy	Mean	Clevr-Count	Clevr-Dist	DMLab	KITTI-Dist	dSpr-Loc	dSpr-Ori	sNORB-Azim	sNORB-Elev	Mean				
Linear	78.1	86.6	65.7	98.9	89.3	41.5	53.2	72.5	83.1	90.0	74.9	74.6	80.6	37.5	35.1	36.5	64.6	16.2	29.4	17.3	23.7	32.5	61.9	0		
Full	62.4	89.9	61.9	97.4	85.8	88.9	36.8	76.7	81.6	88.1	81.6	73.6	81.2	56.2	60.9	48.2	77.9	68.5	46.6	31.0	28.3	52.2	70.0	85.8		
VPT-Shallow	80.2	88.7	67.9	99.1	89.6	77.0	54.2	79.4	81.8	90.3	77.2	74.4	80.9	42.2	52.4	38	66.5	52.4	43.1	15.2	23.2	41.6	67.3	0.07		
VPT-Deep	84.8	91.5	69.4	99.1	91.0	85.6	54.7	81.8	86.4	94.9	84.2	73.9	84.9	79.3	62.4	48.5	77.9	80.3	56.4	33.2	43.8	60.2	75.6	0.43		
BitFit	86.5	90.5	70.3	98.9	91.0	91.2	54.2	82.6	86.7	95.0	85.3	75.5	85.6	77.2	63.2	51.2	79.2	78.6	53.9	30.1	34.7	58.5	75.6	0.1		
DiffFit	86.3	90.2	71.2	99.2	91.7	91.2	56.1	83.2	85.8	94.1	80.9	75.2	84.0	80.1	63.4	50.9	81.0	77.8	52.8	30.7	35.5	59.0	75.4	0.14		
LayerNorm	86.0	89.7	72.2	99.1	91.4	90.0	56.1	83.0	84.7	93.8	83.0	75.2	84.2	77.5	62.2	49.9	78.1	78.0	52.1	24.3	34.4	57.1	74.7	0.04		
SSF	86.6	89.8	68.8	99.1	91.4	91.2	56.5	82.8	86.1	94.5	83.2	74.8	84.7	80.1	63.6	53.0	81.4	85.6	52.1	31.9	37.2	60.6	76.0	0.21		
Pfeif. Adapter	86.3	91.5	72.1	99.2	91.4	88.5	55.7	83.0	86.2	95.5	85.3	76.2	85.8	83.1	65.2	51.4	80.2	83.3	56.6	33.8	41.1	61.8	76.9	0.67		
Houl. Adapter	84.3	92.1	72.3	98	91.7	90.0	55.4	83.2	88.7	95.3	86.5	75.2	86.4	82.9	63.6	53.8	79.6	84.4	54.3	34.2	44.3	62.1	77.2	0.77		
AdaptFormer	85.8	91.8	70.5	99.2	91.8	89.4	56.7	83.2	86.8	95.0	86.5	76.3	86.2	82.9	64.1	52.8	80.0	84.7	53.0	33.0	41.4	61.5	76.9	0.46		
RepAdapter	86.0	92.5	69.1	99.1	90.9	90.9	55.4	82.9	86.9	95.3	86.0	75.4	85.9	82.5	63.5	51.4	80.2	85.4	52.1	35.7	41.7	61.6	76.8	0.53		
Convpass	85.0	92.1	72.0	99.3	91.3	90.8	55.9	83.5	87.7	95.8	85.9	75.9	86.3	82.3	65.2	53.8	78.1	86.5	55.3	38.6	45.1	63.1	77.6	0.49		
LoRA	85.7	92.6	69.8	99.1	90.5	88.5	55.5	82.6	87.5	94.9	85.9	75.7	86.0	82.9	63.9	51.8	79.9	86.6	47.2	33.4	42.5	61.0	76.5	0.55		
FacT_TT	85.8	91.8	71.5	99.3	91.1	90.8	55.9	83.4	87.7	94.9	85.0	75.6	85.8	83.0	64.0	49.0	79.3	85.8	53.1	32.8	43.7	61.3	76.8	0.13		
FacT_TK	86.2	92.5	71.8	99.1	90.1	91.2	56.2	83.4	85.8	95.5	86.0	75.7	85.8	82.7	65.1	51.5	78.9	86.7	53.1	27.8	40.8	60.8	76.6	0.23		
Relative Std Dev	0.81	1.13	1.78	0.34	0.54	1.82	1.24	0.54	1.20	0.59	1.95	0.83	0.94	2.67	1.50	3.22	1.37	4.11	4.46	11.02	9.30	2.70	1.09	-		

Zero-shot /Adaptation Oriented (3D Data)

ARENA

Few-Shot Efficient Fine-Tuning

Challenges of PEFT in low-shot regimes



(a) Robustness

The optimum LoRA rank varies per task.

$$W = W_0 + \Delta W = W_0 + BA$$

$$A \in \mathbb{R}^{r \times n}$$

$$B \in \mathbb{R}^{m \times r}$$

$$r \ll (m, n)$$

Zero-shot /Adaptation Oriented (3D Data)

ARENA

Few-Shot Efficient Fine-Tuning

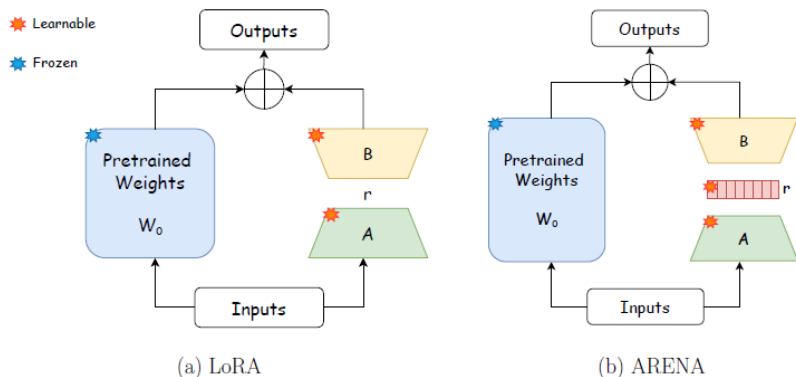
Adaptive Low-rank adaptation



$$W = W_0 + \Delta W = W_0 + B \text{Diag}(v) A$$

The number of non-zero elements of the vector of diagonal elements determine de rank of the decomposition

$$\|v\|_0$$



Zero-shot /Adaptation Oriented (3D Data)

ARENA

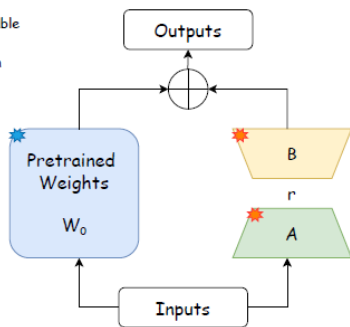
Few-Shot Efficient Fine-Tuning

Adaptive Low-rank adaptation

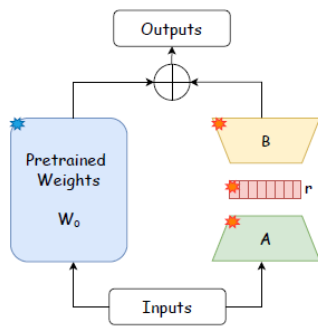


$$W = W_0 + \Delta W = W_0 + B \text{Diag}(v) A$$

★ Learnable
★ Frozen



(a) LoRA



(b) ARENA

The number of non-zero elements of the vector of diagonal elements determine the rank of the decomposition

$$\|v\|_0$$

$$\mathcal{L}(A, B, v) + \lambda \|v\|_1$$

ℓ_1 encourages vector sparsity

Loss function of the task

Zero-shot /Adaptation Oriented (3D Data)

ARENA

Few-Shot Efficient Fine-Tuning



Transferability to known tasks (domain shift)

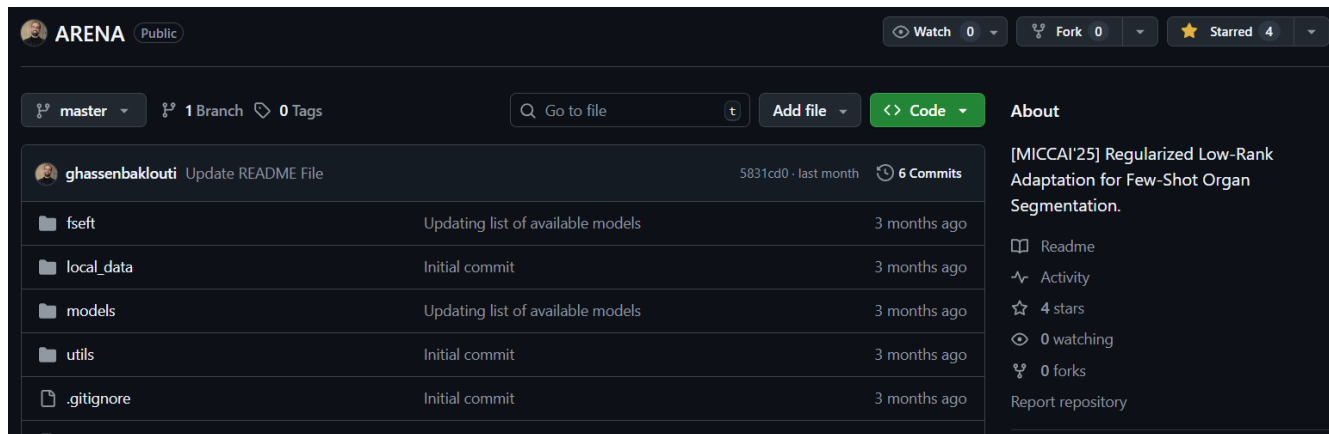
	Method	Spl	lKid	Gall	Eso	Liv	Pan	Sto	Duo	Aor	Avg.
10-shot	Linear probe	91.72	89.78	78.49	47.01	92.16	78.14	76.80	63.63	69.91	76.40
	BitFit [33]	90.85	87.68	75.92	47.92	91.85	79.83	66.35	64.10	77.98	75.83
	Affine-LN [1]	<u>92.20</u>	86.02	79.58	50.27	89.98	77.64	<u>69.15</u>	<u>67.64</u>	83.53	77.33
	FFT	<u>89.61</u>	84.79	76.07	56.82	90.89	74.87	<u>60.78</u>	71.29	91.81	<u>77.44</u>
	LoRA [15]	89.94	89.47	<u>80.65</u>	46.11	<u>92.94</u>	81.18	66.41	61.76	81.66	76.68
	ARENA (<i>Ours</i>)	92.28	<u>89.58</u>	84.49	<u>50.83</u>	93.01	<u>80.27</u>	68.35	62.95	82.46	78.25

Transferability to novel tasks (new organs)

	Method	MYO	LA	RA	LV	RV	Avg.
10-shot	Linear probe	<u>64.50</u>	63.47	66.86	69.12	62.60	65.31
	BitFit [33]	64.18	64.15	66.35	<u>69.79</u>	62.61	64.42
	Affine-LN [1]	64.39	63.62	67.95	69.93	63.66	65.91
	FFT	59.07	54.05	63.06	64.38	59.50	60.01
	LoRA [15]	60.31	<u>65.2</u>	<u>78.44</u>	64.05	<u>65.29</u>	<u>66.66</u>
	ARENA (<i>Ours</i>)	75.29	81.8	82.93	74.2	74.82	77.81

Adaptation code and model weights publicly available

<https://github.com/ghassenbaklouti/ARENA>



The screenshot shows the GitHub repository page for 'ARENA' by user 'ghassenbaklouti'. The repository is public and has 4 stars, 0 forks, and 0 watches. The main branch is 'master'. The repository contains a README file and several folders: 'fseft', 'local_data', 'models', 'utils', and '.gitignore'. The 'models' folder is highlighted as the latest update. The 'About' section on the right describes the repository as '[MICCAI'25] Regularized Low-Rank Adaptation for Few-Shot Organ Segmentation'.

File/Folder	Commit Message	Commit Date
ghassenbaklouti	Update README File	5831cd0 · last month
fseft	Updating list of available models	3 months ago
local_data	Initial commit	3 months ago
models	Updating list of available models	3 months ago
utils	Initial commit	3 months ago
.gitignore	Initial commit	3 months ago

About
[MICCAI'25] Regularized Low-Rank Adaptation for Few-Shot Organ Segmentation.
Readme
Activity
4 stars
0 watching
0 forks
Report repository

Zero-shot /Adaptation Oriented (3D Data)

Challenges and future

1. Model selection in low-shot regimes: we need to facilitate the adaptation/fine-tuning stage to practitioners.
2. How to know a priori if using black-box Adapters, or PEFT. Which PEFT method to use?
3. Improving PEFT for convolutional architectures, e.g., nnUnet/3DUnet.
4. Better benchmarks in supervised pre-training: Known vs. Novel setting.
5. More detailed comparisons between Supervised vs. SSL for few-shot transfer and domain generalization.

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